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ELECTRONIC MASTER MONITOR AND ADVISORY DISPLAY SYSTEM, OPERATIONAL FUNCTIONS REPORT

GENERAL ELECTRIC COMPANY AIRCRAFT EQUIPMENT DIVISION BINGHAMTON, NY 13902

OCTOBER 1980
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is being developed for use on U.S. Army helicopters to reduce crew workload by assuming responsibility for tasks associated with subsystem status monitoring. EMMADS will integrate all instrumentation normally dedicated to subsystem status monitoring (e.g. all pressures, temperatures, etc.) plus caution/warning/advisory indicators, into a computer controlled, solid state system. It will detect, analyze and provide emergency checklists for any faults that it is programmed to monitor for in these subsystems. This report represents a tieing together of Tasks I & II to provide a baseline for defining the requirements of the feasibility demonstration hardware. In Task I, helicopters representing all operational helicopter categories (cargo, utility, scout, and attack) were identified and a signal analysis was done on each. While the EMMADS functions described in this report are applicable to all helicopter categories studied under Tasks I & II, specific examples used herein are all related to the CH-47C helicopter, since this aircraft had been selected as the basis for the EMMADS feasibility model.

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GLOSSARY OF ABBREVIATIONS

AC - Alternating Current ACK - Acknowledge - Aft Vertical Thrust Bearing Aft Vert Thrust Brng AGB - Accessory Gear Box APU - Auxiliary Power Unit - auxiliary aux - boost bst °C - degrees Celsius - Condition lever Cond lever CRSE - cruise CTRL (or CTL) - Control - Direct Current DC ELEC - Electrical **EMMADS** - Electronic Master Monitor and Advisory Display System **ENG** - Engine - exhaust exh - external ext - forward fwd - generator gen - Health Indicator Test HIT hyd (or HYDR) - hydraulic lndg - landing - Miscellaneous MISC MLDS - Multilegend Display Switch - engine gas producer speed N_1 N_2 - engine power turbine speed

- normal

- Overspeed

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GLOSSARY OF ABBREVIATIONS (CONT)

pos - position
press (or prs) - pressure
proc - procedure

PTIT - Power Turbine Inlet Temperature (same as TGT)

qty - quantity
ref - reference
rel - release
rt - right

RTU - Remote Transmission Units
rpm - revolutions per minute

SAS (or Stab Aug) - Stability Augmentation System

STAT - Status sw - switch

TBD - To Be Determined
TBS - To Be Specified

temp - temperature

TGT - Turbine Gas Temperature (same as PTIT)

X-feed - cross feed
X-tie - cross tie
XMSN - transmission

1.0 SCOPE

This report describes the results of work done under Task I of contract No. DAAK 80-79-C-0270, to establish basic system operating requirements for an Electronic Master Monitor and Advisory Display System (EMMADS). This system is being developed for use on U.S. Army helicopters to reduce crew workload by assuming responsibility for tasks associated with subsystem status monitoring. EMMADS will integrate all instrumentation normally dedicated to subsystem status monitoring (e.g. all pressures, temperatures, etc.) plus caution/warning/advisory indicators, into a computer controlled, solid state system. It will detect, analyze and provide emergency checklists for any faults that it is programmed to monitor for in these subsystems.

While this report is being identified with Task I elements of the contract, it in fact also represents a tieing together of Tasks I & II to provide a baseline for defining the requirements of the feasibility demonstration hardware of Task IV. In Task I, helicopters representing all operational helicopter categories (cargo, utility, scout and attack) were identified and a signal analysis was done on each. The results of the analyses for these aircraft (CH-47C, UH-60A, OH-58C and YAH-64 respectively) are in the form of Subsystem Parameter Data Lists, shown in Appendix 1. Under Task II, surveys of pilots were made to determine when and how information should be displayed (see EMMADS Human Engineering Summary Report). Coupling all of the above information together with a thorough understanding of flight operations, the Systems Engineering task of developing and implementing a coherent EMMADS operating philosophy was accomplished. This resulted in a system design based on the following underlying principles:

a) The aircrew should be managers of the aircraft and as such must have information required for operation of the aircraft in minimum time and in the simplest possible form.

- b) The pilot in any flight situation must be able to fly the aircraft, i.e., he must retain or regain control of the aircraft. Any system that relates to this function (such as EMMADS) must enhance this capability and absolutely cannot interfere with it.
- c) During fault display operations, interactive manual inputs to EMMADS by the aircrew should be kept to a minimum.

These principles then form the core of the EMMADS operating philosophy. In this report, each element of the system's operation is presented and justified in terms of this philosophy.

While the EMMADS functions described in this report are applicable to all helicopter categories studied under Tasks I & II, specific examples used herein are all related to the CH-47C helicopter, since this aircraft had been selected as the basis for the EMMADS feasibility model.

2.0 APPLICABLE DOCUMENTS

Electronic Master Monitor and Advisory Display System: Human Factors Engineering Summary Report (ACS 12,385), R. McLane, Reliability and Human Factors Engineering, GE, Pittsfield, MA, Aug. 1980.

Subsystem Parameter Data Lists for CH-47C, UH-60A, OH-58C & YAH-64 (ACS 11,995) Appendix 1, General Electric Co., Binghamton, NY.

Technical Proposal for the Electronic Master Monitor and Advisory Display System - Part 1 (ACS 11,773-1), February 1979, General Electric Aircraft Equipment Division, Binghamton, NY.

TM 55-1520-227-10-2, Operator's Manual, Army Model CH-47C Helicopter, 23 August 1978.

Advanced Subsystem Status Monitor, Final Report, Contract DAAK51-78-C-0023, Sikorsky Aircraft, Div. of United Technologies Corp.

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3.0 EMMADS CHARACTERISTICS

3.1 System Overview

The block diagram shown in Figure 1 illustrates the basic EMMADS architecture as installed on an aircraft. The system utilizes a dual 1553B digital bus for data transmission. RTU's provide the interface required to digitally encode and place on the bus the aircraft sensor signals described in Appendix 1. Two digital display processors perform the monitoring and fault detection functions described in this report. They also determine the current formats to be displayed on the electrolumines rent flat panels. Note that a separate processor is to be made usable at each crew station. A set of multilegend display switches (MLDS) associated with each display unit, provide the pilot with display control during all system operations. A keyboard is provided for data inputs to the system also. Provision for expanding system capabilities to include audio warning is also shown.

3.2 System Functions

The EMMADS operational functions requirements are described in this report according to the system's primary and secondary functions.

The primary functions of an EMMADS are:

- a) Provide a continuous display of Rotor RPM, Torque, Flight Time Remaining (based on continuously monitored fuel consumption) and, when applicable, a countdown of remaining allowable time for operation of parameters within time limited ranges. It shall also display non-flight parameters to aircrew members upon request.
- b) Monitor aircraft subsystem parameters for possible

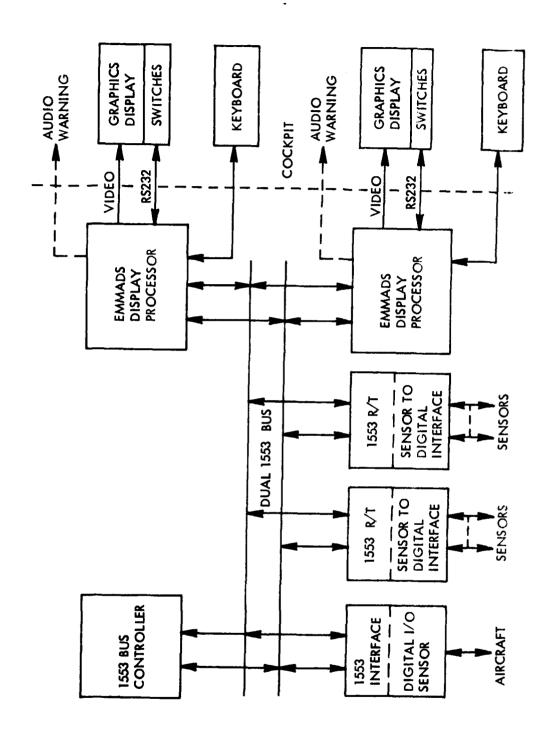


Figure 1. EMMADS Block Diagram

faults. This monitoring activity includes:

- 1) Correlation of current parameter status (value) with a particular limit or set of limits, the values of which may be functionally dependent on other parameter values. A parameter value that approaches, meets or exceeds an associated limit requires that the aircrew be notified.
- 2) Correlation of the time rate of change of a parameter value with a maximum allowable rate of change based on manufacturer/procurement spraifications or some experimentally established based line. A rate of change that exceeds this max mum value requires notification of the air rew.
- c) Detect composite faults resulting from multiple parameter excursions. Provide an unambiguous notification of the fault nature to the aircrew.
- d) Display aults to the crew utilizing a flexible prioritization system and provide a means of rapidly communicating to EMMADS the pilot's observation of each fault.
- e) Display recommended fault correction actions (emergency checklists) in response to aircrew requests.

The secondary functions of EMMADS include:

a) The ability to display routine, interactive type checklists such as the Before Starting Engines, Starting Engines, Engine Ground Operation, Before Taxi, Taxiing Check, Before Takeoff, Cruise Check, Before Landing, After Landing and Engine Shutdown Checklists.

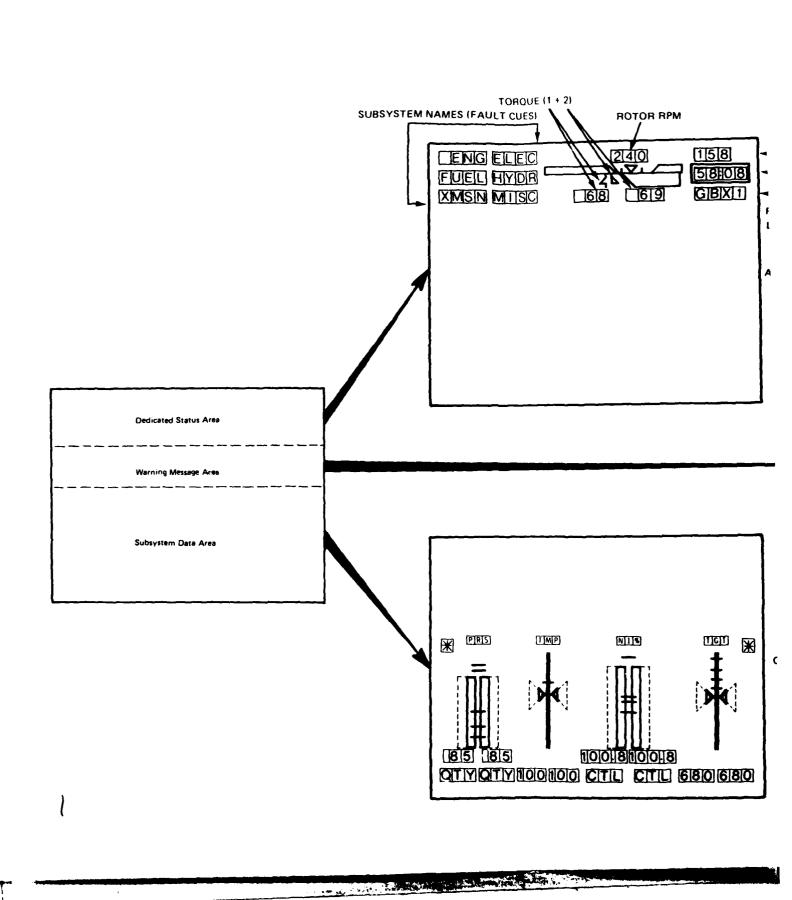
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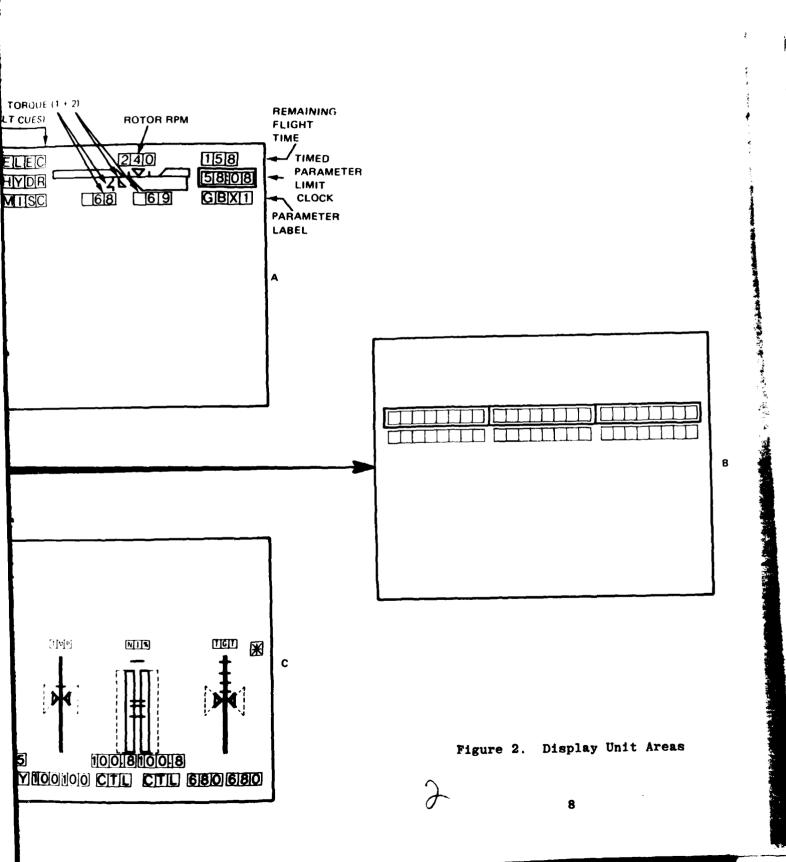
- b) Calculations to predict aircraft performance characteristics.
- c) Recording the occurrence of any faults, as required for post-flight maintenance analysis.

3.2.1 Primary Functions

3.2.1.1 Display Areas

The EMMADS display is broken into three areas to facilitate efficient information transfer to the pilot. These are shown in Figure 2. (Note: In this and all other figures showing display formats, boxes are drawn around alphanumeric characters and may also be shown, empty, in other areas of the display. not part of the format, but are used to indicate the amount of space reserved for these characters.) The Dedicated Status Area is utilized for information requiring continuous display. This includes rotor rpm, torque and remaining flight time (in minutes). Other items shown in this area are connected with fault detection aspects of EMMADS. Once activated, they remain in this area, continuous displayed, until deactivated by other fault logic. Their operation is further described in Section 3.2.1.3. The Warning Message Area is reserved for displaying up to six messages of eight characters each, under conditions described in 3.2.1.3. The Subsystem Data Area is utilized for displaying parameters in the engine, fuel, transmission, electrical, hydraulic and miscellaneous subsystems, as well as emergency action checklists. (The engine subsystem is shown as an example in Figure 2.) The dotted lines shown with the bar (thermometer type) scales and pointer scales indicate these symbols can oversize to indicate a fault with that parameter. Oversized, hollow indicators are used to depict rate (trend) type faults, while oversized, filled-in symbols indicate a limit type fault. Special symbols for chips (*) and other discrete type





faults are also used (e.g. QTY indicates low engine oil quantity and CTL indicates that an N_1 control loop is energized). These and other faults are described in Sections 3.2.1.2 and 3.2.1.3.

3.2.1.2 Fault Detection

The primary functions of fault detection and fault/ parameter display are to be performed on a continuous basis, i.e. they are accomplished independent of flight phase. The primary functions must be considered as preemptive of any secondary function. Sufficient time must be allocated to sample all parameters, update those currently being displayed, compute rates of change and compare these and current values to maximum rates of change or value limits, respectively, determine what faults exist, if any, and display them according to their priority. Adequate additional time per cycle should be available for secondary functions.

The test for fault conditions may be linked to flight phase. For example, in order to distinguish between an engine low side beep trim failure and a pilot commanded reduction to ground idle power, the EMMADS must be able to sense the position of the engine condition lever. While a commanded power reduction is normally a no-fault condition, during airborne operations the placement of an engine condition lever in a ground or idle position should be indicated to the pilot. It could be considered as a fault or as an advisory, but, in any event, it is a condition which warrants an information display to the pilot and constitutes a link with flight phase. The flight phase is useful in determining the operating mode for the measurement of parameter conditions, as part of the EMMADS primary function. Under various operating modes, parameter values (conditions) may or may not be abnormal, as shown in Appendix 1, Subsystem Parameter Data Lists.

There are two fault types which are handled by the EMMADS; single parameter faults and multiple parameter faults. A single parameter fault is detected by examining the characteristics of an individual parameter (signal) for:

- a. An out of tolerance value, or
- b. An out of tolerance rate of change (unfavorable trend).

A multiple parameter fault is one inferred by correlating the values of various related parameters. For example, to properly identify an engine failure, gas producer speed, turbine gas temperature, torque and engine oil pressure need to be compared. Parameter attributes, (values or rates of change) used by EMMADS as standards of comparison to detect either of these fault types, are set by the operating mode mentioned previously. The operating mode may be determined by some unrelated parameter or parameter group (e.g. when gross weight sets the normal rotor rpm limits).

Due to the large variations in the size and configuration of helicopters studied, the classification of faults and the related operating modes is aircraft specific. An example of a fault set, the Fault/Parameter Matrix for the CH-47C, is shown in Appendix 2. This matrix relates each fault to a set of parameters which either belong to a specific aircraft subsystem or are used to relate to a particular operating mode. For single parameter faults in this case, the Subsystem Parameter Data List, CH-47C, Appendix 1 illustrates the relationship between operating modes and various parameter conditions. The conditions on that list not classified as "normal" constitute fault conditions. For multiple parameter faults the operating modes and conditions are obtained from Chapter 9 of the Aircraft Operator's Manual.

3.2.1.3 <u>Fault/Parameter Display</u>

When a fault is detected, the pilot must be made aware of it. The system must allow the pilot to control what is on the display. At the same time he must be given information about new faults as they occur. A priority system must be established to allow the EMMADS to differentiate between faults of higher and lower relative importance.

In establishing such a fault priority structure, it is important to understand the information requirements when a fault occurs during a specific flight situation. The first task of the pilot when a fault occurs is to regain/maintain aircraft control. The second task is to take whatever action is necessary/possible to correct the condition. In no case should the accomplishment of the second task interfere with the first task. These fundamental considerations dictate that faults be divided into three major categories:

- a) Warnings those faults which, if not immediately acted upon by the crew, will most likely seriously compromise the pilot's ability to control the aircraft and therefore could result in personal injury or loss of life.
- b) Cautions/Precautions those faults which do not immediately jeopardize the safety of the crew or the ability to control the aircraft but which may result in equipment damage if not attended to. In addition, such faults, if allowed to continue without corrective action being taken, may precipitate one or more Warnings.
- c) Advisories these are conditions (actually parameter states) the pilot should be made aware of. The

determination of whether or not these states are faults is left to the pilot, since the determination of the normal conditions depends on pilot judgement (e.g. Cargo Hook Open, Parking Brake ON, etc.)

Given the faults to be detected (such as those shown in the Fault/Parameter Matrix of Appendix 2) the first step in prioritization is simply to designate which faults fall into the Warning category. Then, by designating the conditions which are Advisories, the remaining fault conditions fall automatically into the Caution/Precaution category.

Such a fault partitioning scheme as applied to the CH-47C is shown in Table 1. Placing faults into the Warning category was based on the following considerations:

- a) A total loss of hydraulic pressure in the flight control systems makes it impossible to move the flight controls.
- b) Rotor rpm is directly related to aircraft lift, so loss of rotor rpm requires rapid pilot response.
- c) In a dual engine aircraft, given a choice of responding to a loss of engine speed control versus an engine failure, the pilot should first attend to the engine that is still operating.
- d) Faults in any subsystem which can rapidly precipitate loss of flight controls, loss of lift or loss of engine power are candidates for inclusion in the Warnings category. Each must be considered on an individual basis.

In assigning the specific <u>numeric</u> priorities contained in Table 1, the following additional considerations were taken into account:

TABLE 1. FAULT PRIORITIZATION FOR THE CH-47C HELICOPTER

<u>Fault</u>	Subsystem Displayed	Priority
WARNINGS		
Quill Shaft Failure	Hydraulic	1
Rotor RPM Limit (continuous display)	Engine	2
No. 1 Engine Beep Trim High Side Failure	Engine	3
No 2. Engine Beep Trim High Side Failure	Engine	3
No. 1 Engine N ₂ Sensing Failure	Engine	3 3
No. 2 Engine N2 Sensing Failure No. 1 Engine Beep Trim	Engine Engine	3 4
Low Side Failure	Diigriic	*
No. 2 Engine Beep Trim	Engine	4
Low Side Failure No. 1 & 2 Engines Failed	Engine	4
No. 1 Engine Failed	Engine	5
No. 2 Engine Failed	Engine	5
No. 1 Flight Control Hydraulic Press Low/Rate	Hydraulic	6
No. 2 Flight Control Hydraulic Press Low/Rate	Hydraulic	6
Eng. 1 & 2 Fuel Boost Press Limit (PA >6000')	Fuel	7
Eng. 1 Fuel Boost Press Limit (PA >6000')	Fuel	8
Eng. 2 Fuel Boost Press Limit (PA >6000')	Fuel	8
No. 1 and 2 SAS OFF	Miscellaneous	s 9
CAUTIONS/PRECAUTIONS		
<pre>Eng. 1 PTIT Limit/Rate (starting only)</pre>	Engine	10
Eng. 2 PTIT Limit/Rate (starting only)	Engine	10
Eng. 1 Torque Limit (continuous display)	Engine	10
Eng. 2 Torque Limit (continuous display)	Engine	10
Eng. 1 N _{1 Limit} Eng. 2 N ₁ Limit	Engine Engine	10 10
Eng. 2 N1 Limit Eng. 1 Oil Press Limit/Rate	Engine	10
Eng. 2 Oil Press Limit/Rate	Engine	10
Eng. 1 Oil Temp Limit/Rate	Engine	10
Eng. 2 Oil Temp Limit/Rate	Engine	10
Eng. 1 Chip Detected	Engine	10
Eng. 2 Chip Detected	Engine	10

TABLE 1. FLIGHT PRIORITIZATION FOR THE CH-47C HELICOPTER (cont'd)

Fault	Subsystem Displayed	Priority
CAUTIONS/PRECAUTION (cont'd)		
Eng. 1 Oil Level Limit Eng. 2 Oil Level Limit	Engine Engine	10 10
Eng. 1 N ₁ Control Loop Energized Eng. 2 N ₁ Control Loop Energized	Engine Engine	10 10
Fuel Qty-Left, Fwd Limit/Rate Fuel Qty-Left, Main Limit/Rate	Fuel Fuel	11 11
Fuel Qty-Left, Aft Limit/Rate Fuel Qty-Right, Fwd Limit/Rate	Fuel Fuel	11 11
Fuel Qty-Right, Main Limit/Rate Fuel Qty-Right, Aft Limit/Rate	Fuel Fuel	11 11
Eng. 1 Fuel Boost Press Limit (PA <6000')	Fuel	11
Eng. 2 Fuel Boost Press Limit (PA <6000')	Fuel	11
Fuel Boost Press, Left, Fwd Limit	Fuel	11
Fuel Boost Press, Left, Aft Limit	Fuel	11 11
Fuel Boost Press, Right, Fwd Limit Fuel Boost Press, Right, Aft Limit	Fuel Fuel	11
Eng. 1 Fuel Flow High	Fuel	11
Eng. 2 Fuel Flow High	Fuel	11
bing, 2 ruel rrow high	ruei	1.1
Eng. 1 Xmsn Oil Press Limit/Rate	Powertrain	12
Eng. 2 Xmsn Oil Press Limit/Rate	Powertrain	
Combining Xmsn Oil Press Limit/Rate	Powertrain	12
Fwd Xmsn Oil Press Limit/Rate	Powertrain	12
Aft Xmsn Oil Press Limit/Rate	Powertrain	12
Eng. 1 Xmsn Oil Temp Limit/Rate	Powertrain	12
Eng. 2 Xmsn Oil Temp Limit/Rate	Powertrain	
Combining Xmsn Oil Temp Limit/Rate	Powertrain	12
Fwd Xmsn Oil Temp Limit/Rate	Powertrain	12
Aft Xmsn Oil Temp Limit/Rate	Powertrain	12
Combining Xmsn Chip Detected	Powertrain	12
Fwd Xmsn Chip Detected	Powertrain	12
Aft Xmsn Chip Detected	Powertrain	12
Aft Thrust Bearing Chip Detected	Powertrain	12
No. 1 Generator Load Limit	Electrical	13
No. 2 Generator Load Limit	Electrical	13
No. 1 & 2 Generators Failed	Electrical	13
No. 1 Rectifier Load Limit	Electrical	13
No. 2 Rectifier Load Limit	Electrical	13
No. 1 & 2 Rectifiers Failed	Electrical	13
AC Bus X-Tie Failure	Electrical	13
DC Bus X-Tie Failure	Electrical	13

TABLE 1
FAULT PRIORITIZATION FOR THE CH-47C HELICOPTER (Cont'd)

Fault	Subsystem Displayed	Priority
CAUTIONS/PRECAUTIONS (Cont'd)		
No. 1 Flight Control Hydraulic Press High	Hydraulic	14
No. 2 Flight Control Hydraulic Press High	Hydraulic	14
Utility Hydraulic Press Limit/Rate	Hydraulic	14
Utility Hydraulic Temp Limit	Hydraulic	14
APU Accumulator Press Limit	Hydraulic	14
No. 1 SAS OFF	Miscellaneou	s 15
No. 2 SAS OFF	Miscellaneou	s 15
Fwd Cyclic Trim Actuator Position Limit	Miscellaneou	s 15
Aft Cyclic Trim Actuator Position Limit	Miscellaneou	s 15
Right Aft Landing Gear Phase Limit	Miscellaneou	s 15
Heater Output Temperature Limit	Miscellaneou	s 15
ADVISORIES		
AC External Power Connected	Electrical	16
DC External Power Connected	Electrical	16
Parking Brake On/Off	Miscellaneou	s 16
Cargo Hook Open/Closed	Miscellaneou	s 16
APU On/Off	Miscellaneou	s 16

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- a) If similar faults can occur in more than one area of the same subsystem, then there is no difference in their priority unless all such faults occur in combination (e.g., a flameout in one engine is just as serious as a flameout in the other engine, but a flameout in both engines is more serious).
- b) Faults that are mutually exclusive can be assigned the same level of priority. For example, a given engine cannot simultaneously experience a beep trim high side and low side failure.
- c) In assigning general priorities within the Caution/
 Precaution category, it is more reasonable to assign
 priorities based on the subsystems wherein the faults
 reside, as opposed to assigning priorities on an individual basis (except in the case of those faults in the
 "Miscellaneous" subsystem).

This last point may not seem realistic until one one realizes that all of the immediate action (Warning category) faults are removed first and the remaining faults (Not Advisories) all require a pilot reaction of about the same level of urgency. Given that the pilot is going to acknowledge all faults in a reasonably short time and that he will be alerted when any fault occurs, the prioritization according to subsystem importance is the simplest and most logical procedure to follow.

Highest on the list of Cautions/Precautions should be the Engine subsystem since the engines provide the power to stay aloft. This is followed by the Fuel subsystem because it directly affects the ability of the engines to continue operating. Next comes the Powertrain subsystem (minus the continuously displayed rotor rpm) since it is probable that there will be a larger time span within which to react to a fault in this subsystem as opposed to faults

in the two subsystems just listed. (For example, transmissions have been designed to run as long as 30 minutes with no oil in the sump.) Following this would be the Electrical and Hydraulic subsystems, respectively. (Keep in mind that major flight control hydraulic faults are already included in the Warning category.) Finally, all remaining faults are prioritized according to estimated relative urgency in the Miscellaneous subsystem. At this time, no further prioritization has been deemed necessary. It is possible that future considerations may indicate that some faults in one subsystem should really have the same priority as faults in another subsystem, insofar as the urgency of the desired crew reaction is concerned. Determinations of this type can be made only after a prototype system has been used to gather specific aircrew recommendations under suitable test conditions.

The final subcategory, which has not yet been addressed, is that of Advisories. When an advisory level condition occurs, it is generally a state change of a discrete sensor. It has the lowest display priority. Hence advisory state changes will be displayed only if no faults take display priority. In the case of the CH-47C used as an example in Table 1, there are five advisory conditions currently identified: AC External Power, DC External Power, Parking Brake Status, Cargo Hook Status and APU On/Off Status.

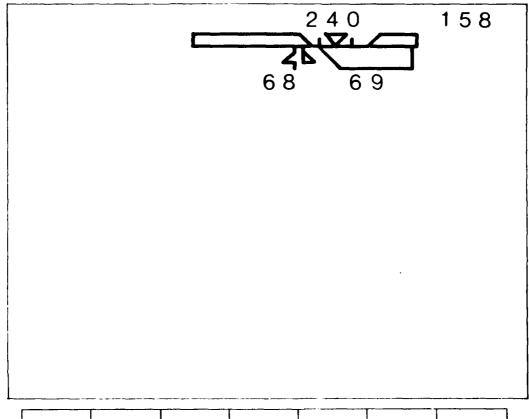
Given the preceeding discussion as background, the system operation with regards to fault detection and display may now be discussed. As previously described, with no faults active, the display is clear except for Rotor rpm, Torque and Remaining

Flight Time, as shown in Figure 3. If a fault is detected, the following events take place:

- a) The aircraft Master Caution light is illuminated by the EMMADS computer.
- EMMADS determines the highest priority fault using the b) priority structure of Table 1 and displays the raw data of the subsystem related to that fault in the Subsystem Data Area. Figure 4 shows an example of this for the case of a failure of the number 2 engine. Note that the out of tolerance parameters are indicated by the use of oversized symbology. The fact that the symbols are filled in indicates that an operational limit has been exceeded. Note also that if other faults existed in the same subsystem, they would likewise appear even though they might be of lower priority than the fault which brought about the display of that subsystem. The symbols are flashing because they are part of a fault which is not yet acknowledged. Also, the subsystem name "ENG" in the upper left of the Dedicated Status Area is flashing because there is an unacknowledged fault in that subsystem. Note that the MLDS previously labeled "ENG DATA" now reads "ENG ACK" and the right most switch now reads "WARN ACK".

When a Warning is detected, an appropriate message is displayed in the Warning Message Area. (In the case of the example in Figure 4, the engine failure results in the message ENG 2 OUT being displayed.) A box around the message(s) indicates the highest priority warning(s) displayed. These highest priority warning messages are located in the top row of the Warning Message Area. The messages have positional significance: left and right of center if they pertain to engine or system numbers 1 & 2 respectively or centered when no such symmetry considerations exist (e.g., rotor rpm).

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ENG FUEL XMSN ELEC HYDR MISC CHCK DATA DATA DATA DATA LSTS

Figure 3. Sample Display Format - No Faults

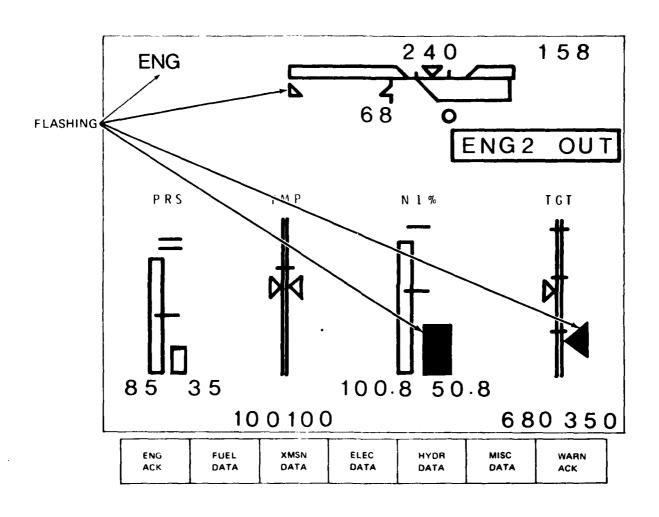


Figure 4. Sample Display Format - Fault Detected

- c) The pilot must manually acknowledge that he has reviewed the faults in the displayed subsystem, using a cyclic mounted acknowledge switch or the MLDS labeled "ENG ACK" or "WARN ACK" as described in Section 3.2.1.4. Actuation of either of these switches acknowledges the highest priority Warning and results in the appropriate emergency procedures checklist being placed on the display together with or instead of the subsystem data. Figure 5 illustrates this transition for the example started in Figures 2 and 3. This first actuation of the acknowledge switch also extinguishes the Master Caution Light.
- d) The pilot notifies EMMADS of checklist completion using the acknowledge function. In the example used in Figure 5, no other faults existed and the failed engine checklist has been acknowledged so the display format would change to that shown in Figure 6. Note that the word ENG is now steadily illuminated in the upper left hand corner, indicating that the engine fault, although acknowledged, still exists.

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An important distinction should be made regarding acknowledgement of Warnings versus other faults. The acknowledge (ACK) switch on the flight control will acknowledge Warnings separately. Once all Warnings are acknowledged, all remaining faults are acknowledged by subsystem. Thus, an engine display with two or more "non-Warning" type faults will be cleared by actuating the ACK switch once. This allows the pilot to rapidly review all faults while keeping his hands on the flight controls.

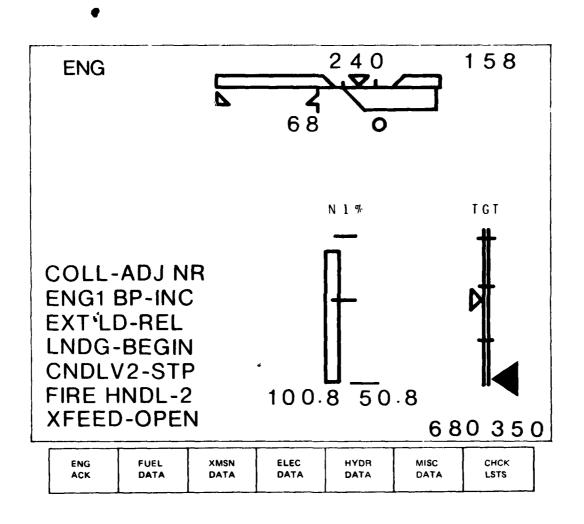
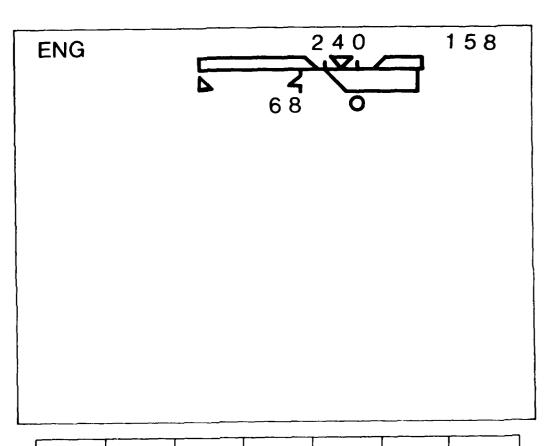


Figure 5. Sample Display Format - Warning Acknowledged, Checklist Displayed



ENG FUEL XMSN ELEC HYDR MISC CHCK
DATA DATA DATA DATA DATA LSTS

Figure 6. Sample Display Format - Fault Acknowledged, Checklist Completed

The previous example did not address the question of what happens when a fault of lower priority is displaced by a high priority fault. This can occur in two ways: the lower priority fault occurs first and then the high priority fault masks it or the low priority fault occurs while the pilot is still dealing with the high priority fault. In either case, the name of the subsystem in which the low priority fault resides will appear, flashing, in the top left of the Dedicated Status Area, to indicate that an active fault(s), not yet acknowledged, exists in that subsystem.

Another element of the fault display not yet discussed has to do with the amount of time remaining when a parameter is operating in a time limited range. This information also appears in the Dedicated Status Area, as a Timed Parameter Limit Clock located under the Remaining Flight Time indicator. The logic governing the use of this Timed Parameter Limit Clock dictates that it's display requires a priority system different from that employed for fault display. From both an operational and a human factors standpoint, the major considerations in establishing such a priority system are:

- a) The pilot is capable of taking action on only one countdown at a time, and
- b) The pilot will concentrate on the countdown with the least time to go.

Based on this, it is logical to display only one countdown at a time; the one with the least time remaining. However, there may be some parameters with timed operating ranges the pilot can control directly and others he cannot. In this case, the display priority for remaining time is in two major divisions, with actively controlled parameters having priority over those that are not. Within each of these two categories, the least time remaining criteria applies for display priority.

As an example of the total amount of information which must be processed for this mode the parameters on the CH-47C that have timed operating limits include Rotor RPM, Torque, PTIT and Engine Gearbox Oil Temperature. (See Subsystem Parameter Data List, CH-4C, Appendix 1.) Thus, the first three are placed in the higher (actively controlled) display category, and their countdowns have priority over that of the Engine Gearbox Oil Temperature.

3.2.1.4 Multilegend Display Switch (MLDS) Operation

The aircrew has the capability of selecting raw data for display, by subsystem, using a series of MLDS's located adjacent to the display panel. Several factors governing their operation should be noted:

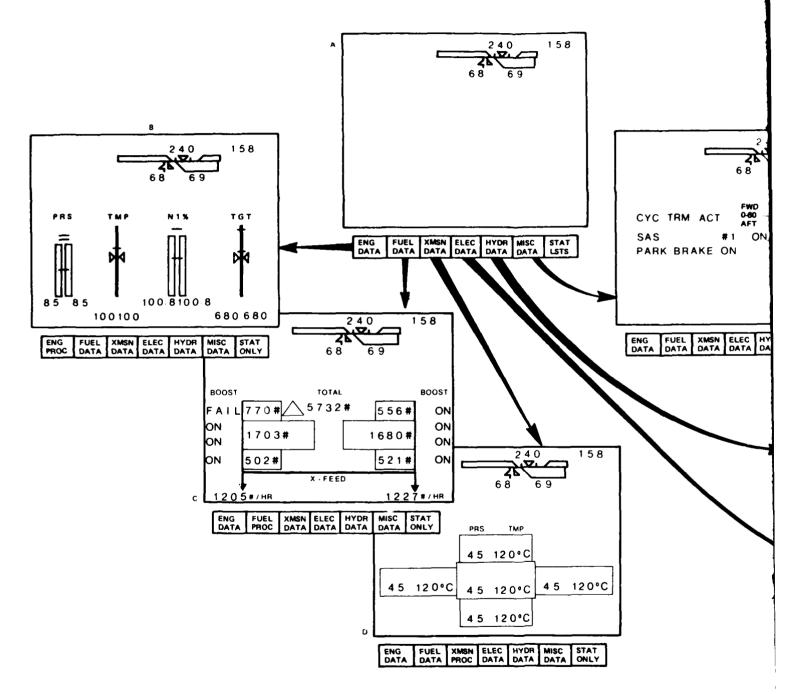
- a) Whenever the format on the EMMADS display is not one seen under "normal" operating conditions (i.e., only the Dedicated Status Area appears) the right most switch marked "STAT ONLY" is available to allow the pilot to return the display back to the Dedicated Status Area only.
- b) This same switch is used to modify the operating mode of all the other switches, by changing their legends simultaneously. This results in three major levels of switch operation: Data/Emergency Procedures, Routine Checklists and Performance Calculations.
- c) Switch actuation will change the display only if there is no conflict with the fault detection and display algorithms, which have priority.

There are two modes of operation possible for the MLDS's Manual Display Command operations and Fault Related Operations.

3.2.1.4.1 MLDS Operations - Manual Display Command

Under normal conditions, with no faults displayed, the seven MLDS's immediately below the display bear the legends shown in of Figure 7a. Actuation of any one of the first six switches places the data for the selected subsystem on the EMMADS display and changes the legend of the depressed switch and the right-most switch as shown in the figure. The set of MLDS legends in Figure 7a then represents the system being in the Subsystem Information Level. The result of depressing a switch with a "PROC" label is that the subsystem data is replaced by the first page of the highest priority emergency procedures checklist applicable to that subsystem. Successive actuations of that switch will result in the sequential display of all such checklists remaining. Depressing the "PROC" switch one more time when the last checklist is on the screen clears the display except for the Dedicated Status Area and returns all switch legends to the original set shown in Figure 7a. For Figures 7b-7g, depressing any switch other than the one with the "PROC" or the "STAT ONLY" legends will have no effect.

The legends may be changed simultaneously to the Routine Checklist Level by depressing the "CHCK LSTS" switch, as shown in Figure 8. This also clears the display except for the Dedicated Status Area. The six left-most switches now provide for selection of various routine checklists, to be displayed in the combined Warning Message and Subsystem Data Areas. As shown in Figure 9, depressing any of the first six switches changes the legend of that switch and the right-most switch, as well as presenting the first page of that checklist on the display. For example, in Figure 9c, the Normal Starting Engines checklist is selected ("NORM STRT" depressed). Depressing that same switch again (now labeled "MTF STRT" in the example shown) calls up a different checklist for display and would change that switch legend back to the previous one ("NORM STRT"). All of the first six switches



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Figure 7

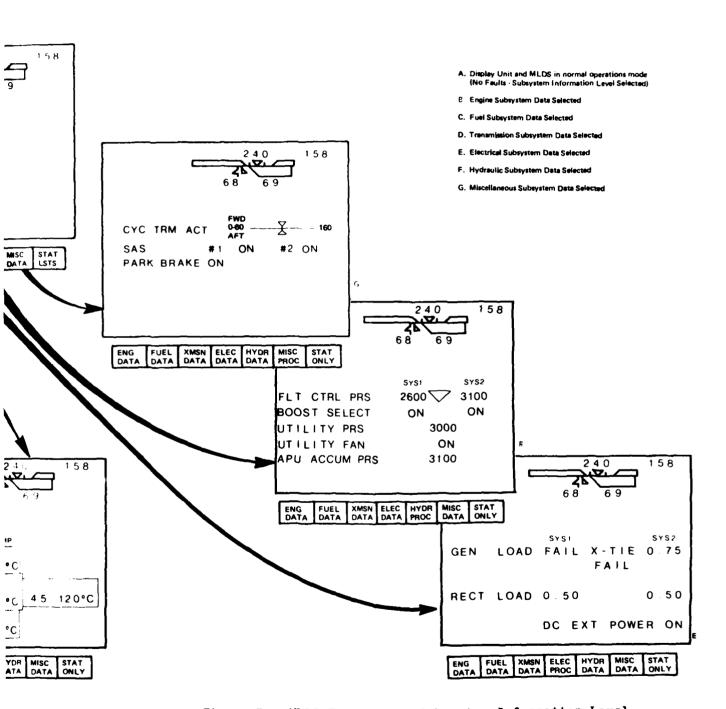
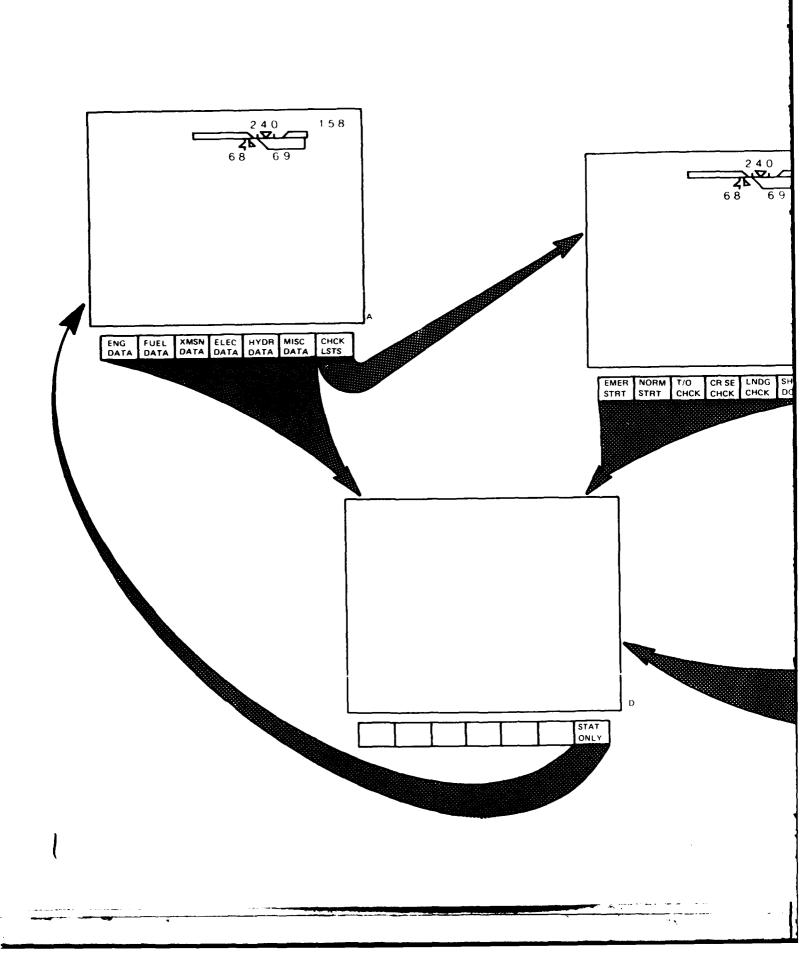
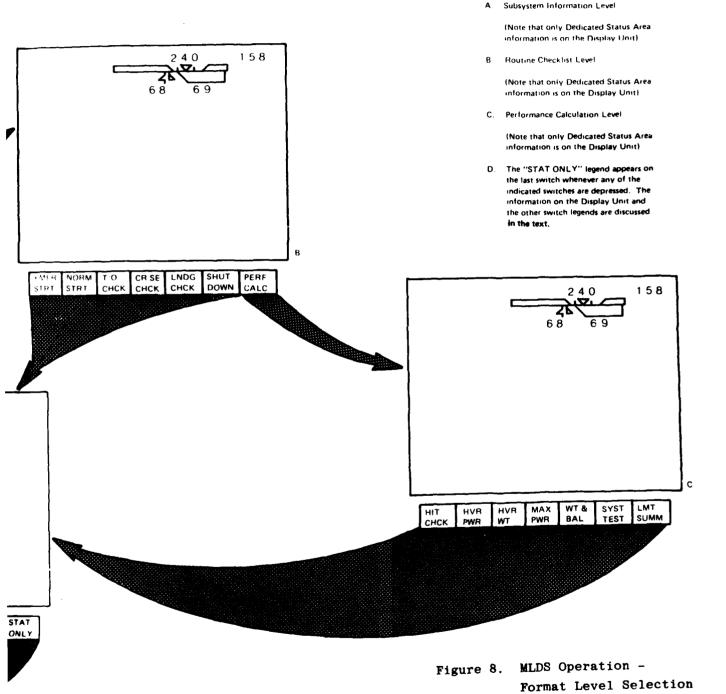
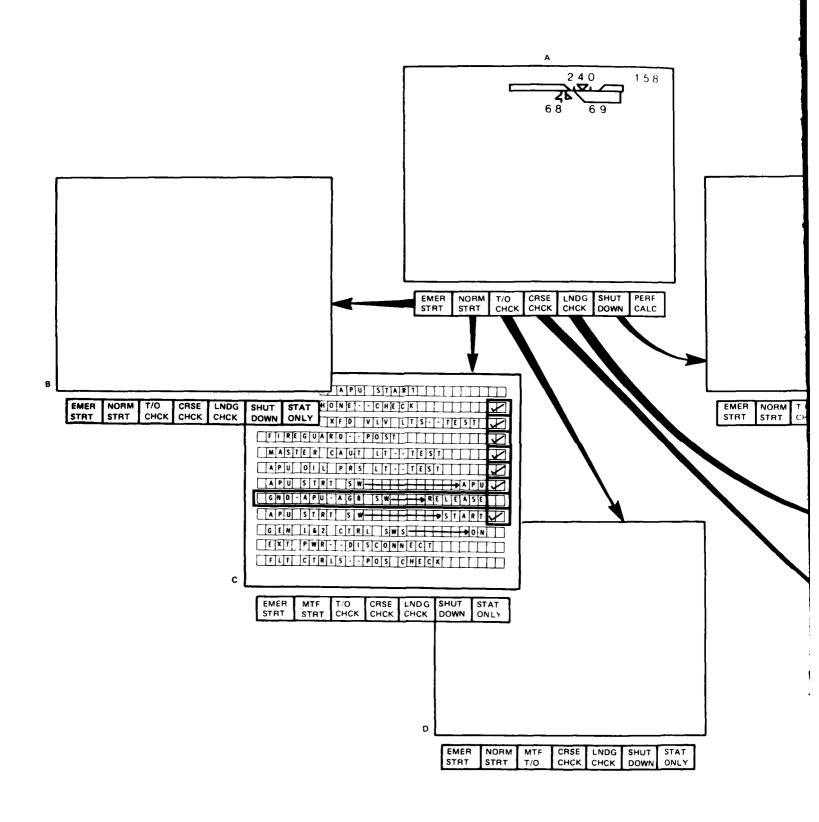
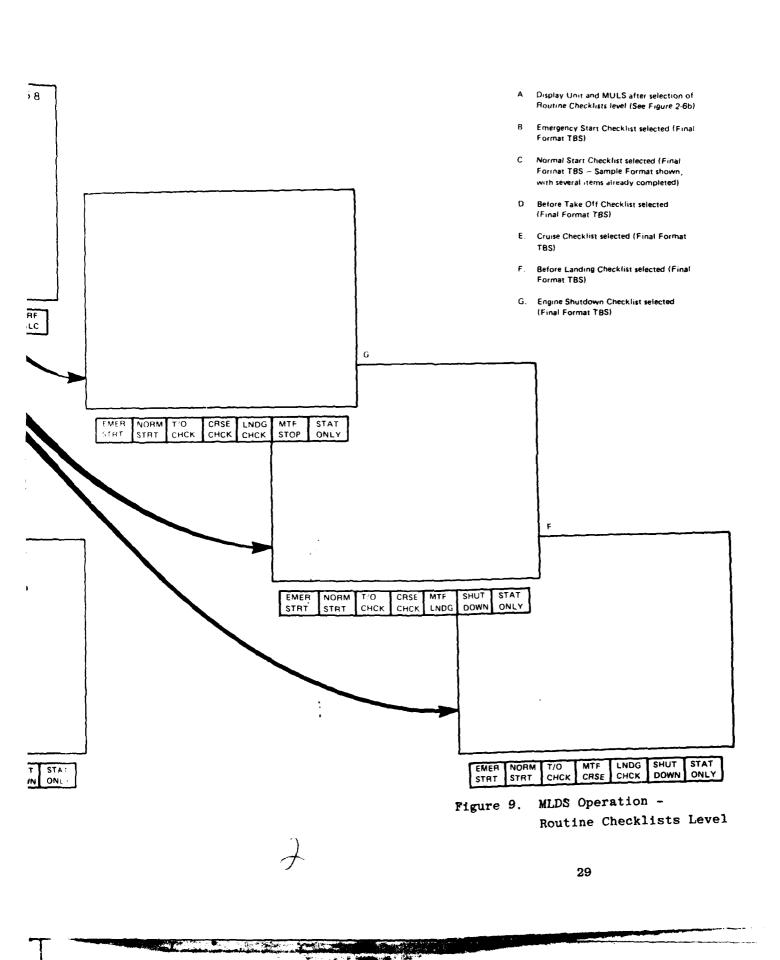


Figure 7. MLDS Functions - Subsystem Information Level









(except "EMER STRT") operate in a similar manner, as shown.

Depressing the switch labeled "PERF CALC" changes the switch legends as shown in Figure 8c while simultaneously clearing the display, except for the Dedicated Status Area. This figure shows that depressing the 7 "LMTS SUMM" switch changes the legend of that switch only. This is true of all the other switches as well, with no change in the legends of the first six switches. The "LMTS SUMM" switch displays the Limits Summary data which is used for post-flight maintenance playback of faults. Other switches select various performance calculations for display (see Section 3.2.2.2)

The only function not yet described is that of the "STAT ONLY" switch. Figure 8d shows that no matter what legends appear on the first six switches, depressing the "STAT ONLY" switch always returns the switch legends to those of the Subsystem Information Level and clears the display except for the Dedicated Status Area.

3.2.1.4.2 MLDS Operations - Fault Related

In the case where a fault is being displayed, the switch normally associated with the displayed subsystem has it's legend changed to "XXXX ACK", where "XXXX" represents the subsystem name. This switch function now exactly duplicates that of the ACK switch on the flight control. The switch legends revert back to those of Figure 7a when all faults/emergency procedure checklists are acknowledged. If Warning Messages are displayed, the legend of the right-most switch will also be changed to "WARN ACK". The pilot has the option of using this switch to simultaneously acknowledge all Warnings, as opposed to acknowledging each one separately. This would also bypass the automatic display of each emergency procedures checklist associated with those Warnings. These checklists would then be selectable later using the "XXXX"

PROC" switches. Once the "WARN ACK" switch is depressed, its legend reverts to "CHCK LSTS".

The switches described above are the only ones actually changed when faults are being displayed. All others retain their original legends but will do nothing if depressed.

A description of the switch legends is included in Table 2.

3.2.1.5 Emergency Action Checklists

The display of emergency action checklists is accomplished through two mechanisms:

- a) Checklists associated with Warning type faults are automatically displayed after an acknowledge switch other than "WARN ACK" is actuated,
- b) All checklists may be accessed using the relegendable switches marked "PROC" as described in Section 3.2.1.4.

After the acknowledgement of an individual Warning, the associated emergency action checklist is displayed, utilizing formats (TBS) supplied by Human Factors Engineering. The checklists are manually acknowledged and are completed item by item in the same manner as the routine interactive checklists discussed later in Section 3.2.2.1. Upon completion of a checklist, the subsystem for the next highest priority Warning appears. The Warning Message is boxed in (see Figure 3) and it's checklist may then be displayed in a like manner. If there are no more Warnings, the subsystem with the next highest priority fault(s) is displayed. To access emergency checklists in a given subsystem, depressing the "PROC" switch (after all faults have been acknowledged) changes the "PROC" to "ACK" and causes EMMADS to display the checklist for the highest priority, active fault

TABLE 2. SWITCH LEGEND DESCRIPTIONS

	TABLE 2. SWITCH LEGEND DESCRIPTIONS
Legend	Description
(XXXX) DATA	Raw sensor data is displayed for the subsystems designated by "XXXX" - i.e., the Engine, Fuel, Transmission, Electrical, Hydraulic and Miscellaneous subsytems. (Formats other than Engine Subsystem TBS)
CHCK LSTS	Checklists switch legends will be selected
(XXXX) PROC	Emergency procedures (checklists) are displayed for the subsystems designated by "XXXX" (as described above for DATA legends. Formats TBS)
STAT ONLY	Display cleared except for the Dedicated Status Area (see Figure 8).
EMER STRT	Emergency Start checklist will be displayed. (TBS)
NORM STRT	Normal Start checklist will be displayed. (see Appendix 4)
T/O CHCK	Before Takeoff checklist will be displayed. (see Appendix 4)
CRSE CHCK	Cruise checklist will be displayed. (see Appendix 4)
LNDG CHCK	Before Landing checklist will be displayed. (see Appendix 4)
SHUT DOWN	Engine Shutdown checklist will be displayed. (see Appendix 4)
PERF CALC	Performance Calculation switch legends will be selected.
MTF (XXXX)	Maintenance Test Flight versions of the checklists designated by "XXXX" will be selected (provisional).
HIT CHCK	(Engine) Health Indicator Test calculation will be displayed. (see Section 3.2.2.2)
HVR PWR	Power Required to Hover (IGE and OGE) calculation will be displayed. (see Section 3.2.2.2)
MAX PWR	Maximum Available Power calcuation will be displayed. (see Section 3.2.2.2)

TABLE 2. SWITCH LEGEND DESCRIPTIONS (CONT)

Legend	Description
WT & BAL	Weight and Balance Calculation will be displayed. (see Section 3.2.2.2)
SYST TEST	System Self Test will be initiated and displayed (previsional).
LMTS SUMM	Limits Summary will be displayed (maintenance data summarized - post-flight operation. See Section 3.2.2.3.)
(XXXX) ACK	Duplicates acknowledge switch function for faults in subsystem described by "XXXX". The "XXXX" portion of the legend also reflects the subsystem being displayed (with unacknowledged faults/emergency procedures checklists).
WARN ACK	Simultaneously acknowledges all currently active Warnings.

in that subsystem, provided the checklist has not been completed since fault detection. If there are none, the switch retains it's "PROC" legend and allows a review of all checklists for that subsystem, as previously described in Section 3.2.1.4.1. Upon completion of one checklist, the next highest priority one is automatically displayed. If no more exist, the display is cleared and the switch legend returns to "DATA" as shown in Figure 8a.

An emergency checklist for a Warning may not be removed from the display unless:

- a) The checklist is acknowledged as complete by using the ACK switch on "XXXX ACK" MLDS.
- b) A higher priority fault is detected.
- c) The fault related to the checklist is cleared.

A complete list of the emergency procedures checklists associated with the CH-47C is shown in Table 3. Before any such checklists are incorporated into EMMADS, they must be rewritten observing the following criteria:

- a) Checklists consisting of so called "immediate action" items will be displayed with the idea that they will be used by the pilot, after he has already completed the items, to verify completion. This is because the required speed of reaction does not allow time to "read and respond" to such items, as the aircraft operator's manuals currently indicate.
- b) Other checklists (or portions thereof) that have no immediate action items but which provide for natural follow on responses to them will be appended to those immediate action items (e.g., Engine Cleanup and Restart combined with Engine Failure checklist).

c) Where applicable, these checklists will be displayed along with any raw data necessary for checklist accomplishment (e.g., Engine Restart shown with N_1 and TGT). Formats are TBS pending final results of a human factors study.

A suitably rewritten version of the checklists in Table 3 is TBS.

TABLE 3. CH-47C EMERGENCY ACTION CHECKLISTS

Checklist	Related Fault(s)*
 Failure of Two Engines - Low Altitude/Low Airspeed 	61
2. Failure of Two Engines - Cruise	61
3. Failure of One Engine - Low Altitude/Low Airspeed	60
4. Failure of One Engine - Cruise	60
5. Engine Restart During Flight	60, 61
6. Engine Cleanup Procedure	60, 61
7. Normal Engine Beep Trim System Failure - High Side	62, 6 3
8. N2 Governor Failure	64, 65
9. Normal Engine Beep Trim System Failure - Low Side	66, 67
10. Engine Shutdown - Complete Electrical Failure	71
11. Engine Residual Fire During Starting and Shutdown	3, 4 (Rate Trigger)
12. Engine Fire - Ground	3, 4 (Rate Triger)
13. Single Fuel Pump Failure	25, 25, 27, 28
14. Fuel Cell Overpressure	17, 19, 20, 22, 68, 69
15. Fuel Pump System Failure	23, 24
16. Fuel Low and One or Both Aft Pumps Inoperative	17-22, 26, 28
17. Failure of Both Generators	71
18. Failure of Both Transformer Rectifiers	72

TABLE 3. CH-47C EMERGENCY ACTION CHECKLISTS (Cont'd)

Checklist	Related Fault(s)*
19. Failure of One Flight Contro Hydraulic System	ol 44,4 5
20. Failure of Both Flight Cont. Hydraulic Systems	rol 70
21. Longitudinal Cyclic Trim Fa	ilure 53, 54
22. Single SAS Failure	55, 5 6
23. Dual SAS Failure	73

^{*} See Appendix 2 - Fault/Advisory List

3.2.2 System Secondary Functions

3.2.2.1 Routine Checklists

The EMMADS secondary functions are related to the flight phases. It is convenient to define the time span from system power-up to power-down as a flight. Each flight, in turn, may be divided into a number of sorties where a sortie begins with a take-off (from the ground or from hover to forward flight) and ends with a landing (to a hover or to the ground). The EMMADS may then be envisioned as normally cycling through various states based on the stage of flight. The current operational state is described by the particular routine checklist which the system is currently running or last finished running. The checklists applicable to the CH-47C are shown in Table 4, including a set of operating conditions (called modification parameters) that modify the indicated checklists. The flight state numbers shown next to each checklist are used in Figure 10 to indicate how the EMMADS would progress from state to state in any flight. It should be noted that it would be quite natural to regroup these checklists into the categories illustrated in Figure 9.

In Figure 10, a method of communicating flight state changes to EMMADS is shown. Differentiation is made between two methods of progression from one state to the next. The sequential state change paths could be brought about through the use of the ACK switch. As EMMADS moves to a new flight state, the associated routine checklist could be displayed. After the last item in a given checklist is completed, (provided there are no faults requiring acknowledgement) actuation of the ACK switch would enable the next checklist in the sequence shown.

The specifically directed state change paths indicate that the crew must make some other input to the system to produce the

TABLE 4. CH-47C ROUTINE CHECKLISTS AND MODIFICATION PARAMETERS

Routine Checklists

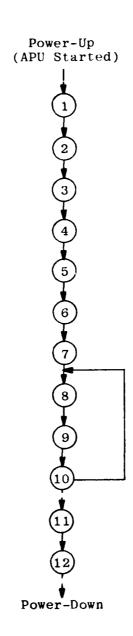
State	Checklist Title
1 2	Before Starting Engines Starting Engines
3	Engine Ground Operation
4	Before Taxi
5	Taxiing Check
6	Before Takeoff (to a hover)*
7	Hover Check
8	Before Takeoff (to forward flight)*
9	Cruise Check
10	Before Landing
11	After Landing
12	Engine Shutdown

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* (These checklists are identical in TM 55-1520-237-10-2. They are listed separately here in order to differentiate between two distinct flight modes.)

Modification Parameters

Par	rameter	Affected Checklist(s)
1.	Through-Flight Operation with crew change	Before Starting Engines Starting Engines Engine Ground Operation
2.	External Cargo Operation	Before Taxi Before Takeoff (8) Cruise Before Landing
3.	Night Flight Operation	Starting Engines Engine Ground Operation Hover Check
4.	Instrument Flight Operation	Starting Engines Engine Ground Operation Hover Check
5.	Water Operation	Before Taxi Before Landing
6.	Cold Weather Operation	Starting Engines
7.	Hot Weather Operation	Engine Shutdown
8.	Maintenance Test Flight Operation	All (except Before Takeoff and Before landing)



- Sequential State Change Path
- ---- Specifically Directed State Change Path

Figure 10. Normal Operational State Sequence

indicated state change. This would accomplished by using one of the MLDS's described in Section 3.2.4.1.

The sequential state change operating scheme would make it easy for the pilot (without removing his hands from the flight controls) to display and accomplish those checklist items most often used in helicopter operations; Before Takeoff and Before Landing. This is a particularly useful feature for both operational and training type missions, where multiple takeoffs and landings are the rule.

Given this operating scheme it is advantageous at this point to consider a representative scenario for the EMMADS operation in order to highlight other features of the routine checklists. When the system powers up it will begin to sample parameter data and display any detected faults. If the EMMADS is powered up before engine start, many subsystems will have erroneous "fault" conditions associated with them. A method for disabling fault displays must be provided, so that as each subsystem powers up to normal operation, the associated fault conditions can be enabled for display. A convenient method for doing this is through the routine checklists such as STARTING ENGINES and ENGINE GROUND OPERATION. (Note: It is assumed that the APU must be running or that external power is connected before EMMADS is powered up. In the former case, provision would have to be made for bypassing the first part of the STARTING ENGINES checklist which deals with APU starting.) The sample scenario is shown below:

a) The system powers up and enables all Advisory conditions for display. In addition, faults 11-22, 40-43, 47, 48, 57 and 58 are all enabled (see Appendix 3). The display at this point only contains data in the Dedicated Status Area unless any of the enabled faults are detected, in which case the display reflects the highest priority faults, as described in Section

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- 3.2.1.3. During power up and initialization, the switch legends should be those shown in Figure 8a. If no faults are detected, the legends will remain in that state. If any faults are detected the relegendable switches will have their legends changed as described in Section 3.2.1.4.2.
- b) Once all faults are acknowledged the pilot may either select the Dedicated Status Area, specific subsystem data or initiate the STARTING ENGINES checklist by depressing the appropriate MLDS under the display.
- c) If the checklist option is elected, this essentially places the system in State 1 of the secondary functions mode, as shown in Figure 10. Although the final checklist formats are TBS (based on the final results of human factors testing), a sample format is illustrated in Figure 11. This shows the essential elements of an EMMADS managed checklist, which are:
 - (1) An indication by the system of what the current checklist item is,
 - (2) A description of the action(s) to be taken by the crew for each item plus the required response, and
 - (3) An acknowledgement by the system that an item is complete.

In this example the system identifies the current item by boxing the procedure description and the response. The pilot accomplishes the item and indicates completion by using the ACK switch. (Note that Figure 11 is the only exception to the rule that the Dedicated Status Area is always displayed. Once an engine is

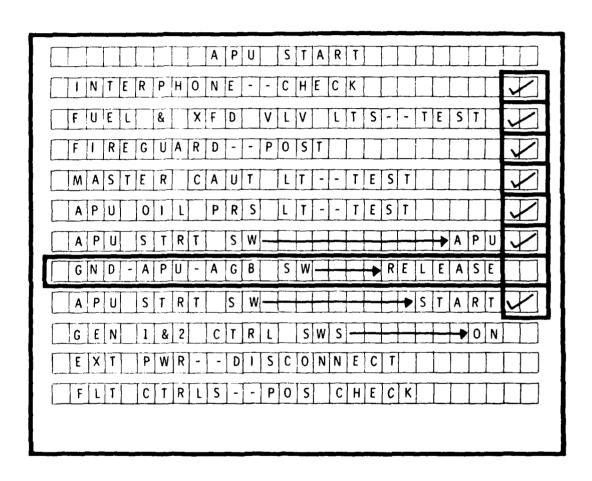


Figure 11. Sample Display Format - Full Page Checklist

started the display area available for the checklist would no longer include the Dedicated Status Area.) of When the item is sensed as completed, the response message is changed to a " " or other suitable indication of completion and the next item is boxed. The response section contains a command word or a switch legend which changes during some sequenced operation, thereby modifying the action to be taken during the course of accomplishing that item. The pilot follows these instructed changes as they appear. The sequence of item completion may loop back to a previously accomplished item, changing the desired response for that item and boxing the procedure description and new response until completion is sensed by the system.

The checklists are indexed by having the current checklist item (boxed procedure description) move down from the top until it is in the middle of the screen. From this point on the checklist items are scrolled from bottom to top so that the current item always maintains the same relative screen position. When the last item in a checklist is completed, the next actuation of the ACK switch clears the display but the system remains in the state associated with that checklist (see Figure 10 and Table 4).

d) If at any time an enabled fault is detected, that fault must be displayed in accordance with the procedures previously outlined. If a fault occurs while running a routine checklist, the checklist is replaced on the display until the fault is cleared and/or acknowledged. If there is an emergency procedures checklist that automatically follows on the acknowledgement of a

Warning then this checklist must be completed, as described in Section 3.2.1.5.

- e) If no checklist is being run and no faults are pending, actuation of the ACK switch or an appropriate MLDS causes a sequencing within the secondary functions mode to the next appropriate state (see Figure 10) and displays the routine checklist associated with that state.
- f) After the last approach is made and the aircraft is on the ground, the crew must manually select the AFTER LANDING CHECKLIST using the appropriate relegendable switch. Progression to the ENGINE SHUTDOWN CHECKLIST may then be accomplished using the ACK switch. As each system is shut down the faults normally associated with that shutdown are detected and displayed, thus allowing a post flight check of their operation. Acknowledgement of these faults clears them from the display and returns the display to the checklist at the appropriate point.

An example of the form that routine CH-47C checklists might take when rewritten for incorporation in an EMMADS is shown in Appendix 4. The section under the heading "EMMADS Actions" describes what the EMMADS does during each item and is not part of the displayed information. These checklists do not include any Maintenance Test Flight (MTF) checklists or the Emergency Start (EMER STRT) checklist listed in Table 2. These switch legends were provided to indicate such checklists as growth items for further development, since it is recognized that EMMADS must be compatible with maintenance test flight activities and also should enhance the pilot's ability to rapidly start the aircraft and evacuate it from a hazardous area (presumably under combat conditions). The checklists in Appendix 4 refer to the list of

faults in Appendix 3 by number, as regards the enabling of various fault conditions. For operations such as engine start where the pilot must normally cross correlate certain parameters (including time) with certain operations, EMMADS performs these functions for the pilot. For example, EMMADS correlates N $_1$ acceleration with time during engine start and triggers a fault indication for N $_1$ if ground idle speed is not attained 45 seconds into the start.

3.2.2.2 Performance Calculations

(TBS)

3.2.2.3 Maintenance Data Summary

(TBS)

Subsystem Parameter Data Lists for the CH-47C, UH-60A, OH-58C and YAH-64

APPENDIX I

SUBSYSTEM PARAMETER DATA LIST
FOR THE

CH-47C

SUBSYSTEM PARAMETER DATA LIST

Table: Al Sheet No.: 1

HEL I COPTER: CH-47C

SUBSYSTEM: Engine (T55-L-11D Only)

NOTE # (SH 4) -10-2, pp 2-25, 5-4 & 5-9, 8-7 & 16-1 -23-3, pp 8-1/2 -23-5, p F-64 -10-2, pp 2-25, 5-4 & 10/11, 8-17 & REFERENCES (TM 55-1520-227) 21 -23-3, pp 8-11/12 -23-5, p F-65 CONDITION TYPE - DURATION Warning - 5 sec to 0 sec (see note) Cautionary - 30 minutes Cautionary - 10 minutes Maximum - none allowed Maximum - none allowed Cautionary - Transient Maximum - continuous Maximum - 10 minutes Normal - continuous Normal - continuous Normal - continuous Maximum - Transient Normal - continuous Normal - Transient PARAMETER 103 (see note) 65-103 (see note) CONDITION 260-350 399-770 770-810 810-860 788-927 60-63 0-260 350 927 927 OPERATING MODE Eng Cond Lever in GROUND, Eng Started Eng Cond lever in FLIGHT, Eng Started Eng Shut-down Other than Eng Start Eng Start UNITS ړ (Maximum)R (See Note) (399-770)G (788-927)Y (810)B (860)R (927)R (see note) MARKINGS INDICATOR RANGE 0-1200 0-110 Circular Dials (2) Circular Dials (2) TYPE NO. 1 (2) ENGINE PERCENT RPM PARAMETER NAME-INDICATOR LABEL Engine Pur Turbine Inlet Temperature -NO. 1 (2) ENGINE TEMP Eng Gas Producer Speed -

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Sheet No.: 2

Table: Al (Engine - Cont'd)

NOTE # ~ -10-2, pp 2-25 & 5-3, 9/10 -23-3, pp 8-14/17 & -23-5, p F-59 REFERENCES (TM 55-1520-227) CONDITION TYPE - DURATION Cautionary - 30 minutes Cautionary - 10 minutes Cautionary - Transient (10 seconds) Maximum - unspecified Maximum - 10 seconds Maximum - 10 seconds Minimum - continuous Minimum - continuous Minimum - continuous Normal - continuous Normal - Continuous Warning - Transient (10 seconds) Normal - continuous Normal - continuous PARAME TER 0-89 @ 235 NR 89-100 @ 235 NR 0-91 @ 230 NR 100 @ 230-235 NR 0-85 @ 245 NR 85-97 @ 245 NR 91-100 @ 230 NR 97-100 @ 245 NR CONDITION 100-138 78-100 0-78 35-50 50-90 138 110 8 2 32 22 OPERATING MODE 45% < N1 <70% (See Note) 70% < N1 <95% 95% <N1 Single Engine Dual Engine Ę MARKINGS UNITS psi (20)R (35-90)G (110)R (78)R (100)R INDICATOR RANGE 0-150 0-200 Circular Dial w/Two Needles Circular Dials (2) TYPE ENGINE TORQUE PERCENT 1 (2) PARAMETER NAME-INDICATOR LABEL Eng Bearing No. 2 Oil Pressure NO. 1 (2) ENGINE 01L PRESS Eng Torque -

Sheet No.: 3

Table: Al (Engine - Cont'd)

		INDICATOR	86	_	_		PARAMETER	-	
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	REFERENCES (TM 55-1520-227)	NOTE # (SH 4)
Engine 0il Temperature -	Circular Diale (2)	-70-150	(138)R	ပ္စ	A11	138	Maximum - unspecified	-10-2, pp 2-25 & 5-4 -23-3, p 8-7	5
NO. 1 (2) ENGINE 01L	(2) (1810							-23-5, p F-60	
Engine 011 Level -	Caution		Amber	qts	A11	< 2.0 qts useable in the reservoir	Cautionary - unspecified	-10-2, pp 2-25 & 70 -23-2, p 4-155	9
01L LOW NO. 1 (2) ENG	(2) (3)							-23-5, p F-71	
Eng Bearing & Accessory Gearbox Integrity -	Caution Lgts (2)		Amber	1	A11	Sensor grounded by metal particles from eng bearings	Cautionary - unspecified	-10-2, pp 2-26 & 71 -23-5, pp F-168/170	7
NO. 1 (2) ENG CHIP DET						and/or gearing			
Eng Condition Lever Position/ Gas Producer Position Signal	Gaution Lgts (2)		Amber	;	A11	Error signal detected between engine condition lever position & gas		-10-2, pp 2-23 & 71 -23-2, pp 4-179/181	80
NO. 1 (2) ENG N1 CONT						producer actuator position, or eng condition lever is not in one of the detents	Cautionary - unspecified	-23-5, p F-89	

MOTES:

- 1. Reference the Operator's Manual, p 5-9, paragraphs 5-23 and 5-24, the actual upper limit of the normal N₁ speed range is obtained from the engine test log or the engine overhaul data plate. A cautionary limit is implied as being set from this maximum power speed up to 2% above this speed. However, the duration is only vaguely specified (i.e. "limit the time spent in that range"). The 103% figure was used since it is described as a maximum allowable N₁ speed for Table 5-2. The N₁ speed sensor is a tachometer generator (6704 3 phase ac type) which supplies a voltage to the indicator (M121 or M118) where the frequency is proportional to the compressor speed.
- Figure 5-5 of the Operator's Manual indicates that for engine start, with a PTIT at or above 788°C, the allowable time versus temperature equation is PTIT = -27.8t + 927 where t is in seconds and PTIT is in °C. There is no specified relationship for PTIT vs t below 788°C on engine start. Also, although not specifically stated, it is presumed that the above equation applies for acceleration and time limited operations between 927°C and 860°C. Sensors are 10 chromel-alumel thermocouple probes, connected to the indicators (MI23), which are millivoltmeters. Also included in the circuit is a variable (spool) resistor (R101) which is set between 21.95 and 22.05 ohms.
- The Operator's Manual specifies 78% and 100% as the transmission steady state torque limits for dual and single engine operations, respectively, and 100% and 130% as the corresponding transient limits. Sensors consist of a primary winding on the engine output shaft which rotates inside of a torquemeter head containing a primary and two secondary windings. A 2KHz reference signal applied to the torquemeter head assembly couples to a secondary winding while the rotating shaft induced signal is coupled to the other secondary winding. A junction box at each engine rectifies these voltages which is sensed and displayed as percent torque by the pilot's and copilot's indicators (M139 and M132). **ښ**
- Sensors are synchros (MT 710) which utilize 26 wac to produce a signal proportional to oil pressure, driving the No. 1 (2) engine indicators (M114 and M117). The operating mode for 20 psi minimum oil pressure is stated in the Operator's Manual as "ground idle". Normal N, speed at ground idle is 60%-63% but this leaves undefined the 0-60% and 63%-70% ranges. Thus 45%-70% N, was chosen to apply the 20 psi minimum bil pressure to as a range which would include the ground idle state with nearly all possible N, speeds. Less than 45% would be a "don't care" condition since this would be a result of shutdown or a hung start.
- Sensors are bimetalic thermistor type probes which change resistance linearly with temperature. The power to operate the No. 1 (2) indicators (M112 and M115) comes from the 28 VDC Primary Bus.
- Sensors are level detecting micro switches in each oil tank which are grounded when the tripping threshold is reached. The signals are routed to caution panel through connector pins F & H. If oil consumption exceeds 2 qts/hour, write up required (-10-2, p 2-24). ė
- Sensors are three magnetic plugs positioned in the accessory gearbox sump, in the No. 2 bearing external oil return line and in the No. external oil return line. The plugs are likely grounded by metal chips, thus grounding pins A & B of the caution panel connector. ۲.
- Sensors consist of a servo amplifier card to detect the position errors between the synchros in each engine control system. Additional sensors are the detent detecting microswitches for each engine condition lever. The error signal is sent to pins P173 E and X on the caution panel.

SUBSYSTEM PARAMETER DATA LIST

Sheet No.: 1

Table: A2

HEL ICOPTER: CH-47C

SUBSYSTEM: Fuel

NOTE # (SH 2) ~ m -10-2, pp 2-31/32, 53, 56, 71 & 75 -23-3, p F0-24 -23-5, p F-69 -10-2, pp 2-31/32 & 70 -23-4, p F0-33 -23-5, p F-147/148 REFERENCES (TM 55-1520-227) -10-2, pp 2-32 -23-4, p F0-33 -23-5, p F-149 CONDITION TYPE - DURATION Cautionary - unspecified Cautionary - unspecified Cautionary - unspecified Cautionary - unspecified Warning - none allowed Normal - continuous PARAMETER 0-(320-420) (320-420)-6804 CONDITION <(9-11) <(320-420) \$ OPERATING MODE Pressure altitude <6000' Pressure altitude >6000 E A] UNITS psi psi Jps MARKINGS Amber Amber Amber None INDICATOR RANGE 0-2300 6666-0 ŀ ł ſ No pointer indication but con-tinuous digital readout on dial. Inde-pendent of selector sw position. Circular Dial w/Pointer & Selector Switch Press to Test Caution Lgts (2) Caution Lgts (2) Caution Lgts (2) TYPE AUX PRESS LEFT (RIGHT) SIDE Fuel Quantity in the Aft, Main and Fwd Tamks on both the Left & Right Sides -Auxiliary Tank Fuel Boost Pump Pressure -FUEL QUANTITY L(R) AFT, MAIN, FWD FUEL QUANTITY TOTAL L(R) FUEL LOW PARAMETER NAME-INDICATOR LABEL Engine Fuel Line Pressure -L(R) FUEL PRESS

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NOTES:

1. Sensors are ten capacitance type probes, three in each main tank and one in each auxiliary tank. The three probes in each main tank are wired in parallel, with one of the resulting twin lead-outs from each tank wired to the selector switch, while the remaining lead-outs are tied together at the indicator. For the auxiliary tank probes, one line from each probe is connected to the selector switch and the other lines are tied together at the indicator. The cautionary range specification is based on the low fuel caution light threshold and not on a dial marking. Note that tank capacities are all different, even for like tanks (TMS5-1520-227-10-2, p 2-75).

Sensors are thermistor bead type units (A608 - Right and A609 - Left) at the lower end of the center fuel quantity probes (MT 604 and MT 609) in the main tanks. The signal is routed to the thermistor control unit (A142) which signals the caution panel when a main tank is down to about 20% of its capacity (see reference quoted in Note I above). in the

Sensors are pressure switches between the aft auxiliary tank and the engine fuel valves. The switch closes a path from the caution panel to ground when the low pressure threshold is reached. Operation above 6000' pressure altitude with the light on is likely to cause an engine flameout.

Sensors are four pressure switches, one for each auxiliary boost pump. The pressure switches on the same side of the aircraft provide a path to ground for the same light, but through the separate auxiliary boost pump switches (via a separate set of contacts in each switch) for that side. Thus, the pressure loss may be tracked to the specific line by alternately turning ON and OFF the Fwd and Aft Auxiliary Boost Pump switches for the affected side. Since power to the lights is through breakers which protect the pump relay power lines (see Table A5) a tripped circuit breaker would cause a fuel pressure loss with no light to show such loss. ÷

SUBSYSTEM PARAMETER DATA LIST

Sheet No.: 1

Table: A3

HEL I COPTER: CH-47C

SUBSYSTEM: Powertrain

NOTE # m ~ -10-2, pp 2-41/43, 70 8 5-5 -23-3, pp 8-50/54 8 F0-22 -10-2, pp 2-45, 5-2, 3 23-2, p 4-51 -23-3, pp 8-63 & 64 -23-5, p F-63 -23-5, p F-53 (Also 55-1500-210-MTF p 2-76) REFERENCES (TM 55-1520-227) CONDITION TYPE - DURATION Cautionary - unspecified Cautionary - unspecified (see note) Normal - continuous (245 rpm if gross weight >40,000 lbs) Maximum (power turbine limit) - 5 minutes Maximum (power turbine limit) - 5 seconds Cautionary - transient Maximum - continuous Minimum - continuous Minimum - continuous Minimum - continuous Minimum - continuous Normal - continuous Maximum - transient Normal - continuous PARAMETER 256-262.5 CONDITION 251-255 261-265 214-232 235-245 232-261 ₹50 12 214 232 250 265 20-90 2 20 Ground Ops, Min Beep, Eng Cond Lyrs @ FLIGHT OPERATING MODE N1 >63% Powered Flight Autoro-tation 60% <N1 <63% Ę MARKINGS | UNITS R PM psi (214)R (214-232)Y (232-250)G (250-255)Y (255)R (261)R (20)R (20-90)G Amber INDICATOR RANGE 0-290 0-100 ; XMSN OIL PRESS Caution Lgt Circular Dial W/Selector Switch Circular Dial TYPE XMSN OIL PRESS PARAMETER NAME-INDICATOR LABEL Forward, Aft, Combining & Engine Gearboxes Oil Pressure -Rotor Speed -RPM ROTOR

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Sheet No.: 2

Table: A3 (Powertrain Cont'd)

NOTE # (SH 3) 9 -10-2, pp 2-43 & 71 -23-2, pp 6-129/132, 135/137, 155 & F0-12/13 -23-5, pp F-168/170 -10-2, pp 2-42/43, 70/71, 5-5 8 9-9 -23-2, pp 6-173 8 -23-3, pp 6-17/52 -23-5, pp F-51/53 8 169 REFERENCES (TM 55-1520-227) Maximum (engine gearboxes only) - 1 hour CONDITION TYPE - DURATION Cautionary - unpsecified Cautionary - unspecified
(see above limits) Cautionary - unspecified Cautionary (engine gearboxes only) ~ 1 hour Maximum (all but engine gearboxes) - continuous Normal - continuous PARAME TER Sensor contacts grounded by metal particles from geargoxes or thrust bearing CONDITION 130-140 <130 >190 140 >130 130 OPERATING MODE A] A11 I UNITS ပ ; (130)R (130-140)Y (140)R MARK I NGS Amber Amber Amber INDICATOR -70-150 RANGE ; Circular Dial W/Selector Switch Caution Lgt Caution Lgt Caution Lgts (2) TYPE Forward, Aft & Combining Gearboxes & Aft Vertical Shaft Thrust Bearing Integrity -NO. 1 (2) ENG XMSN HOT XMSN CHIP DET XMSN OIL TEMP PARAMETER NAME-INDICATOR LABEL Forward, Aft, Combining & Engine Gearboxes Oil Temp -XMSN OIL HOT

OTES:

- 1. Sensor is identical to that used for the gas producer speed indicating system and is located on the Forward Transmission. The indicator is a dual pointer type, with an inner scale range of 0-130 RPM and an outer scale range of 130-290 RPM. Note that the normal rpm range during autorotation is based on the minimum green arc rpm and the specification by the Operator's Manual (p 5-2) of 261 rpm as the "maximum continuous rotor speed during autorotation". Note that although the range 214-232 is marked as a cautionary range, it is probably meant to be a transient range which is also normal for ground operations.
- Sensor is a variable reluctance transformer which supplies a differential voltage, proportional to the sensed pressure, to selector switch circuitry associated with the indicator. ۶.
- Sensor is a switch which is built into the oil pressure indicator (M103). The switch grounds the sensing lead from the caution panel when the threshold is reached for the gearbox being monitored by the oil pressure indicator switch. When the selector switch is in scan, the lowest pressure is displayed and the caution light will act as a warning device for whichever gearbox oil pressure goes below the minimum allowable.
- Sensors are electrical resistance type temperature bulbs, calibrated to provide 1200 ohms at 0°C. They are incorporated into a wheatstone bridge where the resulting voltage inbalance drives a motor which moves the wiper arm of the bridge's variable resistor as well as the indicator pointer. The sensor used in the bridge depends on the position of the XMSN OIL TEMP selector switch. A faulty sensor is indicated by the pointer going above 150° when the selector switch is set to ScAN or below -70° when the switch is set to the faulty sensor's position.
- Sensor is a switch in the temperature indicator described above. Again the light will only indicate an excessive temperature condition for the gearbox designated by the selector switch. ŝ
- The system is in talled only on aircraft #74-22276 and subsequent. Sensors are thermoswitches which are part of a combined chip detector/temperature sensor assembly. The sensing is most likely accomplished by grounding the lead from the caution panel for the affected caution capsule. •
- Sensors are bayonet-type electrical contact/magnetic plug combination detectors which provide a grounding path when ferrous type particles bridge the contacts. This ground is sensed by the caution panel circuitry, which lights the caution capsule.

SUBSYSTEM PARAMETER DATA LIST

Sheet No.: 1 Table: A4

HELICOPTER: CH-47C

SUBSYSTEM: Pydraulic

SUBSTSTEM: Fydrautic	<u>ر</u>								
_		INDICATOR	.0R		1		YAKKE IEK	REFERENCES	NOTE #
PARAMETER NAME-	TYPF	RANGE	MARKINGS UNITS		OPERALING MODE	MCITIONOO	COMPITION TYPE - DURATION	(TM 55-1520-227)	(SH 2)
INDICATOR CABLE						2500	Minimum - continuous		·
Hydraulic	Circular	0-4000	(2500-3200)G			2500-3200	Normal - continuous	-10-2, np 2-40, 70 8 5-8	p-1
NO. 1 (2)	Dials (2)		(3200)R			>3200	Maximum - continuous	-23-3. nn 7-20.	
8008							l	-23-5, p F-50	2
NO. 1 (2) HYD Caution	Caution	<u> </u>	Amber	psi	A11	<(2050-1950) 	Cautionary - unspecified		
1800S1 UF	Lyts (£)					2500	Minimum - continuous		,
Utility Hydrau-			(2500)R					-10-2, pp 2-40 & 5-8	·
Dressure -	Dial	0-4000	(2500-3400)6			2500-3400	Normal - continuous	-23-5, p F-121	
3 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7			(3400)R			3400	Maximum - continuous		
UTILITY									

Table: A4 (Hydraulic - Cont'd)

MOTES:

1. Sensors are 26 VAC. 400 Hz synchro units driving similar units for indicators. 200 psig fluctuations possible with rapid control movements. Normal tolerance ±50 psig.

2. Sensors are pressure switches which ground the sensing lines from the caution panel. Power to the capsules is provided via the CAUTION LGTS circuit breaker. The switching threshold used is from the fourth page reference, versus the 2000-2100 psi threshold given in the first page reference.

3. Sensor is the same type as in Note 1 above. Normal tolerance $\pm 50~\mathrm{psig}$.

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SUBSYSTEM PARAMETER DATA LIST

Table: A5

HELICOPTER: CH-47C

SUBSYSTEM: Electrical	ical							She	Sheet No.: 1
DADAMETED MANE		INDICATOR	70R		OBLIANTING		PARAMETER	S C C C C C C C C C C C C C C C C C C C	MOTE .
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-227)	(SH 21)
Generator Output Suitability -						Volts out >132 vac (3 seconds), volts out <100 vac (3 phse aver, 5-7		-10-2, pp 2-57 & 70	
NO. 1 (2) GEN OFF	Caution Lgts (2)	ł	Amber		All	seconds), freq. out (345 or feeder fault >33.3 amps.	Cautionary - unspecified	-23-3, pp 9-18/20, & F0-28 & 30 -23-5, p F-179	
				· · · · · · · · · · · · · · · · · · ·		nected from the Primary or Sec- ondary bus respectively			
B Phase					Gener-	0-1.0	Normal - continuous		
Load -	Circular	0-1.5	;	Load	on line	1.0 - 1.5	Cautionary (overdraw) - unspecified	-10-2, p 2-13, 56 -23-3, p 8-67 & F0-28	
NU. 1 (2) GEN	Utais (2)			ract	Gener- ator off line	Positive or Negative Load	Cautionary - unspecified	-23-5, p F-1/9	~
AC External Pwr Connection & Suitability -	Caution Lgt	:	Amber	}	A11	External power is connected to the AC Primary Bus	Advisory - unspecified		ю
AC EXT PWR ON						,		-23-5, p F-179	
DC Power Supply						0-1-0	Normal - Continuous		
Load -	Circular	0-1.5	;	Load	Rectifier on line	1.0 - 1.5	Cautionary (overdraw) -	-10-2, pp 2-13 & 5/ -23-3, pp 8-65/66	4
NO. 1 (2) RECT	(2) SIBIO			rract	Rectifier off line	Positive or Negative Load	P -	-63-5, p F-135	
DC Power Supply Output -	10:		44		411	Output voltage of respective power		-10-2, pp 2-57 & 70	
NO. 1 (2) RECT OFF	Lgts (2)	1		} 		supply less than that of bus it supplies. Power	Cautionary - unspecified	-23-5, pp 9-1/3, 11 g F0-26 -23-5, p F-135	n
						supply discon- nected from bus			

Table: A5 Electrical (Cont'd)

PARAMETER NAME- INDICATOR LABEL	TYPE	INDICATOR RANGE (TOR MARK TNGS	UNITS	OPERATING MODE	CONDITION	PARAMETER CONDITION TYPE - DURATION	REFERENCES (TM 55-1520-227)	NOTE #
DC External Pwr Connection and Suitability - DC EXT PWR ON	Caution Lgt	;	Amber		All	External power is connected to the DC Primary Bus	Advisory - unspecified	-10-2, pp 2-57 8 71 -23-3, pp 9-2/3, 12 8 -23-5, p F-135	٠
Generator No. 2. Bus Tie & Aux. Bus Relays					Both gen- erators on line	>5 amps to all relays from the 28 VDC Primary Bus			
K107) Power Overdraw	Tripped Crct Brkr (CB 110)	;	ဟ	Атрѕ	Eng. Start	>5 amps to relays K105 & K103 only. Same power source.		-10-2, pp 2-54 & 59 -23-3, pp F0-28 & 30 -23-5, p F-179	
					Gen. No. 2 off line	>5 amps to relays K107 & K105 only. Same power source			
115 VAC Primary Bus Power Overdraw - A PH FDR	Tripped Crct Brkrs (CB 1031, CB 1033 & CB 1035)					>10 amps through			7
115V AC PRI BUS FEEDERS	Tripped Crct Brkrs (CB 199, CB 1001 & CB 1003)					ser from the 200 VAC Primary Bus, A phase			
115 VAC Secondary Bus Pwr Overdraw - B PH FDR	Tripped Crct Brkrs (CB 1015, CB 1017 & CB 1019)		10	Amps	A11	>10 amps through respective breaker set from the 208		-10-2, pp 2-52/53 & 55	
115V AC SEC BUS FEEDERS	Tripped Crct Brkrs (CB 1005, CB 1007 & CB 1009)					M. Secondary bus,		.cc	ω
26 VAC Instrument Bus Pur Overdraw - 26 VAC FDR	Tripped Crct Brkrs (CB 1041, CB 1043 & CB 1045)					>10 amps through respective breaker			
26 VAC INSTR BUS FEEDERS	Tripped Crct Brkrs (CB 1012, CB 1014 & CB 1016)					but winding of the 115/26V transformer			

Table: A5 Electrical (Cont'd)

ARAMETER NAME.		INDICATOR			OPERATING		PARAMETER			# L1 12 12 12 12 12 12 12 12 12 12 12 12 12
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TIPE - DUR	- DURATION ((14 55-1520-227)	(SF. 21)
115/26V Trans- former Primary Pwr Overdraw - 115-26V XMFR	Tripped Crct Brkr (CB 1039)		.s			>5 amps to the primary winding from the 208 VAC Primary Bus (phase unknown)		-10-	-10-2, pp 2-52/53 & 55 -23-5, p F-185	
DC Power Supply Pur Overdraw - XFMR RECT NO. 1 (2)	Tripped Crct Brkrs (CB 1011 & CB 1013)		35		-	335 amps to the respective pur supply from the 208 VAC Primary and Secondary Busses respectively				
Bus Tie & Radio Bus Tie Relays (K112 & K116) Pwr Overdraw -	Tipped Crct Brkrs (CB 1024 &		S		#1 Pwr Supply off, #2 on	>5 amps to relays through CB 1090, from the 28 VDC Secondary Bus				
DC BUS CONT NO. 1 (2)				Amps	#2 Pwr Supply off, #1 is on	>5 amps to relays through CB 1024 (unless an engine is being started) from the 28 VDC Primary Bus				
Reverse Current Relays (K126 & K128) Volt Relay Coil, Bias Coil A Main Cont Coil Power	Tripped Crct Brkrs (CB 1018 & CB 1020)					>15 amps to relays of respective RCR (K126 or K128) from the output of the respective power supply		-10-2, -23-3, -23-5,	-2, pp 2-54, 56 & 59 -3, pp 9-10 & F0-26 -5, pp F-135 & 141	
REV CUR CO NO. 1 (2)		!	15		LIA					
External Power (Kil4) & Ex- ternal Power Control (Ki22) Relays Power Overdraw -	Tripped Crct Brkr (CB 1022)					>15 amps to the relays from the DC External Power source				
DC EXT PMR CONT										

Sheet No.: 4

			1				,
NOTE	(SH 21)				ω		
DEFEDENCES	(TM 55-1520-227)			-10-2, pp 2-54, 56 & 59 -23-3, pp 9-10 & F0-26 -23-5, p F-135 & 141			-10-2, pp 2-23, 56 & -23-2, pp 4-190/192 & F0-11
PARAMETER	CONDITION TYPE - DURATION						
	CONDITION	>15 amps to the bus from the DC Circuit Breaker Box Battery Bus	>35 amps through the respective breaker set, from	breaker box 28 VDC Primary Bus	550 amps through the respective breaker set from the DC circuit breaker box 28 VDC	secondary bus	>5 amps to applicable reable relay and respective engine beep trim actuator from the 28 'DC Primary Bus
ODEDATING	MODE				LIA		
	UNITS				Amps		
10R	MARKINGS	15	35		99		w
INDICATOR	RANGE						
	TYPE	Tripped Crct Brkr (CB 1026)	Tripped Crct Brkrs (CB 1046, CB 1048 & CB 1050)	Tripped Crct Brkrs (CB 1034, CB 1036 & CB 1038)	Tripped Crct Brkrs (CB 1038, CB 1030 & CB 1032)	Tripped Crct Brkrs (CB 1040, CB 1042 & CB 1044)	Tripped Crtt Brkrs (GB 130 & CB 167)
PARAMETED NAME	INDICATOR LABEL	Overhead Panel Battery Bus Pwr Overdraw - BTRY BUS FEEDER	Overhead Panel 28 VDC Primary Bus Power Overdraw - 28 VDC PRIMARY BUS FEEDERS	28V DC PRI BUS FEEDERS	Overhead panel 28 VDC Secondary Bus Power Overdraw - 28 VDC SECONDARY BUS FEEDERS	28V DC SEC BUS FEEDERS	Engine Con- dition Relays (K503 & K505) and Beep Trim Actuators Pwr Overdram - ENG TRIM DC

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Table: A5 Electrical (Cont'd)

UNITS	INDICATOR NGE MARKINGS UN
Normal Engine Trim On	Normal Engine Trim On
Normal Eng Trim OFF, No. 1 (2) EMERG ENG TRIM Switch actuated	Normal Eng Trim 5 Amps OFF, No. 1 (2) EMERG EN TRIM Switch actuated
Eng 1 or 2 start button de- pressed (respec- tively)	Eng 1 or 2 start button de pressed (respectively)
Same as above but also respective eng condition dition lever @ GROUND, ignition lock, start fuel & ignition switches all ON	Same as above but also respective eng condition lever @ GROUND, ignition lock, start fuel & fuel & fuel & fuel & fuel & ignition switches all ON

Sheet No.: 6

NOTE # (SH 21) 6 10 7 |-23-2, pp 4-179/181 8 | F0-9/10 |-23-5, p F-91 28 -10-2, pp 2-52, 53 & -23-3, p F0-20 -23-5, p F-59 -10-2, pp 2-22/23, 56 & 59 -23-2, pp 4-134 & 135 -10-2, pp 2-33, 56, 5 & 59 -23-3, p 9-95 -23-5, p F-48 -10-2, pp 2-20, 56 & 59 REFERENCES (TM 55-1520-227) CONDITION TYPE - DURATION PARAMETER spective power sup-ply which provides the 2 KHz refer-ence signal to the torque meter head assembly. Power is from the 28 VDC >5 amps to the copiols & pilot's indicators, respectively, from the l15 VAC Primary Bus >5 amps to the respective valves (type 114PS208-3) from the 28 VDC >5 amps to the retion lever in >5 amps to system GROUND from the 28 VDC position Primary Bus >5 amps to brake from the 28 VDC Primary Bus CONDITION Primary Bus Primary Bus OPERATING MODE Respec-tive eng condi-(inter-lock sw closes) A1 UNITS Amps MARK INGS Ŋ INDICATOR RANGE Tripped Crct Brkrs (CB 1087 & CB 1094) Tripped Crct Brkrs (CB 145 & CB 147) Tripped Crct Brkrs (CB 1077 & CB 1079) Tripped Crct Brkrs (CB 1073 & CB 1075) Tripped Crct Brkr (CB 107) TYPE Fairing Hot Air Valve Power Overdraw -Ground Idle Pwr Interlock Relay & Gas Producer Engine Torque-meter Indicator Pwr Overdraw -NO. 1 (2) ENG TORQUE AC ENG COND CONT NO. 1 (2) Thrust Control Magnetic Brake Pwr Overdraw -PARAMETER NAME-INDICATOR LABEL NO. 1 (2) ENG TORQUE DC ENG NO. 1 (2) ANTI-ICE Control Relay Mormal Power Overdraw -THRUST BRAKE Engine Power Supply Power Overdraw -

- 1

Table: A5 Electrical (Cont'd)

REFERENCES NOTE	(TM 55-1520-227) (SH 21)	-10-2, pp 2-25, 53 & 56 -23-3, p 8-6 -23-5, p F-62	p 2-56 & 59 8-10 F-60		-10-2, pp 2-27/29, 53, 55/56 & 59 -23-4, p 10-116 -23-5, p F-147		
		-10-2, pp 2-22 56 -23-3, p 8-6 -23-5, p F-62	-10-2, pp 2-56 -23-3, p 8-10 -23-5, p F-60		-10-2, p		
PARAMETER	CONDITION TYPE - DURATION						
	CONDITION	>5 amps to the transmitters & indicators from the 26 VAC INSTR BUS	>5 amps to the indicators from the 28 VDC Primary Bus	>5 amps to relays K411 & K413, re- spectively, in the Left Relay Box (114E2015-10) from the 28 VDC Primary Bus	55 amps to same relay numbers as above but in the Right Relay Box, same pwr source	>5 amps to the re- spective pump from the AC Primary Bus	>5 amps to the respective pump from the AC Secondary
OPERATING	MODE				All		
	UNITS				Amps		
VTOR.	MARKINGS				ın		
INDICATOR	RANGE						
	TYPE	Tripped Crct Brkr (CB 116)	Tripped Crct Brkr (CB 121)	Tripped Crct Brkrs (CB 1052 & CB 1047)	Tripped Crct Brkrs (CB 1049 & CB 1051)	Tripped Crct Brkrs (CB 1027 & CB 1029)	Tripped Crct Brkrs (CB 1025 &
PARAMETER NAME.	INDICATOR LABEL	Engine Oil Pressure Systems Pur Overdraw - PRESS IND ENG	Engine 011 Temperature Indicators Pur Overdraw - ENG 01L TEMP	Main Fuel Boost Pump Relays (K411 & K413) Pur Overdraw - FUEL PUMP CONTROL L FND (AFT)	FUEL PUMP CONTROL R FND (AFT)	Main Fuel Boost Pumps Power Overdraw - FWD LH (RH) FUEL PUMP	AFT LH (RH) FUEL PUMP

Sheet No.: 8

PARAMETER NAME.		INDICATOR	T0R		ODEDATING		PARAMETER	STOREGUE	MOTE #
LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	NOTITION	CONDITION T/PE - DURATION	(TM 55-1520-227)	(SH 21)
Auxiliary Fuel Boost Pump Relays (K409 & K415) Power Overdraw - AUX TANK FUEL PUMP CONT L FMD (AFT)	Tripped Crct Brkrs (CB 1067 & CB 1069)					As amps to relays K409 & K415, re- spectively, in the Left Relay Box (114E2015-10) from the 28 VDC Secon- dary Bus (also to L Low Aux Press light, DS1070, if either right side aux fuel boost pump Sw is ON)			
AUX TANK FUEL PUMP CONT R FMD (AFT)	Tripped Crct Brkrs (CB 1063 & CB 1065)					>5 amps to same relay numbers as above but in the Right Relay Box, same pwr source. (Also to R Low Aux 1041, if either left side aux fuel boost pump switch is ON.)		-10-2, pp 2-27/29, 53, 55/56 & 59 -23-4, p 10-115 -23-5, p F-149	
Auxiliary Fuel Boost Pumps Pwr Overdraw - FWD LH (RH) AUX FUEL PUMP	Tripped Crct Brkrs (CB 1059 & CB 1055)		ശ	Amps	All	>5 amps to respective pump from the			
AFT LH (RH) AUX FUEL PUMP	Tripped Crct Brkrs (CB 1061 & CB 1067)					respectively			
Crossfeed Fuel Valves and Crossfeed Fuel Lights Power Overdraw - FUEL CONT	Tripped Crct Brkr CB 1010					>5 amps to left or right valve/light system, as a func- tion of the Cross- feed Fuel Valves switch, from the 28 VDC Primary Bus		-10-2, p 2-27/30, 56 & 59 -23-4, p 10-105 -23-5, pp F-153/155	13

Table: A5 Electrical (Cont'd)

2		INDICAT	ATOR		0.000		PARAMETER	1	
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPEKALI NG MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-227)	(SH 21)
Emergency Eng- Fuel Shutoff Valve Power Overdraw - FUEL SHUTOFF ENG NO. 1 (2)	Tripped Crct Brkrs (CB 197 & CB 195)					>5 amps to respective valves and their associated indicator lights, from the 28 VDC Primary Bus		-10-2, pp 2-30, 56 8 59 -23-4, p 10-104 -23-5, pp F151-152	13
Fuel Quantity Indicator Power Overdraw - FUEL QTY IND	Tripped Crct Brkr CB 118					>5 amps to the gauge from the 115 WAC Primary Bus		-10-2, pp 2-31, 53, 56	
Low Fuel (Thermistor Control) Unit Pur Overdraw - FUEL CONT QTY	Tripped Crct Brkr CB 120					>5 amps to the con- trol unit from the 28 VDC Primary Bus		-23-5, pp f-69	
Transmission Oil Pressure Indicating Sys Pur Overdraw - XMSN OIL IND PRESS	Tripped Crct Brkr (CB 119)		w	Amps	A13	>5 amps to system from 115 VAC Primary Bus		-10-2, pp 2-41, 53 8 -23-3, p F-53	
Transmission Oil Temperature Indicating Sys Pur Overdraw - XMSN OIL IND	Tripped Crct Brkr (CB 106)			·		>5 amps to system from 115 VAC Primary Bus		-10-2, pp 2-42/43, 53 -23-3, pp 8-57 & 58 -23-5, p F-51	
Hydraulic Pressure Transmitter & Indicator Synchros Pwr Overdraw - PRESS IND HYD	Tripped Crct Brkr (CB 108)					>5 amps to units from the 26 VAC Instrument Bus		-10-2, pp 2-53 & 56 -23-3, pp 8-47 & -93/95 -23-5, pp F-40 & 49	

Sheet No.: 10

NOTE # (SH 21)

-10-2, pp 2-35, 52/56 4 59 -23-3, p 9-95 -23-5, p F-45 -10-2, pp 2-36/37, 56 & 59 -23-5, p F-41 -23-3, p F0-15 -23-5, pp F-83, 121 & -10-2, pp 2-40, 56 & 59 REFERENCES (TM 55-1520-227) 26 -10-2, pp 2-40, 58 -23-3, p F0-14 -23-5, p F-49 CONDITION TYPE - DURATION PARAME TER >5 amps to the centering spring & speed trim amplifier from the 28 VDC Secondary Bus >5 amps to systems from the 28 VDC Primary Bus >5 amps to the speed trim ampli-fier from the 115 VAC Secondary Bus >5 amps to solen-oids from the 28 VDC Secondary Bus >5 amps to units from the Battery Bus CONDITION OPERATING MODE Ę Amps UNITS MARK I NGS S INDICATOR RANGE Tripped Crct Brkrs (CB 117 & CB 115) Tripped Crct Brkr (CB 175) Tripped Crct Brkr (CB 109) Tripped Crct Brkr (CB 103) Tripped Crct Brkr (CB 101) TYPE Flight Control Hydraulic Boost Solenoids Pwr Overdraw -#1 and #2 SAS Amplifiers DC Voltage Supply and Hydraulic Solenoid Valves Pur Overdraw -Pitch Stability
Augmentation
System Power
Overdraw -Accessory and Utility Solen-oid (L179).
Thermal Switch (S711) & Air Cooler Solen-oid Valve (L717) Power HYD BOOST CONT PARAMETER NAME-INDICATOR LABEL Collective Pitch Trim Sys Pwr Overdraw -SPEED TRIM DC SPEED TRIM AC UTILITY HYD SYS Differential

7

NO. 1 (2) SAS DC

Table: A5 Electrical (Cont'd)

Sheet No.: 11

-	(SH 21)		15				
	PLFERENCES (TM 55-1520-227)	-10-2, pp 2-35, 52/56 & 59 -23-3, p 9-95 -23-5, p F-45	-10-2, pp 2-33, 56, 58 -23-3, p 9-95 -23-5, p F-48	-10-2, pp 2-36/37, 56 -23-5, p F-41	-10-2, pp 2-56 & 59 -23-3, pp 9-95, 98/99 & FO-28 -23-5, pp F-77, 161,		-10-2, pp 2-45, 53 & 56 -23-3, pp 8-30/31 & 36 -23-5, p F-73
PARAMETER	CONDITION TYPE - DURATION						
	CONDITION	>5 amps to systems from the 115 VAC Primary Bus	>5 amps to yaw magnetic brake & pitch and roll trim actuators from the 28 VDC Battery Bus	7.5 amps to the respective actuators through the corresponding manual operation switches, from the 28 VDC Primary Bus	>5 amps to system including negative fault sensed/ triggered caution capsule lamps, but excluding K110, from the 28 VDC primary Bus	Same as above but including KIIO	>5 amps to heaters from the 115 VAC Secondary Bus
	MODE		Ş	č	Bright/ Dim sw at BRIGHT	Brignt/ Dim sw at DIM	A11
	UNITS				Sdiff		
TOR	MARKINGS	Z.	,		s.	,	જ
INDICATOR	RANGE					-	
	TYPE	Tripped Crct Brkrs (CB 113 & CB 111)	Tripped Crct Brkr (CB 105)	Tripped Crct Brkrs (CB 102 & CB104)	Tripped Crct Brkr (CB 112)		Tripped Crct Brkr (CB 137)
OADAMCTED WANT	INDICATOR LABEL	#1 and #2 SAS Amplifiers AC Voltage and Rate Gyros Pur Overdraw - NO. 1 (2) SAS AC	Centering Device Release Mechanisms Pur Overdraw - CONT CTR	Manually Com- manded Cyclic Trim Actuators Pwr Overdraw - CYCLIC TRIM ACT AFT (FWD)	Caution Panel and/or Master Caution Lights, & Troop Jump Signal Light Dimming Relay (K110) Power Overdraw -	CAUTION LGTS	Pitot Tube Heater Pwr Overdraw - PITOT HEAT

Sheet No.: 12

OPERATING CONDITION
>7.5 amps to heaters from the 115 VAC Secondary Bus
>5 amps to the respective temperature controller & relay from the 28 VDC Secondary Bus, through the respective circuit breaker
>25 amps (CB 155 & CB 159) to the pilot and copilot windshield hearing elements (respectively) from the 115 VAC Secondary bus (phases A & C)
>10 amps (CB 157) to the center wind- shield heating ele- ment from the 115 VAC Secondary Bus (phase B)

Sheet No.: 13

MOTE # (58 52) -10-2, pp 2-47/48, 52, 53 & 55 -23-3, pp 9-48/49 -23-5, p F-127 -10-2, p 2-48, 54 & 59 -23-5, pp F-130/131 -23-3, pp 9-7/11 & 45/46 -23-5, p F-114 & 129 -10-2, pp 2-46, 53/55 & 59 -10-2, pp 2-46, 56 & 59 (TM 55-1527-227) REFERENCES -23-4, p 12-27 -23-5, p F-117 CONDITION TYPE - DURATION PARAMETER >15 amps to the respective unit from the 28 VDC >5 amps to outlet from the 28 VDC Secondary Bus >10 amps to motor from the 28 VDC respective unit from the 208 VAC Auxiliary Bus & the 208 VAC Secondary Bus, respectively >15 amps to the respective unit from the 28 VDC Secondary Bus >15 amps to the CONDITION Secondary Bus OPERATING MODE All MARKINGS | UNITS Amps 10 15 INDICATOR RANGE Tripped Crct Brkrs (CB 168 & CB 166) Tripped Crct Brkrs (CB 178 & CB 176) Tripped Crct Brkrs (CB 179 & CB 177) Tripped Crct Brkr (CB 170) Tripped Crct Brkr (CB 172) Tripped Crct Brkr (CB 174) Tripped Crct Brkr (CB 1066) TYPE Cockpit Utility Receptacles Pwr Overdraw -UTILITY RECEPTACLE LH FWD (AFT) UTILITY RECEPTACLE RH FWD UT RECP RH AFT PARAMETER NAME-INDICATUR LABEL Cabin Utility Receptacles Pwr Overdraw -Tracking Receptable Pwr Ovendraw Windshield Wiper Motor Pwr Overdraw -MISSILE WARM UP #1 (2) Receptacles 1 & 2 Power Overdraw -UTILITY REC PILOT (COPILOT) Missile Warmup WSHLD WIPER Strobex Blade BLADE TCK

Sheet No.:

	1)		 -						
	(SH 21)			·					
DEFEDENCES	(TM 55-1520-227)			-10-2, pp 2-49, 52,	-23-5, p F-77				
PARAMETER	CONDITION TYPE - DURATION								
	CONDITION	>15 amps to the blower on any or all phases, from the 208 VAC Auxiliary Bus	>7.5 amps to relay K137 from the 28 VDC Primary Bus	>7.5 amps to all components. Same power source.	>7.5 amps to all components except the Fuel Control solenoid valve.	>7.5 amps to all relays except Kl37 and K205. Same power source.			
ODEDATING	MODE	All	Hea New Yen Ne						
	UNITS	Amps							
70R	MARKINGS	15	15						
INDICATOR	RANGE				_				
	TYPE	Tripped Crct Brkr (CB 141)		Tripped	(CB 143)				
PADAMETER NAME.	INDICATOR LABEL	Heater Blower Pur Overdraw - BLOMER		Heater System Relays (K137, K205, K207, K209, & K211), Temperature Controller,	Fuel Control, Ignition and Master Fuel Valve Solenoid Pur Overdraw -				

Table: AS Electrical (Cont'd)

RFFERENCES (TM 55-1520-227) (SH 21)	65				2-71 & 4-25	pp 2-71 & 4-25 p 16-143 p F-119	2-71 & 4-25 16-143 F-119	2-71 & 4-25 16-143 F-119	pp 2-71 & 4-25 p 16-143 p F-119 pp 2-56, 59 & 4-12 p 14-4 p F-115 p 14-4 p F-115
PEFER CTM STEE	-10 -23 -23		_		-10-2, pp	-10-2, pp : -23-4, p It	-10-2, pp -23-4, p li -23-5, p F	-10-2, pp -23-4, p II	-10-2, pp 2-71 8 -23-4, p 16-143 -23-5, p F-119 -10-2, pp 2-56, -10-2, pp 2-56, -23-4, p 14-4 -23-5, p F-115
PARAMETER CONDITION TYPE - DUR									
CONDITION	57.5 amps to swivel lock mani- fold from the 28 VDC Primary Bus when AFT WHEELS switch position is changed	>7.5 amps to power steering system. Same power source.		>5 amps to components from the 28	>5 amps to compo- nents from the 28 VDC Secondary Bus	>5 amps to components from the 28 VDC Secondary Bus VDC secondary Bus Secondary Secondary Bus Secondary Secondary Bus Secondary Secondary Bus Secondary	>5 amps to components from the 28 VDC Secondary Bus VDC secondary Bus >5 amps to L405 from the 28 VDC Emergency Bus	>5 amps to components from the 28 VDC Secondary Bus YDC Secondary Bus 55 amps to L405 from the 28 VDC Emergency Bus 55 amps to L203 from the 28 VDC Secondary Bus	>5 amps to components from the 28 VDC Secondary Bus from the 28 VDC Emergency Bus from the 28 VDC Secondary Bus Secondary Bus Secondary Bus Secondary Bus Same power source.
UPERATING MODE		Power Steering ON				A11	A11	All Hoist Centrol SW at	All Hoist Control SW at IN or
NO I				_	·	Amps	Amps	Атря	Атр S
I JARKINGS	7.5					, to	ıo.	v	vo.
RANGE I		ļ			_				
TYPE	Tripped Crct Brkr (C8 185)			Tripped Crct Brkr (CB 180)	Tripped Crct Brkr (CB 180)	Tripped Crct Brkr (CB 180) Tripped Crct Brkr (CB 182)	Tripped Crct Brkr (CB 180) Tripped Crct Brkr (CB 182)	Tripped Crct Brkr (CB 180) Tripped Crct Brkr (CB 182) Tripped	Tripped Crct Brr (CB 180) Tripped Crct Brr (CB 182) Tripped Crct Brr (CB 182) (CB 183)
PARAMETER NAME-	Right Aft Lndng Gear Swivel Lock, Power Steering Con- trol Valve, Actuator and Control Box	AFT WHEEL		Cargo Hook Control Relay (K407) and Release Valve Solenoid (L403) Pur Overdraw -	Cargo Hook Control Relay (K407) and Release Valve Solenoid (L403) Pur Overdraw - CARGO HOOK CONT	Cargo Hook Control Relay (K407) and Release Valve Solenoid (L403) Pur Overdraw - CARGO HOOK CONT CARGO HOOK CA	Cargo Hook Control Relay (K407) and Release Valve Solenoid (L403) Pur Overdraw - CARGO HOOK CONT Cargo Hook Emergency Release Valve Solenoid (L405) Power Overdraw - CARGO HOOK	Cargo Hook (K407) and Release Valve Solenoid (L403) Pur Overdraw - CARGO HOOK CONT Cargo Hook Emergency Release Valve Solenoid (L405) Power Overdraw - CARGO HOOK EMER HINCH Hydraulic Control Valve (L201), Brake Release Solen-	Cargo Hook Control Relay (K407) and Release Valve Solenoid (L403) Pur Overdraw - Cargo Hook CONT Cargo Hook Emergency Release Valve Solenoid (L405) Power Overdraw - CARGO HOOK EMER Minch Hydraulic Control Valve (L201), Brake (L201), Brake Release Solen- oid (L203) & Hoist Control Pur Overdraw - Hoist Control Pur Overdraw -

Sheet No.: 16

NOTE # (SH 21) -10-2, pp 2-55/56, 59 & 63 -23-3, p 9-73 -23-5, p F-105 -10-2, pp 2-56, 59 & 61/62 -23-3, pp 9-67/68 -23-5, p F-103 -10-2, pp 2-53, 55 & 62 (TM 55-1520-227) -23-3, pp 9-83/84 -23-5, p F-102 CONDITION TYPE - DURATION PARAMETER >5 amps to rotation motor and applica-ble relay from the 28 VDC Secondary Bus >5 amps to ext/ret motor & retract relay (plus rota-tion motor & right relay if light is being fully retracted). >5 amps to ext/ret motor and extend relay. Same power >5 amps to system from the 115 VAC Primary Bus >5 amps to each light through the respective brkr, from the 28 VDC Secondary Bus >5amps to system from the 28 VDC Secondary Bus CONDITION source. OPERATING MODE sw or overhead panel control sw at RETR light control swat LorR light control light control Search-Search-Search-<u>=</u> Sw at EXTEND UNITS Amps MARKINGS INDICATOR RANGE Tripped Crct Brkrs (CB 142 & CB 144) Tripped Crct Brkrs (CB 152 & CB 154) Tripped Crct Brkr (CB 140) Tripped Crct Brkr (CB 1053) TYPE Pilot & Copilot Searchlgt Ctrl Motors & Relays Pur Overdraw -ANTI COLL LTS TOP (BOTTOM) SLT CONT PILOT (CO PILOT) PARAVETER NAVE-INDICATOR LABEL Anti-Collision Lights Power Overdraw -Formation Lgts and Control Pwr Overdraw -Position Lgts Pur Overdraw -FORM LTS POS LTS

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Table: A5 Electrical (Cont'd)

7 3108	(SH 21)	59	oij	e5	oď.
OUGH	(TM 55-1520-227)	-10-2, pp 2-55/56, 59 -23-3, p 9-73 -23-5, p F-105	-10-2, pp 2-56, 59 & 63 -23-3, p 9-63 -23-5, p F-101	-10-2, pp 2-56, 59 & 63/64 -23-3, p 9-63 -23-5, p F-95/97	-15-2, pp 2-56, 59 & -23-3, p 9-62 -23-5, p F-98
PARAMETER	CONDITION TYPE - DURATION				
	CONDITION	>25 amps to re- spective filament from the 28 VDC Secondary Bus	>5 amps to system from the 28 VDC Primary Bus	b5 amps to light- ing system from the 28 VDC Pri- mary Bus, through the respective breaker (except for the turn & slip and cruise guide indicators during an AC or DC Primary Bus fail- ure. In that case the instruments receive power from the Secondary Cockpit Lights circuit breaker CB 162).	>5 amps to system form the 28 VDC Primary Bus
ODEDATING	MODE			[F	
	UNITS			Amps	
70 %	MARK I NGS	25		ιń	
INDICATOR	RANGE				
	TYPE	Tripped Crct Brkrs (CB 148 & CB 150)	Tripped Crct Brkr (CB 138)	Tripped Crct Brkrs (CB 160, CB 134 & CB 136)	Tripped Crct Brkr (CB 173)
PADAMETER NAME.	INDICATOR LABEL	Pilot & Copilot Searchlight Lamp Power Overdraw - SL FIL PLT (COPLT)	Overhead Switch and Crct Brkr Panels and Dimming Rheostats Pur Overdraw—	Pilot & Copilot Instrument Lights, Center Section and Dimmer Rheostats Pwr Overdraw - INSTRUMENT LTS PILOT (COPILOT	Console Lights and Dimmer Rheostat Pwr Overdraw - CONSOLE LTS

Sneet No.: 18

NOTE # (SH 21) -23-3, p 9-60 -23-4, p 17-2 -23-5, pp F-109 & 113 -10-2, pp 2-56, 59 & 64 -10-2, pp 2-54, 58 & 67 REFERENCES (TM 55-1520-227) -10-2, pp 2-56, 59 64 -10-2, pp 2-54, 58 66 -10-2, pp 2-54, 58 67 -23-3, pp 9-57/59 -23-5, p F-107 -23-3, pp 9-65/66 -23-5, p F-104 -23-3, p 9-56 -23-5, p F-106 -23-3, p 9-64 -23-5, p F-112 CONDITION TYPE - DURATION PARAMETER >5 amps to oper-ating systems from the 28 VDC Battery Bus >10 amps to systems except white lights & K203 from the 28 VDC Battery Bus >5 amps to all lgt systems (except the turm & slip and cruise guide indicator lights) from the 29 VDC >5 amps to oper-ating lights from the 28 VDC Battery Bus >5 amps to all light systems. Same power source. >10 amps to systems except red lights, K201 and K300. Same power CONDITION Battery Bus source. OPERATING MODE Cabin & Ramp Lts Sw at Cabin & Ramp Lts Sw at AC or DC Primary Bus off line AC & DC Primary Busses on line A] Ę Red Amps UNITS MARKINGS 2 2 INDICATOR RANGE Tripped Crct Brkr (CB 158) Tripped Crct Brkr (CB 162) Tripped Crct Brkr (CB 156) Tripped Crct Brkr (CB 146) Tripped Crct Brkr (CB 164) TYPE Rheostats, Turn and Slip and Cruise Guide Indicator Lgts Pur Overdraw -Lights & Relays (K201 & K203), Jump Light Dimming Relay ening Relay (Emergency Exit Lights Charge Pur Overdraw -Oil Level Check Lights Power Overdraw -SECONDARY CKPT LTS Cabin Dome and Utility Lights and Dimmer Rheostats Power Engine Nacelle Work Lights Pur Overdraw --Secondary Cockpit Lights and Dimmer PARAMETER NAME-INDICATOR LABEL Cabin and Ramp COCKPIT LTS ENG NAC LTS OIL CHE LTS CABIN LTS Overdraw -

Table: A5 Electrical (Cont'd)

	(SH 21)			<u> </u>	16			
_	(IM 55-1520-227)	-10-2, pp 2-18, 56 &	-23-3, pp 9-60/62 -23-5, p F-165		-10-2, pp 2-16/18, 56 -23-4, p 12-14 -23-5, pp F-157 & 163		-10-2, pp 2-16, 53 & 56 -23-4, p 12-8 -23-5, pp F-156/157	_
PARAMETER	CONDITION TYPE - DURATION					,		
	CONDITION	>5 amps to lights from the 28 VDC Battery Bus	>5 amps to bells from the 28 VDC Battery Bus	>10 amps to relay and all activated valves from the 28 VBC Primary Bus	>5 amps to the activated valve, through the FIRE EXI circuit brkr (CB 1000)		>5 amps to respec- tive system from the 115 VAC Primary Bus	
- January Control	OPERALING MODE		<u> </u>		A11			
	UNITS				Атрѕ			
08	MARKINGS	ro		10	က		G	
INDICATOR	RANGE							
	TYPE	Tripped Crct Brkr (CB 1004)	Tripped Crct Brkr (CB 1002)	Tripped Crct Brkr (CB 1000)	Tripped Crct Brkrs (CB 706 & CB 702)	Tripped Crct Brkrs (CB 704 & CB 700)	Tripped Crct Brkrs (CB 1008 & CB 1006)	
Steam of The Steam of	INDICATOR LABEL	Troop Jump Lgts Pur Overdraw - TROOP ALARM JUMP LTS	Troop Jump Alarm Bells Power Overdraw - TROOP ALARM	Fire Extinguisher Control Relay (K127) & Fire Bottle Valves Supply Pur Overdram -	Fire Bottle #1 (2) Individual Valve Power Overdraw - BOTTLE NO. 1 FND (AFT) VALVE	BOTTLE NO. 2 FIND (AFT) VALVE	Engine #1 (2) Fire Detection System Control Unit, Sensing Element and T Mandle Lgts Pur Overdraw	FIRE DET FMG

Table: AS Electrical (Cont'd)

	<u>.</u>							
	(SH 21)					11		
	(TM 55-1520-227)	-10-2, pp 2-10, 52 & 55 -23-1, p 2-188 -23-5, p F-132			-10-2, pp 2-56, 58, 60	-23-4, pp 15-1/2 & F0-42 -23-5, pp F-123/125		
	- DURATION							
PARAMETER	CONDITION TYPE - DURATION							
_	CONDITION	77.5 amps to the respective absorber from the 115 VAC Primary Bus	>10 amps to the press to test warn. lgts (norm. put) from the 28 VDC Battery Bus	>10 amps to systems above & No. 1 Flgt Cntrl Valve Solen- oid. Same power source. (See note.)	>10 amps to OVSP & HIGH EXH TEMP warn. 1gts & LOW OIL PRESS warn. 1gt if lit (norm. out) Same power source.	>10 amps to relays K3, K4, K5, the Main Fuel Valve & Apu Fuel Valve solenoids, the APU Fuel Boost Pump & the APU Hour Meter. Same power source.	>10 amps to all components except the warm. gts (assumed off), main fuel valve solenoid & the igniter.	>10 amps to all components except the warn. Igts (assumed off) & relay Kl. Same power source.
COCOATING	MODE		APU SW at STOP, GND APU- AGB SW at NORM	APU sw at STOP, GND APU- AGB sw at START	APU Sw at APU, APU not running	APU sw at APU, APU running	APU SW at START, APU <90%, Fuel pres- sure <110 psi	APU SW at START, APU <90%, Fuel pres- sure
	UNITS							
T0R	MARKINGS	7.5				01		
INDICAT	RANGE							
	TYPE	Tripped Crct Brkrs (CB 1083, CB 1085 & CB 1081)				Tripped Crct Brk (CB 186)		
DADANCTED NAME	INDICATOR LABEL	Self Tuning Dynamic Absorber System Pur Overdraw - VIBRATION ABSORBERS LEFT (CTR & RIGHT)		APU Relays KI- K6, No. 1 & 2 Flight Control	APU Fuel Boost Pump, APU Start Valve Solenoid, APU Start Fuel Valve Solenoid, APU Marin Fuel Valve Solenoid,	ADU Fuel Valve Solenoid, APU Notor Valve Solenoid, APU Igniter, APU Marning Lights and APU Hour	NAV	

OTES:

- Sensors are step down current transformers, contained in the respective generator control panel (ASI/& 514 note that throughout this table, a 11452249 series control panel is assumed in use). The overvoltage time delay decreases linearly with increased output voltage (0.115 seconds for 180 vac). Normal voltage phase to ground is 120 vac (regulated to 115 vac) and phase to phase is 208 vac (regulated to 200 vac). The under frequency protection circuit reconnects the generator to the load if the output frequency rises back above 360 Hz. The undervoltage protection circuit reconnects the generator to the load if the 3 phase average voltage climbs to 104 vac, unless a lackout has been amplied by the underfrequency circuit. The feeder protection senses current differences between the phase feeder and ground return lines.
- 6 units the loadmeters are fractional loads, where 1.0 is 100% of the generator continuous load rating. The cautionary conditions were deduced on the basis that the continuous load should not exceed 100% of the rated load with the generator on line. If the generator is off line, the only load possible Sensors are transformer (1213 & 1215) which electromagnetically couple the loadmeters to the E phase power leads of generators #1 and #2. should be B phase sensing at the generator control panel.
- Sensor is a Phase Sequence Network which checks the external power for proper phase sequence and activates relay K113 which delivers power (through contacts of relays K109 & K111) to the Gen. No. 1 Ext Pwr Relay (K101). K101 then connects the external power to the AC Primary Bus, and through a separate set of contacts, grounds the caution panel sensing lead which lights the light. m
- Sensors are low impedance shunts which produce a voltage sensed and displayed by the millivoltmeter type indicators. Loadmeter units are fractional loads like the AC loadmeters, where 1.0 load is 200 amperes (full rated load) and 300 amperes is a 1.5 load.
- Sensors are REV CUR CO. Relays K128 and K126 respectively, which trip the corresponding XFMR-RECT FAILURE Relays (K118 & K120). These relays have contacts which ground the caution panel sensing lead which actuates the proper light. ŝ
- Sensor is a blocking diode (CR 100, TM 47) which, for external voltage of the correct polarity, provides a current path for the coils of Relay (K122). A pair of contacts for this relay closes a path to ground for the caution panel sensing lead wkich operates the light. ۍ
- There are two circuit breakers for each of the three inter-bus feeder lines. Hence CB 1031 and C199 protect the same line and so forth for the other two lines and four breakers. The A PH FDR breakers are on the overhead breaker panel.
- 8. Arrangement similar to that described in Note 7 above.
- 9. Power is supplied to the brake when the trigger switch is not engaged.
- 10. A caution on page 2-21 of the Operator's Manual notes that these circuit breakers must be in, otherwise the anti-ice will be on, degrading engine performance.
- Σ Note that these breakers are not shown on the typical overhead breaker panel illustrations of p 2-56 (Operator's Manual) and pages 9-93/95 of :
- The boost pumps are AC powered, via relays which are actuated by fuel boost pump switches in the overhead fuel panel. These switches route 28 power to the relays. Specific signal routing is shown in the -23-5 reference figures. The indicator lights are not in the cockpit. 12.
- 13. The valves are electrically actuated by the No. 1 (2) Engine Emergency T-Handle switches, S140 & S187. The indicator lights are not in the cockpit.
- 14. Power is routed to the amplifiers via the SAS Emergency Release Switch.
- 15. Power is supplied to the actuators/brake when the release button is engaged.
- 16. These circuit breakers are on a box located at station 534, on the overhead structure.
- 17. Since the position of the GND APU-AGB switch is not included in all of the operating modes listed, it should be noted that anytime the switch is in the start position, the additional load of the No. I Flight Control Valve solenoid is applied through the circust breaker.

SUBSYSTEM PARAMETER DATA LIST

Table: A6

HEL ICOPTER: CH-47C

SUBSYSTEM: Miscellaneous	ameous							Shee	Sheet No.: 1
Total different		INDICATOR	TOR		781180	۵.	PARAMETER		- ·
INDICATOR LABEL	TYPE	RANGE	PTRKINGS	UNITS	OPEKALING MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-227)	(SH 3)
Longitudinal					0 60 7146	095	Normal - continuous	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
Actuator	Circular	031.0		710	0-0	09<	Cautionary - unspecified	-10-4, pp 2-30, 3-1/ a 9-14	-
Total Car	01415 (2)	001-0	1	2	60-120	095	Cautionary - unspecified	-23-4, p 11-230	-
ACT-FWD (AFT)					note)	09<	Normal - continuous	-63-5, p F-41	
SAS Amplifier Power Interruption or Disengagement -	Caution		Ambos s		1	1. AC or DC power failure to amplifiers 2. <2000 psi hydraulic pressure to the No. 1 or No. 2 hydraulic sysrespectively	Cautionary - unspecified	-10-2, pp 2-36, 56,	۰
NO. 1 (2) SAS OFF	(2) 6361	1				DC power inter- rupted by EMER SAS REL switch	Advisory – unspecified	-23-3, pp 9-98/99 & F0-14 -23-5, pp F-45 & 49	
						1. SAS sw moved to different positions 2. HYD BST sw moved to dif- ferent positions	Normal - transient		
					Heater on	2177 (see note)			
Heater Output Temperature - HEATER HOT	Caution Lgt	ŀ	Атрег	ပ္	Hezter off due to shutdown	1. >177 & heating Sw at HEATER ON, or cal 7 & HEATER START button not pushed or heat-fing sw at HEATER ON	Cautionary - unspecified	-10-2, pp 2-49 & 71 -23-4, pp 13-1 & 7 -23-5, p F-77	м

Table: A6 (Miscellaneous - Cont'd)

	-								7
PARAMETER NAME-		INDICATOR	TOR		ODEDATING		PARAMETER		
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	REFERENCES (TM 55-1520-227)	NOTE # (SH 2)
Right Aft Steerable Landing Gear Swivel Angle -	Caution Lat	;	Amber	50	Lft turn (clock- wise swivel)	262.5	1	-10-2, pp 2-7 & 70	
WHEEL DEPHASED	—↓			, ,	Rt turn (ccw swivel)	₹	Cautionary - unspecified	-23-3, pp 7-253/254 & F0-19 F0-15, p F-128	4
Parking Brake Valve Plunder					Air- craft on ground, no taxi	Plunger position	Advisory - unspecified	-10-2, pp 2-7/9 & /0	
Position - PARK BRAKE ON	Caution Lgt	;	Amber	:	Air- craft ground taxiing or in flight	trap fluid for trap fluid for parking brake actuation	Cautionary - unspecified	-23-5, pp 7-268 & 277	ហ
Cargo Hock Position - CARGO HOCK OPEN	Caution Lgt	:	Amber	:	All	Cargo hook is in OPEN position	Cautionary - unspecified	-10-2, pp 2-71 & 4-21/25 4-21/25 -23-4, pp 16-142/144 -23-5, p f-119	9

able: A6 (Miscellaneous - Cont'd)

MOTES:

- 1. Sensors are (most likely) variable resistors which are built into both the forward pylon actuator and aft pylon actuator. The wiper of the resistor is mechanically driven by the actuator's dc servo motor and the resistor is electrically connected to the speed trim amplifier which in turn supplies the drive signal for the indicators. For operations at airspeeds above 60 KTS with the indicator showing 0-60 KTS, the maximum allowable airspeed is obtained from Figure 5-11, p 5-17 of the Operator's Manual.
- Sensors are the No. 1 and No. 2 SAS amplifiers themselves, sensing vac, and No. 1 and No. 2 hydraulic system pressures. The activation of the capsule segments is accomplished by applying a ground to the appropriate line running to the caution panel. In addition the EMER SAS REL switch applies a ground to both of these lines when in the RELEASE position. Power to the capsule segments is most likely supplied by the DC Primary Bus through the CAUTION LTS circuit breaker on the overhead panel. Airspeed limit with one SAS on line is V_{ne} or 120 KTS (if lower). Airpseed limits with both SAS off line below 120 KTS is V_{ne}, if V_{ne} <u>(120 KTS</u>.
- Sensor is a thermoswitch (A209) which opens at 177°C removing power from relay K209 which shuts down the fuel control and ignition circuits completing the grounding circuit for the caution light. The requirements for lighting the light are that K209 be deenergized and relay K205 energized, which is accomplished by leaving the heating switch in the HEATER ON position. ÷
- are explained Sensor is a cam actuated microswitch which simultaneously disables the power steering while turning on the caution light. The limits used are ex on the referenced page 7-253 and differ from those given in the Operator's Manual, these latter, being mean angular swivel values for the power steering tolerance zones. The disabling limits which are used in this A6 table are the wheel "out-of-zone" buffer zone extreme limits.
- Sensor is most likely a position sensitive switch, linked to the parking brake valve pressure actuated plunger. Thus the switch may be indirectly referred to as pressure sensitive, although it is unclear whether loss of brake pressure would release the plunger and result in a state change of the switch and parking brake lever. Caution light activation is through grounding of the caution panel sensing lead. ŝ
- Sensors are two position sensing switches. Switch \$403 senses the hook rotating cam position, as operated by the manual emergency release. Switch \$405 senses the hook actuating cylinder position, as operated by the normal hydraulic or emergency air release modes. Either switch provides a grounding path for the caution panel sensing lead. ė

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SUBSYSTEM PARAMETER DATA LIST

Table: A7

HEL 1COPTER: CH-47C

SUBSYSTEM: Auxiliary Power Unit (APU: 1-621-2A Type)

SUBSYSTEM: Auxiliary Power Unit (APU: 1-621	ary Power Unit	t (APU: T-62T	r-2A Type)					She	Sheet No.: 1
DADAMETED NAME		INDICATOR	70R		000000	~	PARAMETER		_
INDICATOR LABEL	TYPE	RANGE	MARKINGS UNITS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	REFERENCES (TM 55-1520-227)	NOTE #
					APU SW at START	06	Maximum (release APU switch) - transient		
Turbine Speed -						90-98	Cautionary - transient		
APU TACHOMETER	Circular Dial	0-110	!	*	APU SW	98-106	Normal - continuous (5 to 15 seconds after start initiated)		
					2	106-110	Cautionary - transient		
						2110	Maximum - transient	-10-2, pp 2-60/61, 5-1, 8-5/6.1	
ds AD	Warning Lgt (Press to Test)	:	Red	9-6	APU is	2110	Maximum (overspeed) - unspecified (see note)	-23-4, pp 15-1/3, 13 & F0-42 -23-5, p F-123/125	2
Exhaust Gas Temperature - HIGH EXH TEMP	Marning Lgt (Press to Test)	:	Red	ပ္	APU is	2(577-582)	Maximum (overtemp) - unspecified		۴
Low 011 Pressure - LOW 0IL PRESS	Warning Lgt (Press to Test)	;	Red	psi	APU 1s on	₹(5-7)	Minimum - unspecified		4
					-				

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Sheet No.: 2

Table: A7 (APU - Cont'd)

NUTES:

1. Sensor is a tachometer generator, mounted on and driven by the APU speed switch. The 3 phase AC output voltage is proportional to the APU turbine speed. The APU speed should stabilize in the 98-106% range 5-15 seconds after start is initiated.

2. Sensor is an overspeed switch which deenergizes the overspeed switch relay (K5), thereby simultaneously turning on the light and removing power from the APU and the APU and the APU for overspeed duration is unspecified, since shutdom commences simultaneously with the warning light activation. However, should the light activate and the APU not shut down, the 5 second overspeed limit should be observed and the APU should be shut down manually. The light will also illuminate when the APU is shut down and the APU position.

Sensor is a thermoswitch which deenergizes the high exhaust gas temperature relay (K4) thereby simultaneously turning on the light and shutting down the APU as described in Note 2 above. The first page reference says the switching 'hreshold is 882' \pm 6°C for a 162-7-2Al type APU, but the page 18-1 reference lists two thresholds: the one which is used on sheet 1 of this table plus a 560° -577°C range for an unspecified type of APU. The light is also on when the APU is not running and the switch is in the APU position.

Sensor is a pressure switch which deenergizes the low oil pressure relay (K3) thereby simultaneously turning on the light and shutting down the APU in the manner described in Note 2 above. The light does not come on if the APU is shut down and the switch is in the APU position.

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GENERAL ELECTRIC CO SINGHANTON N Y AIRCRAFT EQUIPMENT DIV F/G 1/3 ELECTRONIC MASTER MONITOR AND ADVISORY DISPLAY SYSTEM. OPERATIO--ETC(U) AD-A105 516 OCT 80 ACS-12-217 DAAK80-79-C-0270 USAAVRADCOM-TR-79-0270-2 NL UNCLASSIFIED NL 2 or 3

SUBSYSTEM PARAMETER DATA LIST FOR THE

UH-60A

SUBSYSTEM PARAMETER DATA LIST

Sheet No.: 1 Table: B1

HELICOPTER: UM-60A

SUBSYSTEM: Engine

NOTE (SH 4) -10, p 2-57 -23-2, pp 6-69; 6-78 & 13-3 -23-3, pp 46-5, 24, 25 & 31 -2 -23-2, pp 6-69, 12-5 14-1 -23-3, pp 46-24/25 -10, pp 5-4 -23-2, pp 3-16, 6-68 13-1 -10, pp 2-32, 5-2 8 5-6 REFERENCES (TM 55-1520-237) Minimum - none except transients and idle (how-ever, operation in 25-40% and 60-75% range is pro-hibited). CONDITION TYPE - DURATION Cautionary - 30 mimutes Cautionary - 30 minutes Cautionary - transient Maximum - 12 seconds Normal - continuous Normal - continuous Warning - transient (12 sec) Warning - transient (12 sec) Normal - continuous Sec Maximum - 12 PARAMETER CONDITION 101-105 105-107 96-101 98-102 91-96 102-105 52-98 52-55 107 105 5 OPERATING MODE Eng Cond Lever in IDLE, Eng Started Eng Cond Lever in FLY, Eng Started All MARKINGS UNITS * (91-96)A (91-96)A (96-101)G (101-105)A (105-130)R (0-98)G (98-102)A (102-110)R 2 INDICATOR RANGE 0-130 0-110 Segmented Vertical Light Bar (Part of Engine/ Rotor Tachometer) Master Warning Lights (2) Segmented Vertical Light Bar w/Digital Readout TYPE Ng SPEED 1 (2) PARAMETER NAME-INDICATOR LABEL Engine Gas Producer Speed Engine Power Turbine Speed 1 RPH 1 (2) \$1(\$2) ENG

-10, p 5-3 -23-2, pp 3-13, 6-68, 12-1 & 13-1

- 30 minutes

Cautionary

775-850

0-775

850-886

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(0-775)G (775-850)A (850-950)R

0-950

Segmented Vertical Light Bar w/Digital Readout

Engine Turbine Gas Temperature

TGT TEMP 1 (2)

Maximum - 12 seconds Marning - Transient (12 sec)

886

Normal - continuous

Warning (possible flame out) - continuous

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Steady Tone in ICS

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Sheet No.: 2

(able: Bl (Engine - Cont'd)

NOTE # (SH 4) S 9 œ -10, pp 2-60, 2-62 -23-2, pp 3-15, 3-18, 6-69, 6-75/76 & 13-3 -23-3, pp 11-10 & -10, pp 2-24 & 5-4 -23-2, pp 3-15/17, 12-1/4 & 13-1 -23-3, pp 11-9, 12-9 & 46-24/25 -10, pp 2-25, 5-2, 5-6, 7-4/9 -2-2, pp 3-16, 6-69, 12-5 & 14-1 -10, pp 2-24 & 5-4 -23-2, pp 3-13, 6-68 13-1 REFERENCES (TM 55-1520-237) CONDITION TYPE - DURATION Marning - transient (10 sec limit but single eng. xmsn limit is 111%) Cautionary - transient (101% - dual engine xmsn limit) Cautionary - unspecified (see above) Cautionary - 30 minutes Maximum - 10 seconds Maximum - 10 seconds Maximum - continuous Maximum - 30 minutes Normal - continuous Warning - transient (10 sec) Normal - continuous Normal - continuous Minimum - see below Normal (Ng > 85%) continuous Idle (Ng < 85%) continuous PARAMETER CONDITION 100-110 110-135 110-135 -40 - 135135-150 0-100 0-110 25-45 45-100 135 135 150 >150 100 52 OPERATING MODE Dual Engine Single Engine = A1. ٦ UNITS ပ ပ္စ psi MARK I NGS (0-100)G (100-110)A (110-150)R (-40-135)G (135-150)A (150-180)R (10-25)R (25-45)A (45-100)G (100-130)R Amber INDICATOR RANGE -40-180 0-150 10-130 Segmented Vertical Light Bar W/Digital Readout Segmented Vertical Light Bar Caution Lights (2) Segmented Vertical Light Bar TYPE ENG OIL Temp 1 (2) \$ TORQUE 1 (2) Engine Torque -PARAMETER NAME-INDICATOR LABEL ENG OIL PRESS 1 (2) #1(2) ENGINE OIL TEMP Engine Oil Temperature -Engine Oil Pressure -

Sheet No.: 3

Table: B1 (Engine - Cont'd)

1 1 1

MOTE:	(SH 4)	6	10	=	12		13	14
OUTOTIO	(TM 55-1520-237)	-10, pp 2-21, 2-24, 2-60/62 -23-2, pp 3-15 & 18, 6-69, 6-75 & 13-1 -23-3, pp 46-24/25	-10, pp 2-22, 2-60 & 62 62 -23-2, pp 3-18 & 6-75/76	-10, pp 2-21 & 2-61 -23-2, pp 3-18 & 6-75/76 -23-3, pp 11-11/12, R 5R-9		-10, pp 2-21 & 63 -23-2, pp 3-18/19 &	-23-3, pp.17-1/8 & 58-7/9	-10, pp 2-22, 60, 62 & 8-8/9 -23-2, pp 3-8/12 & 6-75/76 -23-3, pp 16-1/14 & 58-6/7
PARAMETER	CONDITION TYPE - DURATION	Cautionary - none allowed	Cautionary - unspecified	Cautionary (engine oil about to bypass filter) - unspecified	'Advisory - unspecified	Advisory - continuous	Advisory – unspecified	Advisory - 30 seconds (see note) Caution - unspecified
	CONDITION	425	Sensor contacts grounded by metal particles from engine gearing	ioil pressure dif- ference between filter inlet and outlet is 60 to 89	-Valve is open		Inlet temperature is above 200°F	Valve is open
0000	MODE	All	All	A11	Ng > (86- 87%) & Eng Anti- Ice sw on	Ng ≤(86- 87%)	A11	Eng Strt, Ng < (52-55%) Other than Eng. Start
	UNITS	psí	1	ps.			ပ္စ	!
8 0.	MARKINGS	Amber	Amber	Amber	Green		Green	Amber
INDICATOR	RANGE							
	TYPE	Caution Lights (2)	Caution Lights (2)	Caution Lights (2)	Advisory Lgts (2)		Advisory Lgts (2)	Caution Lgts (2)
DADANCTTO MANC	INDICATOR LABEL	Engine 011 Pressure #1 (2) ENGINE OIL PRESS	Engine Power- train/Gearbox Integrity - CHIP #1 (2)	Engine 011 Filter In/Out Differential Pressure - #1 (2) 071 FLTR BYPASS		#1 (2) ENG ANTI-ICE ON	EMGINE INLET TEMPERATURE - #1 (2) ENG INLET ANTI-ICE ON	Engine Start Control Valve Position - #1 (2) ENGINE STARTER

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Table: B1 (Engine - Cont'd)

Sensor is a tachometer type whose variable frequency output is converted to a d.c. voltage by the SDC (Signal Data Converter) Interface No. 2 module.

Same type of sensor as note 1 above, with conversion via the SDC Interface No. 1 module.

The signal is derived from the Ng speed sensor described above, via the SDC, The SDC provides signals to the voltage regulator card of the CDU (Central Display Unit) which then outputs the signals which actuate the warning lamps. The signals are routed back through the SDC connectors (but are not conditioned by the SDC) and then directly to the capsules in the pilot's and copilot's master warning panel and to the LH relay panel for routing

Seven alume]-chrome] thermocouple probes provide direct temperature sensing. Their outputs are averaged and routed to the SDC which first for ambient temperature changes and then conditions the signal at the SDC Interface No. 4 module before routing to the CDU for display.

The sensor is of an unspecified type which provides a signal, proportional to the amount of twist on the power turbine shaft, to the SDC Interface No.

A variable resistance type sensor is used, the output of which is transformed into a d.c. voltage by the Interface No. 2 module of the

Using the same sensor signals as above, the signal to the caution panel is produced by the CDU Voltage Regulator and routed to caution/advisory channel cards Al and A2, via the SDC connectors (although the SDC does not operate on the signal). 7. Using the same

Sensor output is 400 Hz ac voltage which is routed to the SDC Interface No. 4 module. It is combined there with a 10 vac 400 Hz refe logic power supply) to produce a d.c. voltage proportional to the engine oil pressure, which is then routed to the CDU for display. ø

The sensor is the same as for the note above, However, when this signal reaches the CDU it is routed to the Voltage Regulator (as well as to the resulting from that comparison is then routed to caution/advisory panel cards Al and A2, via the SDC connectors (although the SDC does not operate or the signal).

Sensors are contacts, one of which is connected to ground and the other is wired to caution/advisory panel card A3. The contacts are bridged by metal chips and the ground sensing (with subsequent capsule illumination) is performed inside the panel, presumably by the card. 50.

Sensors are pressure switches connected to caution/advisory panel cards Al and A2.

Sensors are switches which are either on or off depending on the valve position. Routing of the #1 (2) signals is through caution/advisory panel cards 12.

Sensors are temperature senstive switches wired to caution/advisory channel card A3. Although there is no duration specified in the manuals listed, additional checking should be done to confirm no limitation is imposed due to a high 0.A.T. 13.

Sensors are switches which detect start control value position. Wiring for #1 (2) switch is through caution/advisory panel channel card A1 (A2).

SUBSYSTEM PARAMETER DATA LIST

Table: 82

HELICOPTER: UM-60A

SUBSYSTEM: Fuel

NOTE # (SH 2) Sheet No.: 1 7 ო S 7 9 -10 pp 2-26, 5-5 & 8-7 -23-2 pp 3-20/26, 6-68, 12-1 & 4, 13-1, 5 & 6 -23-3 pp 23-3&8 -23-2, pp 3-16, 6-75/ 76 & 15-1/3 -23-3, pp 11-11/12, 58-5/7 -23-3, pp 11-10, 12-10, & 58-6/7 -23-2, pp 3-27, 6-75/ 76 & 15-4 -23-3, pp 22-1/6 & 58-4 -23-2, pp 3-16, 6-75/ 76 & 15-1/3 -10, pp 2-26 & 2-63 -23-2, pp 3-20/23 & 15-1 -23-3, pp 21-5/6 & 58-9 -10, pp 2-26, 2-60 & 62 -10, pp 2-25, 2-60 & 62 -10, pp 2-19 & 2-60/ 62 REFERENCES (TM 55-1520-237) -10, pp 2-26/28 & 6-8/9 -23-3, pp 1-9/11 Cautionary - unspecified (However, this gives about 20 minutes flight time at cruise power.) CONDITION TYPE - DURATION Cautionary - unspecified Cautionary - unspecified Cautionary - unspecified Cautionary - unspecified Advisory - unspecified note Normal - Continuous Normal - continuous Cautionary - see PARAMETER Fuel pump switch in either "Fuel Prime" or "APU BOOST" po- Astion & APU T-Handle switch in the normal-closed position (T-handle not pulled) 0-2600 (single tank) or 0-5200 (both tanks) tank) or 0-5200 (both tanks) ≤ 8.5 ± 0.5 0-2600 (single CONDITION 200-1500 <(170-180) ≥ 7.5 <10 per tank OPERATING MODE >400 lbs per main tank <400 lbs
per main
tank</pre> A] E F E A1 **=** 3 UNITS <u>1</u>6 **1**bs ps i psi ; 165 ş (0-200)A (200-1500)G MARK I NGS Amber Amber Green Amber X/A INDICATOR 0-1500 RANGE 0-5200 Digital
W/three
position
selector
switch (No.
1, No. 2 &
Total) Segmented Vertical Light Bar w/Digital Readout Flashing Caution Lgts (2) Caution Lgts (2) Caution Lgts (2) Advisory Lgt Warning Lgts (2) 78 Fuel Qty Front (#1) & Rear (#2) Aux. Tanks -Fuel Qty, Left & Right Tanks -#1(2) FUEL LOW FUEL QTY (1 & 2) Fuel Pump Sw & APU T-Handle Sw Positions -NO. 1 (2) AUX EMPTY PARAMETER NAVE-INDICATOR LABEL #1(2) FUEL FLTR BYPASS PRIME BOOST PUMP ON Differential Pressure -#1(2) FUEL PRESS Pump Output Pressure -**Engine Boost** Engine fuel Filter AUX FUEL QUANTITY

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Table: B2 (Fuel - Cont'd)

MOTES:

- Sensors are capacitance type probes powered by 6 KHz a.c. voltage, through normally closed contacts of the FUEL IND TEST pushbutton switch. The a.c. current probe output is routed to a signal conditioner (where the 6 KHz signal also comes from) which transforms it to a d.c. voltage. This signal is then routed through the SDC (which does not operate on it) to the CDU Interface No. 2 module, along with the analog reset and multiplex signals from the SDC Analog Processor No. 2 module. The signal is then fed to the appropriate indicator. Need clarification of what is actual usable fuel capacity in each tank, since TM 55-1520-237-23-2, para. 3-34 says it's "about 177 gallons (1155 pounds)" and TM 55-1520-237-10 para. 2-73 says it's "about 181
- Sensor is a set of thermistor "beads" at the bottom of each fuel probe. When the beads are no longer wet, the signal applied to the Low Level Warning Conditioner causes the output of that device to go low, which activates the flashing circuit on caution/advisory panel channel card A4. The fuel range threshold given in TM 55-1520-237-10 was 170-190 lbs. while TM 55-1520-237-23-2 said activation occurred at 172 lbs. of fuel. Finally, TM 55-1520-237-23-3 consistently used 170-180 lbs. as the threshold condition. This last reference was used since this would be the range maintenance personnel would refer to. %
- Sensors are pressure switches with outputs wired to caution/advisory panel channel cards Al and A2. Switches are an integral part of the fuel filter ÷

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- Sensors are pressure switches with outputs wired to caution/advisory panel channel cards Al & A2.
- Sensor consists of switch 5102 (which is connected to the APU T-Handle) wired in series with one part of switch 519, the Fuel Pump switch. When these switches are closed, 28 vdc is routed to the advisory light through the control/advisory panel channel card A3. ŝ
- Sensors are similar to those in Note 1 above. The indicator is located on the lower portion of the Range Extension Control Panel. Signal processing is accomplished within this panel. The cautionary condition depends upon a number of variables: actual fuel weight in all four tanks, fuel transfer rate, additional weight in aircraft due to crew, equipment, etc., all of which can vary according to mission type and phase. ė
- Sensors are of the type described in Note 2 above. The indicators are positioned on and the signals are processed within the Range Extension Control 7:

SUBSYSTEM PARAMETER DATA LIST

Sheet No.: 1 Table: B3

HELICOPTER: UH-60A

SUBSYSTEM: Powertrain (Includes Main and Tail Rotor Groups)

_	_	INDICATOR					PARAMETER		
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	REFERENCES (TM 55-1520-237)	NOTE (SH 4)
						16	Minimum - transient and idle only		
					Powered	91-96	Cautionary - transient		
a de	3		R(10-0)		Filght	101-96	Normal - continuous		
A DOE D	Vertical	0-130	(96-101)6	•		122	Maximum - unspecified	0.00	,
	רושני פער		(122-130)R	e		06	Minimum - continuous	-10, p 5-6 -23-2 pp 6-69 & 14-1	
					Power Off	90-110	Normal - continuous		
					rotation)	110-120	Cautionary - transient		
						120	Maximum - transient		
Main Rotor	,					2 127	Maximuum RPM has been		
overspeed -	Discrete		Red	24	A11	2 137	remain on until manually	-23-2, pp 0-68, 13-3 & 14-3	2
KIK UVEKSPEEU	Ligats			1		2 142	reset by maintenance personnel) - unspecified	-23-3, p 46-3	
Main Rotor Speed	Steady tone in ICS		1	•	No weight on wheels		Warning - unspecified	-10, p 2-63	2
LOW ROTOR RPM	Light on Master Wrng Panel		Red	•	All	< 95 (or 96)	(nowever see durations Specified for Main Rotor RPM)	-23-3, p 46-24	m
Main Transmis-	3		(-50 -120)6			-50-120	Normal - continuous	3 - 01	
Temp -	Vertical	-50 -170	(120-140)A	ပ္	A11	120-140	Cautionary - transient	-10, p 5-5 -23-2, pp 6-68 & 13-1	4
XMSN TEMP	1 gar og		(140-170)R			140	Maximum - transient		
MAIN XMSN 01L TEMP	Caution Lgt		Amber	ე,	All	∑ (112-121)	Cautionary - unspecified (see above)	-10, pp 2-36 & 60 -23-2, pp 4-11 & 6-75 -23-3, p 26-8 (note 4)	ď

Sheet No.: 2

Table: B3 (Powertrain - Cont'd)

σ 9 7 œ -10, p 5-5 -23-2, pp 4-14, 6-68 & 13-1/6 -23-3, pp 26-7 & 46-25 -10, pp 2-36 & 61 -23-2, p 6-75 -23-3, p 26-8 (note 5) -10, pp 2-37, 2-60 & 2-62 -23-2, pp 6-75 & 6-77 -23-3, pp 27-7/8 -10, pp 2-36 & 60 -23-2, pp 4-14 & 6-75 -23-3, p 26-8 (note 3) REFERENCES (TM 55-1520-237) CONDITION TYPE - DURATION Cautionary - unspecified (see above) Cautionary - unspecified Cautionary - unspecified Maximum - none allowed Cautionary - transient Cautionary - transient Normal - continuous Maximum - transient Sensor contacts grounded by metal particles from gearbox >(134-146) CONDITION 77 65-130 20-30 30-65 14 130 OPERATING MODE A] F A] F UNITS psi psi ပ (20-20)R (20-30)A (30-65)G (65-130)A (130-190)R MARK I NGS Amber Amber Amber INDICATOR RANGE 0-190 Caution Lgt Caution Lgt Segmented Vertical Light Bar Caution Lgts (7) TYPE Intermediate Tail Rotor Drive Gearbox Oil Temperature -Main Transmis-sion Module Oil Pressure -CHIP INTM XMSN CHIP TAIL XMSN TAIL XMSN 01L TEMP CHIP MAIN MOL SUMP MAIN XMSN 01L PRESS PARAMETER NAME-INDICATOR LABEL INT XMSN OIL TEMP Tail Kotor Gearbox Oil Temperature -CHIP ACCESS MOL - RH CHIP ACCESS CHIP INPUT CHIP INPUT MOL - LH XMSN PRESS Gearbox Integrity -

Table: B3 (Powertrain - Cont'd)

		TANTICATOR	100	-				She	Sheet No.: 3
PARAMETER NAME-	,		5		011.140300		PARAMETER		-
INDICATOR LABEL	TYPE	RANGE	MARKINGS UNITS U	UNITS	MODE MODE	CONDITION	CONDITION TYPE DIRECTOR	REFERENCES	NOTE #
Main Rotor							CONSTITUTE LIFE - DORAL TON	(IM 55-1520-237)	(SH 4)
Gust Lock Engagement -	Caution Lgt		Amber		All	Rotor gust lock on Cautionary - N/A	Cautionary - N/A	-10, p 2-61 -23-2, pp 4-17, 6-75	2
GUST LOCK								-23-3, pp 28-3/4	2
Tail Botor									
Control Cable Integrity -	Caution Lgt		Amber		A11	All Tail rotor cable	Cautionary - N/A	-10, pp 2-39 & 2-60 -23-2, pp 5-16 & 6.75	=
TAIL ROTOR						Droxer Droxer		-23-3, p 30-4	:
TOTOTOTO									

(able: 83 (Powertrain - Cont'd)

Sensor is a tachometer or frequency transducer. Reduce the maximum rpm in autorotations at 0.A.T. below -20°C by 1%/5° reduction in 0.A.T.

2. Same sensor as above but drive signal comes from SDC.

3. Light flashes at 3-5 Hz. The TW 55-1520-237-10 reference indicates the LOW ROTOR RPM light comes on "below about 95%" rotor RPM, but all other references use the 96% figure as a threshold. Hence both numbers are included herein, and further clarification may be needed. Since 96% is at the bottom of the green segment on the % RPM R indicator, it is more likely that that is the correct number.

Variable resistance sensor output converted to d.c. voltage by the CDU Interface #2 module.

The sensor is a temperature switch wired to caution panel card Al. The first reference listed indicates that the caution light goes on when the oil temperature reaches 121°C. The second reference is "over 112° to 121°C". The fourth reference says the light is on "above 113° to 121°C (235° to since that reference is a maintenance trouble shooting manual, but the actual range should be clarified.

Sensor output is a d.c. voltage which is conditioned by the CDU Interface No. 1 module.

The sensor is a pressure sensitive switch wired to caution panel card Al. The first reference listed says that the caution light comes on when a "pressure drop" occurs at 14 ±2 psi. The second reference indicates that the light is on "below about 14 psi", the third reference says it occurs "below 14 psi" and the last two references say "below 14 ±2 psi". Although there is some uncertainty here, the <14 ±2 psi seems to be the most agreed

Sensor is a temperature sensitive switch connected to caution panel card A4. All references indicate the caution light goes on when the gearbox oil temperature is above 140°C, except the last reference, which says the threshold "is above 134°C to 146°C". Since most sensors have a tolerance associated with the switching threshold, this last reference is assumed to be the most realistic of those available.

Sensors are connected to caution panel cards A3 and A4. The last reference shown indicates that the ground sensing circuitry which lights the caution capsules is actually integrated into the caution/advisory panel. The TM 55-1520-237-23-2 reference seems to indicate this circuitry is split between required. Finally, the reference indicates the CHIP MAIN MDL SMP capsules 31, Also, knowledge of the fuzz burn-off circuitry is lacking and may be no explanation is given for why this is so.

Sensor is a microswitch connected to caution panel card Al.

Sensors are two microswitches in the tail rotor quadrant, connected to caution panel card Al.

SUBSYSTEM PARAMETER DATA LIST

Table: 84

HELICOPTER: UH-60A

SUBSYSTEM: Hydraulic	71c							Shee	Sheet No.: 1
PARAMETER NAME.		INDICATOR	'08		OPEDATING		PARAMETER	DECEDENCES	MOTE .
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-237)	(SH 2)
Mydraulic Pump Pressure - #1 (2) HYD	Caution Lgts (2)		Amber	psi	llA	(2000 ±50)	Cautionary - unspecified	-10, pp 2-34/35 & 61 -23-2, pp 5-2/6 -23-3, pp 29-9 & 58-5	-
BACK UP PUMP	Advisory Lgt		Green	psi	AII	> 2350	Advisory - unspecified (but see note)	-10, pp 2-34/35 & 63 -23-2, pp 5-6 & 6-77 -23-3, pp 29-28 & 58-9	2
Primary Servo Pressure (1st & 2nd Stage) -	Caution		Amber	psi	All	(2000 ±50)	Cautionary - unspecified	-10, pp 2-60/62 -23-2, pp 5-2/6 & 6-75/76	т.
#1 (2) PRI SERVO PRESS	Lgts (2)							-23-3, pp 29-30/34	
Tail Rotor Servo Pressure (1st & 2nd Stage) -							1	-10, pp 2-62/63	
#1 TAIL RTR SERVO	caution Lgt		Amber	*1	-	(2000 ±50)	Cautionary - unspecified	-23-2, pp 5-6 & 6-76/77 -23-3, pp 29-30/32 &	4
#2 TAIL RTR SERVO ON	Advisory Lgt		Green	sd -	=	> 2350	Advisory - unspecified	6//-80	5
Yaw & Collective Boost Servo Pressure -	Caution Lgt		Amber	psi	A11	Low pressure -	Cautionary - unspecified	-10, p 2-60	9
BOOST SERVO OFF						see note		-23-2, pp 5-3/6, 5-14 & 5-75	
Hydraulic Fluid Reservoir Low -									,
#1 (2) RSVR LOW	Caution		Amber	¥	All	9*0 >	Cautionary - unspecified	-10, pp 2-61/62 & 69 -23-2, pp 6-76/77	
BACK-UP RSVR LOW	(6) 5167							-23-3, pp 29-30/32 & - 58-51	ω

fable: 84 (Hydraulic - Cont'd)

OTES:

- 1. Sensors are pressure switches attached to the #1 or #2 transfer module and wired to caution/advisory panel channel cards A1 and A2 respectively.
- 2. Sensor is a pressure switch attached to the utility module and wired to caution/advisory panel channel card A3. Although there is no caution given concerning a time limit on operation of the backup pump, IM 55-1520-237-23-3, p 29-1 contains a caution for ground maintenance run time not to exceed 30 minutes. Need to know if this limit applies only to operations with rotors not turning, all ground operations, etc.
- Samsors are pressure switches attached to the lateral, forward and aft servos of the primary servo manifold, stages 1 and 2. The wiring is caution/advisory panel channel cards A1 and A2.
- Sensor is a pressure switch attached to the 1st stage position of the Tail Rotor Servo Cylinder. The signal to operate the light is routed, via the No. I Logic Module in the LM Relay Panel, to caution/advisory panel channel card A2.
- Same sensor type as above but installed on the 2nd stage position of the Tail Rotor Servo Cylinder. The switch output is wired directly to caution/advisory panel channel card A3.
- Sensors seem to be two pressure switches, mounted on the yaw and collective boost servos and wired to caution/advisory panel channel card Al. Sensor pressure threshold is not specified in the available sources. The most likely threshold is < (2000 ±50) psi since that is the pressure threshold for the #2 HVD Pump caution light. Also TM 55-1520-237-23-3 p 65-1 step 7 indicates a pressure of 2000 psi at 2gpm on the yaw boost assembly activates a Boost Press Off light on the Pilot Assist/Nulling Test Box, which may be looking at the yaw boost pressure switch normally connected to the caution
- Sensors are micro switches which detect the position of the pressure piston in pump reservoirs 1 and 2. The signals are routed, through Logic Modules and 2 respectively, to caution/advisory panel channel cards Al and A2. .
- Sensor is a micro switch coupled to the backup pump reservoir pressure piston position. The signal is routed through the No. 2 Logic Module and thence to caution/advisory panel channel card A2. **.**

SUBSYSTEM PARAMETER DATA LIST

HELICOPTER: UM-60A

SUBSYSTEM: Electrical

Table: 85 Sheet No.: 1

•				•			•	-	•
MANE.		INDICA	ICATOR		OPEDATING		PARAMETER	DEFEDENCES	NOTE A
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-237)	(SH 20)
Switability -					No weight on wheels	Volts out <100 ±5 vac, volts out >125 ±1 vac or feeder fault (unbalanced	Cautionary - unspecified	-10, pp 2-45/49 &	•
Z Y	Lgts (2)		Alloer	:	Weight on wheels	Volts out <100 ±5 vac, volts out >125 ±1 vac, freq. out 575 ±5 Hz (1-3 seconds) or Feeder fault (unbalanced load)	Cautionary - unspecified	-23-2, pp 6-10/16 & 6.75/76 -23-3, pp 31-15/20 & 58-5	-
APU Generator Output & Connection Status - APU GEN ON	Advisory Lgt		Green		ILA	100 ±5 <pre></pre> ±1 vac, Freq. out >375 ±5 Hz, no feeder fault, and GENERATORS APU switch ON.	Advisory - unspecified	-10, pp 2-49 & 63 -23-2, pp 6-1/15 & 77 -23-3, pp 31-16/20 & 58-9	2
Generator Main Bearing Mear - #1 (2) GEN BRG	Caution Lgts (2)		Amber	;	All	Sensor ring embed- ded in bearing con- tacts outer face of the auxiliary bearing	Cautionary - unspecified	-10, pp 2-49, 60 & 61 -23-2, pp 6-11 & 6-75/76 -23-3, pp 58-9/10	e e
A.C. Essential Bus Status - AC ESS BUS OFF	Caution Lgt		Amber	:	ILA	Bus disconnected from both No. 1 and No. 2 A.C. Primary Bus	Cautionary - unspecified	-10, pp 2-50/51 & 60 -23-2, pp 6-7, 13, 17 -23-3, pp 31-19 & 58-5	4
External Pur Re- ceptacle Connec- tion Pins - EXT PUR	Advisory Lgt		Green	:	AII	Pins jumpered	Advisory – unspecified	-10, pp 2-49 & 63 -23-2, pp 6-7, 9, 14 & 77 -23-3, pp 31-18/19 &	\$
0.C. Converter Output - #1 (2) CONV	Caution Lgts (2)		Amber	-	AII	No output voltage	Cautionary - unspecified	-10, pp 2-45, 60 & 51 -23-2, pp 6-21/25 & 6-75/76 -23-3, pp 32-14/15 &	9

Sheet No.: 2

2 8 Φ -10, pp 2-45 & 61 -23-2, pp 6-18/27 & 76 -23-3, pp 32-14 & 58 -10, pp 2-45 & 60 -23-2, pp 6-18/26 & 75 -23-3, pp 32-14 & 58-5 -10, p 2-61 -23-2, pp 6-21/27 & 76 -23-3, pp 32-14/15 & 58-5 -23-2, pp 6-66/67 -23-3, pp 31-21/22 8 46-24 REFERENCES (TM 55-1520-237) -23-2, pp 6-66 -23-3, pp 32-16 & 46-24 -23-2, p 3-14 -23-3, pp 13-15/16 -23-3, pp 29-27 & 31-21 -23-2, p 6-24 -23-3, p 32-13 CONDITION TYPE - DURATION Cautionary - unspecified Cautionary - unspecified Cautionary - unspecified PARAMETER >20 amps/phase to the applicable con-verter from No. 1 or No. 2 AC Pri-mary Bus, respec-tively >5 amps to the No. 2 SDC from the No. 2 AC Primary Bus through CB 243 and >5 amps to the No. 1 SDC and Fuel Quantity signal conditioner from the No. 1 AC Pri-Temperature >160°F and/or unbalanced cell voltage Bus has been disconnected from No. 1 and No. 2 DC Primary Buses and from the BATT BUS >5 amps redundant current to respec-tive engine ECU and/or history recorder, from No. 1 or No. 2 AC Primary Bus, through CB 124 mary Bus, respectively >40 amps to pump motor from the No. 1 AC Pri-mary Bus CONDITION 6 OPERATING MODE Ξ Ę F A E UNITS Amps Amps 1 ł * **MARKINGS** Amber Amber Amber S S 20 5 INDICATOR RANGE Tripped Crct Brkrs (CB 146, CB 244) Caution Lgt Caution Lgt Caution Lgt Tripped Crct Brkrs (CB 124 & CB 243) Tripped Crct Brkrs (CB 163 & CB 264) Tripped Crct Brkrs (CB 132 & CB 229) Tripped Crct Brkr (CB 404) Engine Overspeed Protection Circuit Redundant Power #1 (2) SCD Power & Fuel Qty Sig Conditioner Pwr Backup Hydraulic Pump Motor Pwr -DC ESS BUS OFF NO. 1 (2) AC INST Battery Over-charge & Over-temperature -NO. 1 (2) ENG OVSP PARAMETER NAME-INDICATOR LABEL BATTERY FAULT NO. 1 (2) DC INST HYD PIAR PUMP D.C. Essential Bus Status -BATTERY LOW CHARGE Interrupted -Interrupted -DC Converted Power Low Battery Charge -NO. 1 (2) CONVERTER Interrupted

(able: 85 (Electrical-Cont'd)

ADAMETED NAME		INDICATOR	08				PARAMETER		
INDICATOR LABEL	TYPĘ	RANGE	MARKINGS	UNITS	WODE MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-237)	(SH 20)
Range Extension Tank Pump Pwr – #1 (2) EXTD RANGE PUMP	Tripped Crct Brkrs (TBD)		15			vespective pump from the No. 1 or No. 2 AC Primary Bus, respectively		-10, pp 2-48/51	:
Auxiliary Fuel Quantity Indicator Pwr - AUX FUEL QTY	Tripped Crct Brkr (TBD)		2			>2 amps to gauging unit from the No. ? AC Primary Bus		-23-2, pp 2-48 & 51 -23-2, pp 1-9/11	4
Provisional 60 Hz Converter Power - 60 HZ	Tripped Crct Brkr (CB 161)		15	Amps	A11	>15 amps to converter from the No. 1 AC Primary Bus		-10, p 2-51 -23-3, pp 31-14 & 20	
AC Essential Bus Fail Relay Power - AC ESNTL BUS WARN	Tripped Crct Brkr (CB 225)		S			>5 amps to relay from the AC Essential Bus		-10, pp 2-48 & 51 -23-2, pp 6-13 -23-3, p 31-19	
Stabilator Amplifier 115 VAC Power - STAB CONTR	Tripped Crct Brkrs (CB 145 & CB 242)		S			>5 amps to No. 1 and No. 2 ampli- fiers from the No. 1 and No. 2 AC Primary Busses, respectively		-10, p 2-33 & 51 (TM 11-150-237) -23-1, pp 2-16 & 17 -23-2, pp 2-98 & 102	
Stabilator Con- trols/AFCS- Panel, Stabila- tor Amplifiers, Stabilator Actuators and Stabilator Up-Down Limit	Tripped Crct Brkr (CB 116 & CB 209)		7.5	Amps	LIA	77.5 amps to indi- cated devices from No. 1 and No. 2 DC Primary Busses, respectively		-10, pp 2-33 & 47 (TM 11-1520-237) -23-1, pp 2-16 & 17 -23-2, pp 2-98 & 102	The second secon
STAB PWR									

The W.

Table: B5 (Electrical-Cont'd)

-	(SH 20)		est.	• 0				
0.0000000000000000000000000000000000000	(TM 55-1520-237)	-10, pp 2-34 & 5! (TM 11-1520-237) -23-1, pp 2-15 & 17		-23-2, pp 2-94 & 100				
PARAMETER	CONDITION TYPE - DURATION							
	CONDITION	>2 amps to indi- cated devices from the 26 vac Essen- tial Bus	22 amps, 115 vac to amplifier from AC Essential Bus	>5 arps, 28 vdc to amplifier, AFCS panel and SAS OFF caution light from DC Essential Bus	>2 amps to compu- ter and fan motors from No. 2 AC Primary Bus	>2 amps to the roll and yaw rate gyros from the 26 volt AC Essential Bus	77.5 (5) amps to the AFCS panel and SAS/FPS computer from the No. 1 (2) DC Primary Bus	55 amps to systems listed above from No. 2 DC Primary Bus with the addi- tion of power to self test cir- cuitry in the com-
ODE DATENCE	MODE				A11			Weight on wheels
	UNITS				Атро		· · · · · · · · · · · · · · · · · · ·	
CATOR	MARKINGS	2	2	ιn.	2	2	, ,	(Resp.)
INDICA	RANGE							
	TYPE	Tripped Crct Brkr (CB 218)	Tripped Crct Brkr (CB 217)	Tripped Crct Brkr (CB 313)	Tripped Crct Brkr (CB 259)	Tripped Crct Brkr (CB 219)	Tripped	CR 208)
DADAMETED NAME	INDICATOR LABEL	Stabilator Posi- tion Transmitter and Indicators 26 vac Power - STAB IND	Analog Stability Augementation System (SASI) Power - SAS AMPL	SAS BOOST	Digital Auto. Flt Control Sys. (SAS2) Power Interrupted -	26V INST	er er er er	

Sheet No.: 5

		INDICATOR	T0R		Courtes		PARAMETER	DEFEDENCE	NOTE #
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	COMDITION TYPE - DURATION	(TM 55-1520-237)	(SH 20)
Pitot Heater Power Interrupted - LEFT (RIGHT) PITOT HEAT	Tripped Crct Brkrs (CB 122 & CB 241)		10			or right heater or right heater elements from No. 1 or No. 2 AC Primary Busses, Respectively		-10, pp 2-48 & 51 -23-2, pp 6-62 -23-3, pp 31-21/22 & 44-4	
Engine Inlet Anti-Ice Valve & Anti-Ice Start Bleed Valve Pur Overdraw - NO. 1 (2) ENG	Tripped Crct Bkrs (CB 135 & CB 234)		w	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \		55 amps to start bleed valves from No. 1 & No. 2 DC Primary Bus respectively. Also >5 amps to No. 2 Eng. Inlet Anti-Ice valve from No. 2 DC Primary Bus & 55 amps to Left & Right Pitot Heat caution capsules through CB 135		-10, pp 2-40, 47 & 51 -23-2, pp 3-19 & 6-62 -23-3, pp 16-13/14, 17-8, 44-4 & 32-13, 16	
			:	Schut	No. 1 Ng > 52% to 55%	>5 amps to the No. 1 Eng. Inlet Anti- Ice Valve from the No. 1 DC Primary Bus, thru CB 135			
Engine Anti-Ice On and Engine Inlet Anti-Ice On Advisory Cap- sules Power Interrupted - NO. 1 (2) ENG ANTI-ICE WARN	Tripped Crct Brkrs (CB 134 & CB 233)		5		A11	>5 amps to the capsules from the No. 1 & No. 2 DC Primary Busses respectively			
Cargo Hook Re- lease Solenoid Pur Overdraw - CARGO HOOK PUR	Tripped Crct Brkr (CB 237)		S			25 amps to sole- noid from No. 2 DC Primary Bus		-10, pp 2-47 & 4-11 -23-2, pp 2-21/22 -23-3, pp 2-9/10	

Sheet No.: 6

	(SH 20)				
	REFERENCES (TM 55-1520-237)	-10, pp 2-47 & 4-11 -23-2, pp 2-21/22 -23-3, pp 2-9/10		-10, pp 2-11 & 47 -23-1, p 3-2 -23-2, pp 2-27 & 6-34 -23-3, pp 6-5 & 38-4	-10, pp 2-43, 44 & 51 -23-2, pp 2-17 -23-3, pp 3-7/8, 16-13/14 & 31-22
PARAMETER	CONDITION TYPE - DURATION				
	CONDITION	55 amps to cargo hook, anti cycling relay & HOOK ARMED advisory light (when arming sw is in ARMED position) & CARGO HOOK (when Hook Open sw; Sz, or linkage safe switch S3 is open) from No. 2 DC Primary Bus	>5 amps to cir- cuitry and squib from DC Essential Bus	>5 amps to indi- cated systems from the No. 1 DC Primary Bus	>5 amps to motor from No. 2 AC Primary Bus
OWIT A GROOM	MODE		A11		
	UNITS		Amps		
ICAT0R	MARKINGS	ഗ	w	ഗ	so.
INDICA	RANGE				
	TYPE	Tripped Crct Brkr (CB 238)	Tripped Crct Brkr (CB 306)	Tripped Crct Brkr (CB 140)	Tripped Crct Brkr (CB 263)
DADAMETED NAME	INDICATOR LABEL	Cargo Hook Re- lease Control Pur Overdraw - CARGO HOOK	Emergency Release Cartridge & Test Circuitry Pur Overdraw - CARGO HOOK	Dimming Cir- cuitry, Instru- ment Panel & Console Lights, Parking Brake Light & Gust Lock Light Pur Overdraw -	Ventilation Blower Motor Pur Overdraw - HEAT & VENT

Sheet No.: 7

		INDICATOR	T0R		241740700		PARAMETER	212/11/20	4 2104
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-237)	(SH 20)
Ventilation Blower Motor Control Pur Overdraw -	Tripped Crct Brkr (CB 213)		S		A11	>5 amps to blower relay in RH Relay Panel, thru VENT BLOWER switch		-10, pp 2-43, 44 & 51 -23-2, pp 2-17 -23-3, pp 3-7/8, 16-13/14 &	
HEAT VENT								77-16	
Engine Cross- bleed Valve or APU Bypass Valve and/or Mixing Valve Pwr	Tripped Crct Brkr (CB 155)				Air Source HEAT/ STARI SW at ENG, HEAT SW	>5 amps to No. 1 or No. 2 cross- bleed walve relay from No. 1 DC primary Bus			
AIR SOURCE HEAT					5				
			'n	Amps	Air Source HEAT/ START Sw at ENG, HEAT SW	55 amps to valves above plus Mixing valve			
					Air source HEAI/ START sw at OFF	>5 amps to Mixing Valve			
					Air source HEAT/ START sw at APU, HEAT sw OFF	>5 amps to APU start bypass valve relay (K22)			
					Air source HEAT/ START SW at APU, HEAT SW	>5 amps to relay K22 plus Mixing valve relay			

Sheet No.: 8

NOTE # (SH 20) 12 -10, pp 2-47, 48 & 4-1 -23-2, pp 2-25 -23-3, pp 9-5/6 -10, pp 2-39/40, 47, 48 & 50 -23-2, pp 6-48/50 -23-3, pp 5-7/8 & 31-32 REFERENCES (TM 55-1520-237) -10, pp 2-39 & 51 -23-2, p 2-18 -23-3, pp 4-5/6 & 31-21 CONDITION TYPE - DURATION PARAMETER 77.5 amps to Chaff Dispenser control panel & electronic module from No. 1 DC Primary Bus >5 amps to the controllers from the No. 2 & No. 1 DC Primary Busses, >7.5 amps to in-hibit relay & electronic module >15 amps to ele-ments or Anti-Ice Controllers from No. 2 & No. 1 AC Primary Busses respectively >5 amps to motor from No. 1 AC Primary Bus >5 amps to the relay from the Battery Bus CONDITION respectively OPERATING MODE wheels Weight on wheels Weight off A: UNITS Amps MARKINGS S 'n 2 15 INDICATOR RANGE Tripped Crct Brkrs (CB 252 & CB 133) Tripped Crct Brkr (CB 10) Tripped Crct Brkrs (CB 261 & CB 160) Tripped Crct Brkr (CB 159) Tripped Crct Brkr (CB 110) TYPE Windshield Anti-Ice Heating Ele-ment Power Overdraw -Windshield Anti-Ice Controller Pwr Overdraw -Windshield Anti-Ice Pwr Disable Relay (K21) Pwr Overdraw -Windshield Wiper Motor Power Overdraw -PILOT (CO-PILOT) WSHLD ANIT-ICE Chaff Dispenser Pur Overdraw -PARAMETER NAME-INDICATOR LABEL APU GEN CONTR PILOT (CO-PILOT WSHLD ANTI-ICE WSHLD WIPER CHAFF DISP

Sheet No.: 9

NOTE # (SH 20) -10, pp 2-33, 47 & 48 -23-2, p 3-12 -23-3, pp 14-6 & 32-16 -23-2, pp 3-16 \$ 23 -23-3, pp 11-10/11, 12-10/11 \$ 15-5/6 -10, pp 2-22, 40, 47 51 -10, pp 2-19, 26, 47 48 -23-2, pp 3-11 & 19 -23-3, pp 16-13/14, 17-8 REFERENCES (TM 55-1520-237) CONDITION TYPE - DURATION PARAMETER tion light, if lit (also possible pwr to start valve) or to APU Bypass valve if relay K22 is on (Air Source Heat/ Start switch in APU position or relay jammed) >2 amps to lights specified from No. 1 or No. 2 DC Primary Busses, respectively Eng Start >5 amps to systems on APU, Ng <52%- Bus 55% >5 amps to motor from No. 2 DC Primary Bus Eng Start >5 amps to all no APU, above except APU NG <52%- Bypass valve 55% CONDITION All other condi-OPERATING MODE Ę MARKINGS | UNITS Amps S S INDICATOR RANGE Tripped Crct Brkrs (CB 136 & CB 235) Tripped Crct Brkr (CB 210) Tripped Crct Brkr (CB 312) TYPE No. 1 Engine
Inlet Anti-Ice
Valve, Relay
K45, #1 Engine
Starter Caution
Light, #1 Engine
Start Confrol
Valve # APU Bypass Valve Pwr
Overdraw -Filter Bypass & Engine Chip Caution Lights Pur Overdraw Engine Speed Trim Motor Pwr Overdraw -NO. 1 (2) ENG WARN LTS PARAMETER NAME-INDICATOR LABEL SPEED TRIM NO. 1 ENG START

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Table: B5 (Electrical-Cont'd)

		INDICATOR	70 R		CMITAGO		PARAMETER	SUCNIGIA	* STON
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-237)	(SH 20)
Starter Speed Sw. #2 Engine Starter Caution	Tripped Crct Brkr				Eng Start on APU, Ng <52%- 55%	Eng Start >5 amps to systems on APU, from No. 2 DC Ng <52%- Primary Bus 55%		-10, pp 2-22, 40, 47 & 51 -23-2, pp 16-13/14,	
Light, #2 Engine Start Control Valve & APU By- pass Valve Pwr					Eng Strt, no APU, Ng <52%- 55%	Eng Strt, >5 amps to all no APU, above except APU Ng <52%- Bypass valve 55%		3	
NO. 2 ENG START CONTR					All other condi- tions	All other >5 amps to caution condi- light if lit (also tions possible power to Start valve) or to APU Bypass valve if relay K22 is on (Air Source Heat/ Start switch in APU possible contact in APU contact or APU contact in APU contact or APU contact in APU contact or APU conta			
			u	4		jammed)			
APU Control Amplifier, Fire Detector, APU	Tripped Crct Brkr		n	S	No APU Fire	<pre>>5 amps to detec- tor & amplifier from the Battery Bus</pre>		-10, pp 2-16, 47 & 48 -23-2, pp 6-48, 52 & -23-3, pp 18-8/9	
Overdraw -	(11 00)				APU Fire	>5 amps to all systems			
No. 2 Eng Contrl Amplifier, Fire Detectors, Eng T-Handle & Fire	Tripped Crct Brkr				No #2 Eng Fire	>5 amps to detectors & amplifier from the DC Essential Bus			
Overdraw - FIRE DET NO. 2 ENG					#2 Eng Fire	>5 amps to all systems			

Sheet No.: 11

1

NOTE # (SH 20) -10, pp 2-26, 46 & 48 -23-2, pp 3-20 & 23 -23-3, pp 21-5/6 & 32-17/18 **4**8 -10, pp 2-16, 47 & 48 -23-2, pp 3-18, 20 & 21 -10, pp 2-26, 47 & 48 -23-2, pp 3-27/28 -23-3, pp 22-5/6 -23-3, pp 19-13/14 & 32-16/18 REFERENCES (TM 55-1520-237) -10, pp 2-16, 47 & -23-2, pp 6-48, 52 -23-3, pp 18-8/9 CONDITION TYPE - DURATION PARAMETER >5 amps to detector & amplifier (& relay K43 if caution/advisory lgts dimmed) from DC >5 amps to all systems except Re-lay K24 from CB I at hru CB 253 from the No. 2 DC Primary Bus >5 amps to systems, depending on Fuel Pump, APU & APU Turnly Handle Sw's. Pwr is from the Battery Bus. >5 amps to systems from No. 1 DC Primary Bus >5 amps to all systems thru CB l from the Battery Utility Bus >5 to all systems except relay K43 (unless caution/ CONDITION **Essential Bus** advisory lgts dimmed) OPERATING MODE T-Handle Pulled Impact Sw Acti-vated (Force Fuel Pump Sw Not Off No #1 Eng Fire #1 Eng Fire All UNITS Amps MARK I NGS S S S S INDICATOR RANGE Tripped Crct Brkrs (CB 1 & CB 253) Tripped Crct Brkr (CB 3) Tripped Crct Brkr (CB 154) Tripped Crct Brkr (CB 304) TYPE Eng Prime Shut-off Valves, APU Shutoff Valve, Prime Boost Pump & Prime Boost Pump On Advisory Light Pwr Fire Extinguisher Logic Module, Impact Relay K24 Directional Control Valve & No. 1 & 2 Main & Reserve Squib Per Overdram Fuel Low Caution Lights Pur Overdraw -Mo. 1 Eng Control Amplifier, Fire Detectors, Eng T-Handle & Fire Lights & Relay K-43 Purr PARAMETER NAME-INDICATOR LABEL FUEL LOW WARN FIRE DET NO. ENG uel Low Level Conditioner & FUEL PRIME BOOST FIRE EXTGH Overdram -

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Sheet No.: 12

NOTE # (SH 20) -10, pp 2-46, 48 & 52 -23-2, pp 3-32 & 35 -23-3, pp 24-16/17 & 32-17/18 -10, pp 2-35 -23-2, pp 5-2, 3, 10, 11 & 16 -23-3, pp 29-27/34, 30-4 & 32-16 -10, pp 2-37, 47 & 48 -23-3, pp 26-8 & 27-7/8 -10, pp 2-36, 37, 47 REFERENCES (TM 55-1520-237) -23-3, pp 26-8 -10, p 2-48 -23-3, p 29-27 CONDITION TYPE - DURATION **PARAMETER** >5 amps to systems as selected by Backup Hyd Pump sw. Power is from the DC Essential Bus >5 amps to systems from Battery Util-ity Bus & Battery Bus respectively | >5 amps to lights | from No. 2 DC | Primary Bus >5 amps to lights from the AC Essential Bus CONDITION Unspecified OPERATING MODE A] UNI TS Amps MARK I NGS 'n 2 2 INDICATOR RANGE Tripped Crct Brkrs (CB 7 & CB 12) Tripped Crct Brkr (CB 211) Tripped Crct Brkr (CB 153) Tripped Crct Brkr (CB 317) Tripped Crct Brkr (CB 324) TYPE Intermediate &
Tail Rotor Gearbox Temp Caution
Lgts & all Xmsn
Chip Caution
Lgts Pwr
Overdraw -Hydraulic Logic Modules & Re-lays K19, K31 & K46 Pwr Overdraw -Main Xmsn Oil Pressure & Temp Caution Lgt Pwr Overdraw -APU Control Sw, ESU & APU Time Delay Relay K47 Pwr Overdraw -APU CONTR INST PARAMETER NAME-INDICATOR LABEL BACKUP PUMP PWR Ground from CB 404 pin 3 -BACKUP HYD CONTR MAIN XMSN CHIP DET

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Table: 85 (Electrical-Cont'd)

	(SH 20)										
	₹\$) 										
0100100	(TM 55-1520-237)		-23-3, pp 29-27/34, 30-4 & 32-16								
	- DURATION										
PARAMETER	CONDITION TYPE										
	CONDITION		>5 amps to systems	Frimary Bus		>5 amps to systems from No. 1 DC Primary Bus					
) DOCO ATTING	MODE					A11					
	UNITS					Amps					
708	MARKINGS					w					
INDICATOR	RANGE		:								
	TYPE	Tripped Crct Brkr (CB 228)	:	Tripped Crct Brkr (CB 227)		Tripped Crct Brkr (CB 128)	!	Tripped Crct Brkr (CB 127)		Tripped Crct Brkr (CB 129)	
DARAMETER NAME.	INDICATOR LABEL	2nd Stage Pri- mary Servo Shut- off Valve & Logic Module Pwr Overdraw -	NO. 2 SERVO CONTR	#1 Pri Servo Press & #2 Hyd Pump Caution Lgts & Logic Module Pwr Overdraw -	NO. 2 SERVO MARN	1st Stage Pri- mary Servo Shut- off Valve, Tail Rotor Servo Sw Position Sense to Logic Module Pwr Overdraw -	NO. 1 SERVO CONTR	#2 Pri Servo Press & #1 Hyd Pump Caution Lgts & Logic Module Pur Overdraw -	NO. 1 SERVO WARN	t 4	WARN

Sheet No.: 14

NOTE # (SH 20) -10, pp 2-46/51 -23-2, pp 6-6/18 -23-3, pp 31-18/22 & 32-13/18 REFERENCES (TM 55-1520-237) CONDITION TYPE - DURATION PARAME TER >7.5 amps to AC Essential Bus from #2 AC Primary Bus 77.5 amps to AC Essential Bus and to AC ESNT. BUS XFR relay (K8? from the #1 AC Primary Bus >5 amps to one or both lights from the Battery Bus >5 amps to trans-former from AC Essential Bus >5 amps to light from #1 (2) DC Primary Busses >5 amps to light from Battery Bus CONDITION respectively OPERAT: NG MODE #2 AC Pri Bus Off #1 AC Pri Bus Off 711 All MARKINGS UNITS Amps 7.5 S INDICATOR RANGE Tripped Crct Brkrs (CB 130 & CB 230) Tripped Crct Brkrs (CB 125 & CB 257) Tripped Crct Brkr (CB 4) Tripped Crct Brkr (CB 5) Tripped Crct Brkr (CB 224) TYPE Ext Pwr Con-nected Advisory Lgt & DC Ess Bus Off Caution Lgt Pwr Overdraw -AC Essential Bus
Off, #1 & #2
Conv Caution
Lgts Pwr
Overdraw -#1 (2) Gen Caution Lgts Pwr Overdraw -ESNTL BUS AC & CONV WARN T12 Auto Trans-former Pwr Overdraw -PARAMETER NAME-INDICATOR LABEL BATT & ESNTL DC WARN EXT PWR CONTR NO. 1 (2) GEN WARN AC ESNTL BUS SPLY AC Essential Bus Pur Overdram -AUTO XFMR

Sheet No.: 15

NOTE # (SH 20) -10, pp 2-46/51 -23-2, pp 6-6/18 -23-3, pp 31-18/22 & 32-13/18 REFERENCES (TM 55-1520-237) CONDITION TYPE - DURATION P AR AME TER 77.5 amps thru CB 232 from the #2 DC Primary Bus or 55 amps booster current thru CB 258 from the #2 AC Primary Bus >50 amps from the No. 1 or No. 2 DC Primary Busses respectively. (Note CB 102 also powers No. 2 DC ESNTL BUS SPLY Relay KIO) >7.5 amps to receptacle from the >5 amps to relay from #1 DC Primary Bus >50 amps from the Battery Bus >7.5 amps to receptable from No. 1 DC Primary Bus >5 amps to relay from #2 DC Primary Bus CONDITION OPERATING MODE #1 Con-verter Failure #2 Con-verter Failure verter failed, Battery > 35% ± 5% charge #1 8 #2 A] A11 A۱۱ A]] Con-Amps UNITS 7.5 & 5 (Respectively) MARK I NGS 7.5 7.5 S 20 INDICATOR RANGE Tripped Crct Brkrs (CB 131 & CB 231) Tripped Crct Brkrs (CB 232 & CB 258) Tripped Crct Brkrs (CB 102 & CB 202) Tripped Crct Brkr (CB 6) Tripped Crct Brkr (CB 156) Tripped Crct Brkr (CB 260) Battery Charger Current Over-draw -DC Essential
Bus Pwr
Overdraw DC ESNTL BUS
SPLY 28 vdc Utility Receptacle Pwr Overdraw -BUS TIE CNTOR Utility Receptacle Pwr Overdraw -ESNTL DC BUS SPLY PARAMETER NAME-INDICATOR LABEL DC Bus Tie Cntor Relay (K15) Pwr Overdraw -UTIL RECP CABIN UTIL RECP BATT CHOR

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Table: B5 (Electrical-Cont'd)

Sheet No.: 16

	• (0,			<u>-</u>									
	(SH 20)												
	(TM 55-1520-237)	-10, pp 2-46/51 -23-2, pp 6-6/18 -23-3, pp 31-18/22 & 32-13/18						-10, pp 2-54 & 46/51 -23-2, pp 6-27, 29, 30, 32, 36, 38	& 40 -23-3, pp 33-6 & 36-5				
PARAMETER	CONDITION TYPE - DURATION												
	CONDITION	>10 amps to bus from DC Essential Bus	>5 amps to relay from DC Essential Bus		>5 amps to relays from Battery Utility Bus	>5 amps to relays except K9			>5 amps to lgts	rrom No. 2 DC Primary Bus		>5 amps to lgts from No. 1 AC Primary Bus	
	MODE	All	All		Battery > 35% ± 5% chrg (Batt sw on)	Battery < 35% ± 5% chrg	(Batt Sw on)			All	•		-
	UNITS							Amps					
TOR	MARK I NGS	10	5		S.								
INDICAT	RANGE												
_	TYPE	Tripped Crct Brkr (CB 301)	Tripped Crct Brkr (CB 302)		Tripped Crct Brkr (CB 2)			Tripped Crct Brkr (CB 249)		Tripped Crct Brkr (CB 248)		Tripped Crct Brkr (CB 150)	
Court Court Court	INDICATOR LABEL	Battery Bus Pwr Overdraw - BATT BUS SPLY	DC ESNTL Bus Fail Relay Pwr Overdraw -	ESNTL DC SENSE	Battery Analyzer/Condi- tioner Relay (KZ), Battery Relay (KT) &	Bus Sply Relay (K9) Pur Overdram -	BATT BUS CONTR	Non Flgt Panel Lights Pur Overdraw -	LIGHTS NON FLT	Pilot's Flt Instrument & POU Lgts Pwr Overdraw -	LIGHTS PLT FLT	Copilot's Fit Instrument & CPDU Lgts Pwr Overdraw -	LIGHTS CPLT FLT

Sheet No.: 17

NOTE # (SH 20)

-10, pp 2-54 & 46/51 -23-2, pp 6-27, 29, 30, 32, 36, 38 & 40 -23-3, pp 33-6 & 36-5 REFERENCES (TM 55-1520-237) CONDITION TYPE - DURATION PARAMETER >5 amps to lamps selected by ap-plicable sw's, from DC Essential Bus >5 amps to lgts from No. 2 AC Primary Bus >5 amps to lgts from No. 1 AC Primary Bus >5 amps to lgts from No. 1 AC Primary Bus >5 amps to lgts from No. 1 DC Primary Bus >5 amps to lgts from No. 1 AC Primary Bus >5 amps to lgts from Battery Utility Bus CONDITION OPERATING MODE Ę Amps UNITS MARKINGS S INDICATOR RANGE Tripped Crct Brkr (CB 141) Tripped Crct Brkr (CB 310) Tripped Crct Brkr (CB 250) Tripped Crct Brkr (CB 148) Tripped Crct Brkr (CB 8) Tripped Crct Brkr (CB 149) Tripped Crct Brkr (CB 147) Lower Console lgts, Dimming Control & Relay K41 Pwr Cockpit Utility Lgts Pwr Overdraw -Pilot's Standby Compass, Sec-ondary & Flood Light Pur LIGHTS LIFE CSL Cabin Dome Lgts Pur Overdraw -LIGHTS CABIN DOME PARAMETER NAME-INDICATOR LABEL LIGHTS SEC PNL LIGHTS UPPER CSL UTIL LTS CKPT Red Secondary Lgts Pwr Overdraw -Upper Console Lgts Pwr Overdraw -LIGHTS CKPT FLOOD White Flood Lgts Pwr Overdraw -LIGHTS SEC Overdraw -

Sheet No.: 18

NOTE # (SH 20) -23-2, pp 6-41, 43/47 -23-3, pp 39-4 -10, pp 2-55, 47, 48 51 REFERENCES (TM 55-1520-237) CONDITION TYPE - DURATION PARAMETER >5 amps to lights from dimmer control >5 amps to system from No. 2 AC Primary Bus >5 amps to system from No. 2 DC Primary Bus >5 amps to system from No. 1 DC Primary Bus >5 amps to system from No. 2 AC Primary Bus >25 amps to lamp from No. 1 DC Primary Bus CONDITION OPERATING MODE F UNITS Amps MARKINGS S 22 2 INDICATOR RANGE Tripped Crct Brkr (CB 245) Tripped Crct Brkr (CB 246) Tripped Crct Brkr (CB 212) Tripped Crct Brkr (CB 138) Tripped Crct Brkr (CB 137) Tripped Crct Brkr (CB 247) TYPE Formation Lgts
Dimming Control
& Formation Lgts
Pur Overdraw -Position Lgts & Dimmer & Flasher Crct Pur Overdraw -LIGHTS FORM HV LIGHTS FORM LV Anti-Collision Lgts Pwr Supply Current Over-draw -LIGHTS RET LDG CONT LIGHTS RET LDG PUR PARAMETER NAME-INDICATOR LABEL Landing Light Motor, Control & Advisory Lgt Pwr Overdraw -Formation Lgts Pwr Overdraw -Landing Lgt Lamp Pwr Overdraw -LIGHTS ANTI-COLL POS LTS

Sheet No.: 19

PADAMETED MAME		INDICATOR	T0R		OBEDATING		PARAMETER		-
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-237)	(SH 20)
Search Light Motor Pur Overdraw -	Tripped Crct Brkr (CB 308)		S			>5 amps to motor from DC Essential Bus		-10, pp 2-55, 47, 48 & 51 -23-2, pp 6-41, 43/47	
LIGHTS SCHLT CONT								-23-3, pp 39-4	-
Search Lgt Lamp Pwr Overdraw -	Tripped Crct Brkr (CB 309)		20			>20 amps to lamp from DC Essential Bus			iller Sildervoor - voor. v
LIGHTS CONTR PMR									
Tail Wheel Lock Actuator & Lgts Pwr Overdraw -	Tripped Crct Brkr		S	Amps	A11	>5 amps to system from DC Essential Bus		-10, pp 2-11, 47 & 48 -23-3, p 7-4	er – sakra ansk gra nd
TAIL WHEEL LOCK	(18 311)								
Master Warning Pnl, Caution/ Advisory Pnl & Audible Warning Unit Pur	Tripped Crct Brkr (CB 325)		S			>5 amps to system from DC Essential Bus		-10, pp 2-47, 48 & 57 -23-2, pp 6-70, 72 & -23-3, pp 47-8/10	
CAUT/ADVSY PNL									
Caution/Advisory Pnl Lamp Test Pwr Overdraw -	Tripped Crct Brk.		7.5			>7.5 amps to lamps from No. 1 DC Primary Bus			
LIGHTS CAUT ADYSY	(ce 133)								

OTES:

- 1. Sensors are contained in the respective generator control units (GCU's). When any of the voltage, current or frequency limits are exceeded, the GCU's cause the No. 1 or No. 2 generator control relays (K1 & K2) to close, and power is supplied to the caution lights from the No. 1 and No. 2 DC Primary Busses, respectively, through caution/advisory panel channel card Al. Additionally, the caution light may be activated by placing the applicable generator switch in the TEST position, which will activate the test relay in the appropriate GCU.
- Sensors similar to those above, except GENERATORS APU switch must also be enabled to light the capsule. Power is supplied to the switch from the PWR READY terminal of the APU GCU, and is routed through APU/EXT PWR CNTOR relay (K3) and the AC BUS TIE CNTOR Relay (K4) to caution/advisory panel ;
- Sensor is a lead contact in the main bearing which is exposed when the bearing wears down and grounds the caution lamp, via caution/advisory panel channel card A3. Power to the lights is most likely from the No. 1 and No. 2 DC Primary Busses, through the No. 1 and No. 2 GEN WARN circuit breakers, since they supply power to channel card A3. ë
- Sensor is the AC ESNTL BUS FALL Relay (K13), which receives its power from the AC Essential Bus. Light circuitry is via caution/advisory panel channel card Al, with power from the Battery Bus.
- Sensor is the external power plug which, when inserted in the external/power receptacle (J136) jumpers pins N & E of the receptacle, thereby grounding pin J118-N of caution/advisory panel channel card A3. Power is most likely supplied by the DC Essential Bus through the CAUT/ADVSY PNL circuit breaker (CB 325).
- Semsors are the No. 1 (2) DC PRI BUS CNTOR relays, located in the No. 1 (2) Junction Boxes. The relays are energized by the respective converter output. Power to the caution lights comes from the Battery Bus through the ESSNIL BUS AC & CONV WARN circuit breaker, and is routed through the applicable relay to caution/advisory panel channel card Al.
- Sensor is the DC ESNTL BUS FAIL RELAY (K20) which is energized when power is on the DC Essential Bus. Power to the caution capsule, on channel card Al, comes from the Battery Bus through the BAIT & ESNTL DC WARN EXI PMR CONTR circuit breaker. The bus disconnect normally occurs when the No. 1 and No. 2 DC Primary Busses both lose power and the battery is below 35% ±5% charge. Additional relays which control the connection of the DC Essential Bus to a power source are the No. 1 and No. 2 DC ESNTL BUS SPLY relays (K10 & K9), the low battery charge disconnect relay (K1) in the Battery Analyzer/Conditioner and the auxiliary contacts of the No. 1 and No. 2 DC PRI BUS CNTOR relays (K16 & K6). ۲.
- Sensor is the BATTERY ANALYZER/CONDITIONER. The operator's manual says the turn-on threshold is 40% ±5%, but all other references just use 40%. Signal routing is to caution/advisory panel channel card Al. œ.
- 9. Same sensor as above. Signal goes to caution/advisory panel channel card A2. In both this case and the one above, the light power source is not specified, but is most likely the BATTERY ANALYZER/COMDITIONER.
- 10. CB 404 is on the No. 1 Main Electrical Junction Box.
- 11. Unable to identify circuit breaker number since information on the Range Extension Kit (No. 50) is not yet available on TM 55-1520-2¹⁷-23-3.
- 12. If the APU Generator is the only source of AC power and the Hydraulic Backup Pump is operating, power is applied from the Battery Bus through CB 10, through the contacts of the energized APU/EXT PUR CNTOR relay (K2), the contacts of the de-energized No. 2 GEN CNTOR relay (K2), the contacts of the de-energized No. 1 GEN CNTOR relay (K1), and the contacts of the energized HYD PUR PUMP relay (K19) to energize relay K21 which disconnects heater element power to the Anti-Ice Controller.
- 13. Insufficient information to determine function of this circuit breaker.

SUBSYSTEM PARAMETER DATA LIST

HELICOPTER: UM-60A

SUBSYSTEM: Miscellaneous

Sheet No.: 1 Table: 86

		INDICATOR	8 0				PARAMETER	-	
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	REFERENCES (TM 55-1520-237)	NOTE #
Stabilator Position Error	Beeping Tone in ICS					>10° pos. error For 0-30KTS,	Cautionary - unspecified	-10, pp 2-33/34 & 61 -23-2, p 6-75	
STABILATOR	Caution Lgt		Amber	!	matic	error for 2150KTS		-23-3, p 58-5 (TM 11-1520-237) -23-1, p 2-18	
Pitch Bias Actuator (PBA) Position Error Signal -	Caution Lgt		Amber	1	All	Signal strength indicates PBA is no longer responding to drive	Cautionary - unspecified	-10, pp 2-31 & 61 -23-2, p 6-76 -23-3, p 56-8 (TM 11-1520-237)	2
PITCH BIAS FAIL		,				signals		-23-1, pp 2-6, 9 & 12	
SAS Actuator Servo Valve Hydraulic Pressure -	Caution Lgt		Amber	psi	All	<pre><2000 ±50 to the servo valves on the pitch/trim, roll and yaw SAS</pre>	Cautionary - unspecified	-13, pp 2-32 & 61 -23-2, pp 5-3 & 6-76 -23-3, p 58-8 (TM 11-1520-237)	3
SAS OFF						actuators		-23-1, pp 2-3 & 5 -23-2, pp 2-94 & 101	
Pitch Trim Servo and/or Roll or Yaw Trim Actu- ator Pos Error -	Caution		Amber	psi	All	A trim channel has been disengaged.		-10, pp 2-32, 33, 61 &	4
TRIM FAIL	Lgts (2)							-23-2, p 6-76 (TM 11-1520-237)	
FLT PATH STAB						The flight path stabilization section of the computer is disabled.	Lautionary - unspecified	-23-1, pp 2-9, 10 & 14	
Left (Right) Pitot Heat Ele- ment Current -	Caution Lgts (2)		Amber	:	Pitot Heat Sw On	Low current in elements	Cautionary - unspecified	-10, pp 2-40, 60 & 62 -23-2, pp 6-56, 60, 62, 75 & 77	S
LFT (RT) PITOT HEAT									

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Sheet No.: 2

Table: 86 (Miscellaneous - Cont'd)

NOTE # (SH 3)

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-10, pp 4-11/14 & 2-63 -23-2, pp 2-18/21 & -23-3, pp 2-9/10 & -10, pp 2-55 & 63 -23-2, pp 6-41, 43, 46 -23-3, pp 42-5/6 & 58-9 -10, pp 2-40/42, 60/62 -23-2, pp 6-75/76 -10, pp 2-11 & 63 -23-2, pp 2-25/27 & 6-77 -23-3, pp 6-5 & 58-9 REFERENCES (TM 55-1520-237) CONDITION TYPE - DURATION Cautionary - unspecified Cautionary - unspecified Cautionary - unspecified Advisory - unspecified Advisory - unspecified Advisory - unspecified Advisory - unspecified **PARAMETER** Partial system failure. Possible uneven ice shed-ding Short or open circuit in main roter element Short or open circuit in tail rotor element Frequency shift due to ice form-ing on probe Release switches enabled Load beam open CONDITION Handle is in up position Power is on OPERATING MODE A 1 F A11 A] A11 A] A1 MARKINGS UNITS ; ; ŀ ; 1 ŀ i Amber Green Green Green Green Amber Amber INDICATOR RANGE Caution Lgt Caution Lgt Caution Lgt Advisory Lgt Advisory Lgt Advisory Lgt Advisory Lgt TYPE No. 2 Engine Inlet Ice Probe Vibration Frequency -Blade De-Ice System Status -MR DE-ICE FAIL TR DE-ICE FAIL Cargo Hook Load Beam Position -PARKING BRAKE ON Rotor Blade De-Ice Heating Element Cargo Hook Release Switch Power Enable -PARAMETER NAME-INDICATOR LABEL Parking Brake Lever Position ICE DETECTED Landing Light Lamp Power -CARGO HOOK OPEN HOOK ARMED Integrity -IR DE-ICE FAULT LDG LT ON

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MOTES:

- Sensors are feedback potentiometers in each actuator. These signals are applied to the No. 1 or No. 2 stabilator amplifiers, as applicable, which generate error signals for position commanded versus position sensed. These error signals are applied to a fault circuit which trips according to the values shown under the Parameter Condition column. The values shown seem to represent the lower and upper bounds of an error versus airspeed fault indication threshold, but this is not specifically described in any reference. The fault signal is applied to the Stabilator Control/AFCS panel, which in turn produces a signal that is applied to caution/advisory panel channel card A3 and to relay K44 of the left relay panel. This relay energizes the beeping tone of Audible Marning Unit (which has priority over the steady tone signal) and applies it to the ICS through a junction box assembly, while also energizing the warning reset circuit.
- Sensor is contained in PBA and is most likely a potentiometer driven by PBA position. The drive signal to light the capsule is generated by the Stability Augmentation System/Flight Path Stabilization computer and is routed to caution/advisory panel channel card A2. ;
- Sensor is a pressure switch on the pilot assist manifold. The signal is routed from the DC Essential Bus, via the SAS BOOST circuit breaker and pressure switch, to caution/advisory panel channel card A2. æ,
- The lamp drive signals are produced separately by the TRIM and FPS sections of the computer. Sensors for the trim section are position feed back sensors which are most likely mechanically linked potentiometers. Sensors for the FPS section are actuator return signal (current sensors which are routed to the Fault Monitor section of the computer) which will produce an FPS disable signal causing the FPS to idle and light the FLI PATH STAB caution capsule. Hence the two capsules could be lit independently if feedback information from the two sets of signals did not agree on a threshold error value for the TRIM and FPS sections. Power to the capsules is through channel cards A2 and A1 respectively. ÷
- Sensors are current switches. Power to the lights is routed through the closed left (right) hand switch from the No. 1 DC Primary Bus, via the No. 1 Eng Anti-Ice circuit breaker, to caution/advisory panel channel cards Al and A2. Š.
- Need more information on blade de-ice kit. (Listed as "to be provided" in TM 55-1520-237-23-2 & 3.) Operating modes may be tied in with de-ice system operation. ė,
- Sensor is the cargo hook release arming switch. When placed in the ON position, power is supplied from the No. 2 DC Primary Bus, through the CARGO HOOK CONT circuit breaker, to caution/advisory panel channel card A3. .
- Sensing is accomplished using the Hook Open Switch (S2) or the Linkage Safe Switch (S3). Signal routing is the same as for note 7 above. œ
- Sensor seems to be a position microswitch versus a pressure switch. Power is routed from the No. 1 DC Primary Bus through the LIGHTS ADVSY circuit breaker, through the switch (542) over to channel/advisory panel channel card A3. 6
- Power is routed to caution/advisory panel channel card A3 from the No. 1 DC Primary Bus, through the LIGHTS RETR LDG CONT circuit breaker, through contacts of an unspecified relay in the RH Relay Panel. The relay is actuated by the landing light lamp ON/OFF switch, closing relay K28, the contacts of which energize the referenced relay that turns on the advisory light. There is a maximum landing light extension airspeed of 180KTs. 10.

SUBSYSTEM PARAMETER DATA LIST

Sheet No.: 1 Table: B7

HELICOPTER: UH-60A

SUBSYSTEM: Auxiliary Power Unit (APU)

Control of the contro		INDICATOR	TOR		SPERFITME		PARAMETER	REFERENCES	Note #
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-237)	(SH 2)
APU Start Sequence (Ng. Spool-Up Time, Oil Press. 8 EGT) -	Advisory Lgt		Green	:	All	1.5 seconds after Ng reaches 90% and Ng >90%	1.5 seconds after Ng reaches 90% and Advisory - unspecified Ng >90%	-10, pp 2-52 & 63 -23-2, pp 3-32 & 6-77 -23-3, pp 24-7, 16 & 58-7	7
APU FAIL	Caution Lgt		Amber	-	ll l	Any of the following items: 1. Ng reaches 90% but then goes below 90%. 2. Ng >110% over 40 seconds over 40 seconds Ng >10% N		-10, pp 2-52 & 62 -23-2, pp 3-32 & 6-76 -23-3, pp 24-7, 16 & 58-7	2
APU 011 Temperature - APU 01L TEMP HI	Caution Lgt		Amber	:	ILA	>300°F @ Ng > 70%	Cautionary - unspecified	-10, pp 2-52 & 62 -23-2, pp 3-32 & 6-76 -23-3, pp 24-16 & 58-7	т
APU Accumulator Pressure - APU ACCUM LOW	Advisory Lgt		Green	pst	A11	(2600	Advisory - unspecified	-10, pp 2-53 & 63 -23-2, pp 5-2, 10, 13 -23-3, pp 29-29 & 58-7	4

MOTES:

- Sensors include a magnetic pickup (Ng), pressure switch (S2) and alumel-chromel thermocouple in the APU. These sensors output signals to the electronic sequence unit (ESU) which supplies a timer and combinational logic to control the APU hydraulic start valve, fuel shutoff valve, main fuel valve, maximum fuel valve, ignition exciter, start bypass valve, bite indicator and the APU caution/advisory lights. The start bypass valve is enabled and the maximum fuel valve is turned on under the same conditions which turn on the APU ON light. Power is routed by the ESU to caution/advisory panel channel card A2. **:**
- ጀ Same sensors as above. Light indicates a start sequence failure, where the specific failure (items 1-6 in the Parameter Condition column) may checked on the Built In Test Equipment (BITE) indicator. 5
- Sensor is a thermal switch in the oil sump. The second and third page references indicate a trip condition occurs above 300°F while the fourth reference says "about 301°F". No tolerance is given in any reference. The ESU provides 28 vdc to the thermal switch when Ng > 70%. The ESU senses switch position and supplies 28 vdc to caution/advisory panel channel card A2 at the temperature threshold. m;
- Sensor is a pressure switch which monitors nitrogen gas pressure used to squeeze hydraulic fluid from the accumulator to the APU start motor. The second reference gives the threshold as 2600 psi while the sixth reference (p. 6-77, TM 55-1520-237-23-2) says it is 2800 psi. However, p. 5-13 shows a normal charge of 2850 ±150 psi accumulator hydraulic pressure. Hence, the 2600 psi seems the most likely threshold. The pressure switch routes 28 vdc from the DC Essential Bus, through the BACKUP HYD CONTR (CB324) circuit breaker, to caution/advisory panel channel card A2. ÷

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MINE BUILDING AN AND AND WAY BEAUTY

SUBSYSTEM PARAMETER DATA LIST
FOR THE
OH-58C

SUBSYSTEM PARAMETER DATA LIST

Table: C1 Sheet No.: 1

HEL1COPTER: OM-58C

SUBSYSTEM: Engine (T63-A-720)

NOTE # (SH 4) -10, pp 2-17, 5-4/6 & 8-9 (TM 55-1520-228)
-23-1, pp 8-5, 9/10, -23-2, pp F-18, 27, 52 & 65 -10, pp 2-17 & 5-2 (TM 55-1520-228) -23-1, pp 8-5/8 -23-2, pp F-18 & 52 REFERENCES (TM 55-1520-235) - Minimum (to open throttle to engine idle) -25 sec (ext pwr) or 40 sec - (battery pwr) CONDITION TYPE - DURATION Warning (possible flame out) - continuous Maximum - none allowed Maximum - 15 seconds Maximum - continuous Maximum - 15 seconds Maximum - continuous Maximum (full beep) (transient) Normal - continuous Normal - continuous Normal - continuous PARAME TER 13 @ -18°C COAT 15 @ OAT > 7°C 12 @ OAT <-18°C 0= CONDITION <u><(55±3)</u> 98-100 62-105 30 @ NR 60-62 105 106 100 101 102 OPERATING MODE Collec-tive not full down Throttle full open (engine running) at idle, engine started Throttle Throttle idle -engine running Engine Start Ę above UNITS ŀ ł (62-105)G (105)R MARKINGS (98-100)G (100)R ŀ ŀ INDICATOR RANGE 0-110 0-150 ŀ ; Circular Dial (part of dual tachometer) Tone in ICS Circular Dial Warning Light TYPE PARAMETER NAME-INDICATOR LABEL Engine Gas Producer (N₁) S**pee**d -Engine Power Turbine (N₂) Speed -ENGINE OUT ENGINE RPM <u>¥</u>

Table: C1 (Engine - Cont'd)

PARAMETER NAME.		INDICATOR	T0R		OPEDATING		PARAMETER	2000000	A DIOM
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	(302-031-39 ML)] () [] ()
					Engine	0-150	Normal - continuous		
					throttle closed	150	Maximum (to open throttle to idle) - continuous		
					Casino	0-738	Normal - continuous		
					starting	738-810	Cautionary - transient		
Turbine Outlet	Circular	100-1000	(300-738)6	٥	at idle	810-927	Cautionary - 10 seconds	-10, pp 2-17, 5-3,	•
IOI			(810)R (810)R			927	Maximum - 1 second	(TM 55-1520-228)	•
Ē			W(176)		00:00	300	Maximum - continuous	-23-2, pp F-20 & 54	
					running	300-738	Normal - continuous		
				_		738-810	Cautionary - 30 minutes		
					1	810	Maximum - 30 minutes		
					shut- down	400	Maximum (w/o motoring) - none allowed		
						200	Maximum (during motor- ing) - none specified		
Factor Tomina	50000		2/30 0/			0-85	Normal - continuous	10 - 11 - 5	
TOBOLE	Dial	0-120	(85-100)Y	34	LIA	85-100	Cautionary - 5 minutes	(TM 55-1520-228)	5
			N(DOT)	_		100	Maximum - 5 minutes	44/4-0 dd *1-57-	
Factor 041			5(05)			50	Minimum - transient		
Pressure -			(50-110)Y		Engine	50-110	Cautionary - transient		
ENG OIL P		0-150	(130)R		<u></u>	110-130	Normal - continuous		o
	Shared					130	Maximum - continuous	-10, pp 2-17 & 5-3	
Engine 0il Temperature -	Dial	051 - 05-	5(201-04)	٥	r) i oht	-50	Minimum (cold weather) - unspecified	-23-1, pp 803 & 12/14 -23-2, pp F-20 & 54	,
ENG OIL T		3	(107)R	,	, , , , , , , , , , , , , , , , , , ,	60-107	Normal - continuous		-
						107	Maximum - continuous		

DADA OTTO		INDICAT	CATOR		0.00		PARAMETER		
INDICATOR LABEL	TYPE	RANGE	MARKINGS UNITS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	KEFERENCES (TM 55-1520-235)	(SH 4)
Engine Oil Reservoir I evel	oi tie		r south	200 [[6 2	Engine oil bypass switch OFF		Cautionary - none specified	-10, pp 2-17 & 29 (TM 55-1520-228)	C
ENG OIL BYPASS	Light				Engine oil bypass switch AUTO	; ;	Cautionary - none speci- fied but monitor engine oil temp. (see note)	-23-2, pp F-27 & 65	0
Engine Geartrain Integrity - ENG CHIP DET	Caution Light	1	Amber	ŀ	A11	Sensor contacts grounded by par- ticles from engine gearing	Cautionary - none specified	-10, pp 2-17 & 29 (TM 55-1520-228) -23-1, pp 4-26, 9-43 & 46/47 -23-2, pp F-27 & 65	ō
Engine Automatic Reignition System Operation -	Advisory Light	1	l	1	Engine relight switch ON	Engine flamed out and ignition being automatically applied	Advisory - none specified	-10, p 2-16 (TM 55-1520-228) -23-1, pp 9-53 & 54 -23-2, pp F-41 & 70	10

Sheet No.: 3

Table: Cl (Engine - Cont'd)

Table: Cl (Engine - Cont'd)

OTES:

1. Sensor is a tachometer generator, powered by 28 VDC. Method of operation is not described.

 Description of sensor operation was not in the available literature. An rmp sensor (S18) somehow discriminates the N₂ rpm threshold and supplies a
signal to the Audio Warning Engine Out Signal device ES17 and to the ENG OUT warning light DS14. The light flashes for 30 seconds and then illuminates
steadily. The audio warning is disabled when the collective is full down by a switch (S70). The type of tone is not described, nor is the color of the warning light.

3. Sensor is similar to that described in Note 1 above.

4. Sensors are 4 alumel-chromel thermocouples. The "A" model system requires no external power while the "C" model does.

5. Indicator is wetline type, driven by an oil pressure line ("gage line") from the engine plenum.

6. Indicator is a wetline type as above. Tolerance at 130 psi is ±4.5 psi.

7. Sensor is a variable resistance bulb type, with resistance values of 83.77 ohms (-20°C) to 104.6 ohms (+40°C) ±0.4 ohms for test points.

Sensor is a float switch in the oil reservoir. The light is illuminated by providing a grounding path through the switch to P64D on the caution panel. When this light comes on the oil cooler bypass valve circuit is enabled. Bypass occurs when the Engine Oil Bypass Switch is in the AUTO position. According to the Operator's Manual, the high oil temperatures resulting from cooler bypass can cause an engine failure "in a few minutes." Use of this bypass feature assumes oil loss in the cooler system. œ.

Sensors are magnetic plugs with contacts which provide a path to ground when bridged by ferrous metal particles. The ground is applied to P64E on the caution panel. e;

Sensor is a Reignition Control Assembly (211) which operates when a loss of bleed air from the compressor is sensed. The system activates approximately 5 seconds after detecting the pressure loss and remains active for about 3 seconds. The light will remain illuminated after that second period however, until manually reset. 9

SUBSYSTEM PARAMETER DATA LIST

Table: C2 Sheet No.: 1

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SUBSYSTEM: Fuel

Park Car		INDICAT	ATOR		03114		PARAMETER	330000000	MOTE #
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	COND 1:10N	CONDITION TYPE - DURATION	(TM 55-1520-235)	(SH 2)
Fuel Quantity. Main Tank -	Circular	009	\(\(\frac{1}{2}\)			0-65	Cautionary - none specified	-10, pp 2-17/19, 29, 32, 54 & 6-6	-
FUEL QTY	2	000-0	(60-0)	ž		009-59	Normal - continuous	-23-1, pp 8-32/39	•
20 MIN FUEL	Caution Light	•	Amber	<u> </u>		<u>⟨</u> (81.25 ±16.25)	Cautionary - none specified	23/24, F-37, 53 8 69	2
Fuel Boost Pump Pressure -					Fuel boost				r
FUEL BOOST	Caution	1	Amber	psi	Dump sw ON or Start Button	∠(4.5 ±0.5)	Cautionary - none specified	000000000000000000000000000000000000000	,
					5			(TM CC 1000 000)	
Fuel Filter Differential Pressure -	Caution Light	ŀ	Amber	1	A11	Fuel filter obstructed	Cautionary - none specified	-23-2, pp F-27 & 65	4
FUEL FILTER									

Table: C2 (Fuel - Cont'd)

NOTES:

- 1. Total fuel capacity in the main tank is 71.5 gallons with 70.3 gallons useable. For JP-4 @ 6.5 lbs/gallon, that translates to 464.75 lbs total and 456.95 lbs useable. Note that the fuel loading chart in the Operator's Manual indicates maximum fuel is 70.3 gallons. These figures are for a crash worthy fuel system. For a non crash worthy system, total capacity is 73 gallons (see TM 55-1520-228-10 p 2-10.1). Sensors are two capacitance type probes mounted in the main tank, driven by an ac signal. The indicator receives a rectified dc signal from the upper tank unit assembly (25) proportional to the pounds of fuel in the tank. An auxiliary tank with a 23.9 gallon capacity may be added to the system. There is no fuel quantity probe in the tank so a correction card (p 2-18 of the Operator's Manual) is used.
- Sensor is a float switch near the lower fuel quantity probe. It provides a path to ground for connector P64B on the caution panel. The threshold range used was given on page 10-20 of the last reference cited, and was actually given as 12.5 ±2.5 gallons. This translates to the range listed on sheet 1, using 6.5 lbs/gallon. The lower limit of the range is 65 lbs, which coincides with the figure given in the Operator's Manual. ?
- Sensor is a pressure switch located upstream of the boost pump on top of the tank. The light turn-off threshold is 8 psi (increasing pressure). The turn-on threshold is the one listed on sheet 1. The boost pump is required for operations above a 10,000' pressure altitude. ۳.
- 4. The light may be on for as much as ten seconds when the boost pump is turned on. No pressure threshold for switch activation could be found in the literature.

Sheet No.: 1

Table: C3

SUBSYSTEM: Powertrain

NOTE # (SH 2) 2 ٣ 2 4 9 -10, pp 2-21, 5-2 & 9-44/45 & 47 (TM 55-1520-228) -23-1, pp 6-80, -23-2, pp F-27, 63 & 65 -(TM 55-1520-228) -23-1, pp 8-5/7, 10, & -10, p 2-21 (TM 55-1520-228) -23-1, pp 6-75, 9-45 & 46A -10, pp 2-17, 21/22 & 5-2 -10, pp 2-21 & 29 (TM 55-1520-228) -23-1, op 6-71, 80, 9-43 & 47 -23-2, pp F-27 & 65 -23-2, pp F-18 & 52 REFERENCES (TM 55-1520-235) CONDITION TYPE - DURATION Cautionary - transient Minimum - continuous Maximum - continuous Minimum - continuous Normal - continuous Normal - continuous Sensor contacts
grounded by ferrous Cautionary - none
metal particles specified
from the gearbox |Cautionary - none | specified Cautionary - none specified Cautionary - none specified Maximum - none specified PARAMETER ₹(95 ±1.4) CONDITION 93-110 ∠(30 ±2) 49-58 <u>≥</u>110 93 110 30-60 8 2 OPERATING MODE Collec-tive not full A . 4 A] 1 MARKINGS | UNITS psi ٧ ١ (49-58)Y (93)R (93-110)G (110)R (30)R (30-60)G (70)R Amber 1 ŀ ŀ ; INDICATOR RANGE 0-120 0-100 ; i į i ŀ Circular Dial (part of dual Tone in ICS tachometer) Circular Dial Warning 1 ight Warning Light Marning Light Caution Light TYPE XMSN OIL PRESS Transmission 0il Temperature -Transmission Oil Pressure -PARAMETER NAME-INDICATOR LABEL XMSN CHIP DET Main Rotor RPM XMSN 01L HOT TAR CHIP DET Transmission Mechanical Integrity -Tail Rotor Gearbox Mechanical Integrity -ROTOR RPM ROTOR RPM XMSN OIL

The second secon

CANADA STATES OF STATES

(Pomertrain - Cont'd) ឧ Table:

- Sensor is a tachometer generator with a 28 VDC power source connected to the generator/indicator system. Mode of operation is not described in the
- Sensor is an rpm interpreter (S91) which receives inputs from the tachometer generator. Mode of generation is not described in the available
 literature. The sensor threshold listed is from the Operator's Manual and is the only one listed in all of the references with values in % rpm. All
 other sources indicate a threshold of 335 ±5 rpm. The type of tone in the ICS (Audio Marning signal) is not described. The tone is disabled by switch
 S70 which is actuated by placing the collective full down. The color of the warning light is not described.
- The parameter conditions shown are further amplified on page 9-9 of the Operator's Manual. If the XMSN OIL PRESS light comes on, three different courses of action are recommended, based on whether the oil pressure gauge is less than 20 psi, 20-30 psi or above 30 psi. The sensor operation is not described but the tolerance on the gauge at 70 psi is given as ±2 psi. m
 - is 36 Sensor is a pressure switch. Then turn-on threshold (decreasing pressure) is listed on sheet 1. The turn-off threshold (increasing pressure) psi. The color of the warning light is not described. Pages 9-44 & 45 of TM 55-1520-228-23-1 also indicate high pressure turn-on and turn-on thresholds, for helicopters prior to S/N 72-21061. These helicopters presumably do not have analog pressure indicating systems.
 - The only reference to a turn-on/turn-off threshold which could be found was in the Operator's Manual, page 2-21. The color of the warning light is also not described. ŝ
 - 6. Sensors are the same as those described for the engine chip detection system.

SUBSYSTEM PARAMETER DATA LIST

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Table: ∪+

HELICOPTER: 0H-58C

SUBSYSTEM: Hydraulic

SUBSTSIEM: Mydraulic	lic							She	Sheet No.: 1
Pater Carry		INDICATOR	8				PARAMETER	-	
INDICATOR LABEL	TYPE	RANGE	MARKINGS UNITS MODE MODE	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	REFERENCES (TM 55-1520-235)	NOTE #
Hydraulic Pressure - HYD PRESS	Caution	ı	Amber	psi	All	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	-10, pp 2-20 & 29 (TM 55-1520-228) (TM 55-1520-228) (A 55-1500-228) (A 55-1500	-10, pp 2-20 & 29 (TM 55-1520-228) -23-1, pp 7-9, 25, 23-2, pp 5-27 & 65	-

Table: C4 (Hydraulic - Cont'd)

NOTES:

1. Sensor is a pressure switch which provides a grounding path to connector P64M on the caution panel. The threshold of 300 psi is for switch closure on decreasing pressure. The increasing pressure, (switch open) threshold is 400 psi.

SUBSYSTEM PARAMETER DATA LIST

Table: C5

HELICOPTER: OH-58C

SUBSYSTEM: Electrical	ical							Shee	Sheet No.: 1
2012		INDICATOR	3 6		-		PARAMETER	0	* 1100
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-235)	(SH 7)
DC Generator Load -	Circular Dial	0-150	(140)R	Amps	All	140	Maximum - none specified		
AMPS DC		i						-10, p 2-26, 29 & 5-2	,
DC GENERATOR	Caution Light	:	Amber	1	Gen sw ON Gen Field Circuit breaker in	Gen sw Generator voltage ON Gen Field <(18 ±1.8) VDC circuit or 2(32 ±1) VDC breaker in	Cautionary - none specified	-23-1, pp 8-40 & 9-6/7 -23-2, pp F-21, 27, 55 -8 65	-
115 VAC Bus Power – INST INVERTER	Caution Light		Amber	:	A11	No AC power on Bus Cautionary - none specified		-10, pp 2-26 & 29 (TM 55-1520-228) -23-1, pp 9-49 & 50 -23-2, pp F-17 & 51	2
DC Ammeter Power Overdraw – AMM	Tripped Crct Brkrs (2)	;	5		IIA	>5 amps through the ammeter circuit			ю
Voltage Regulator Essential Bus Sensing Circuit Power Overdraw -			10	•	A11	>10 amps to cret from the 28 VDC Essential Bus			
Voltage Regulator Generator Reset Crct and Non Essential Relay Pur Overdraw - GEN & BUS	Crct Brkr		un	S dip	Gen sw ON, Gen- erator on line Gen sw to	>5 amps to the relay (K2) from the 28 VDC Essential Bus >5 amps to voltage regulator (same power source)		-10, pp 2-10, 24/20 -10, 25-1520-228) -23-2, pp F-27 & 65	4

Table: C5 (Electrical - Cont'd)

		INDICATOR	TOR			_	PARAMETER		
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-235)	(SH 7)
Inverter Pur Overdraw - INV PUR			ß			>5 amps to inverter from the 28 VDC Non Essential Bus			
Inverter Fail Relay (K10) Pur Overdram - AC FAIL RELAY	Tripped Crct Brkr		r.			>0.5 amps to relay from the 115 VAC BUS		-10, pp 2-10, cs 20 (TM 55-1520-228) -23-2, pp F-17 & 51	4
N2 Governor Control Actuator Pur Overdraw - GOV CONT			ဟ			>5 amps to actu- ator from the 28 VDC Essential Bus		-10, pp 2-10 & 24 (TM 55-1520-228) -23-1, p 9-18 -23-2, p F-23	
Auxiliary Pwr Receptacle Pwr Overdraw - AUX RECP	Sw Cret Brkr Tripped to OFF		10	Amps		>10 amps to receptacle from the 28		-10, pp 2-20, 24 & 26 (TM 55-1520-228) -23-1, pp 9-68/69 -23-2, pp F-21 & 55	\$
Engine Auto Relight System (1f installed) and/or Igniter Pur Overdraw - IGN ENG					Starter button pressed	>5 amps to systems from the 28 VDC Essential Bus		-10, pp 2-10, 16 & 24	
Starter Relay (K3), Voltage Regulator, Starter/Gen and Fuel Boost Relay (K16) Pur Overdraw -	Crct Brkr		o		Starter button pressed & Starter Lockout switch ON	Starter & to terminal A of button the starter/ the starter/ the starter/ starter voltage regulator, Lockout & to K16 from the switch ON 28 VDC Essential		(1M 55-15(0-228) -23-1, pp 9-53 & 54 -23-2, pp F-21, 41, 55 & 69	

Table: C5 (Electrical - Cont'd)

- 3.07	(SH 7)	ಪ თ	24 25	24	24	54	45		24
1	1.2 45-1520 235,	-10, pp 2-10, 16, 19 24 (TM 55-1520-228) -23-2, pp F-41 & 69	-10, pp 2-10, 15 & 24 (TM 55-1520-228)	-10, pp 2-10, 17 & 2 (TM 55-1520-228) -23-2, pp F-18 & 52	-10, pp 2-10, 17 & 3 (TM 55-1520-228) -23-2, pp F-18 & 52	-10. pp 2-10, 17 & 2 (TM 55-1520-228) -23-1, pp 8-18/18A -23-2, p F-54	-10, pp 2-10, 17 & 2 (TM 55-1520-228) -23-2, pp F-20 & 54	-10, pp 2-10 & 24 (TM 55-1520-228) -23-2, pp F-27 & 65	-10, pp 2-10, 19 & 2 (TM 55-1520-228)
PARAMETER	And the state of t								
۵	CONDITION	>5 amps to the pump from the 28 VDC Essential Bus	>5 amps to control from the 28 VDC Essential Bus	>5 amps to the sys- tem from the 28 VDC Essential Bus	>5 amps to the sys- tem from the 28 VDC Essential Bus	>5 amps to the indicator from the 28 VDC Essential Bus	>5 amps to sys- tem from the 28 VDC Essential Bus	>5 amps to sys- tem from the 28 VDC Essential Bus	>5 amps to system from the 28
ON TTA GTGG	MOU!	Starter button pressed or Fuel Boost Pump sw			LIA				
	1.11			<u>.</u>	Amps				
TOR.	85, 17 , 14.				1 0				_000000
INDICATOR	غوياكالخريه								
	TYPE				Tripped Crct Brkr				
DADA CTTO	INDICATOR LABEL	Fuel Boost Pump Pur Overdraw - FUEL PUMP	Engine Deice Control Pur Overdram – ENG DEICE	Gas Producer Tachometer Sys Pwr Overdraw - GAS PROD TACH	Rotor & Engine Speed Indicating Sys Pwr Overdraw -	Turbine Outlet Temp. Indicator Pur Overdraw - TURB OUTLET	Eng Oil Temp. Sys Pur Overdraw – ENG OIL TEMP	Eng Oil Bypass Relay (K4) & Valve Pwr Overdraw -	Fuel Indicating Sys Pwr Overdraw -

Table: C5 (Electrical - Cont's)

NG. 1	13					r.			7
, 70 , 10 , 10 , 10 , 10 , 10 , 10 , 10 , 1	(00-00-00	-10, pp 2-10, 20 8 24 (TM 55-1520-228) -23-1, p 9-36 -23-2, p F-26	-10, pp 2-10, 20 & 24 (TM 55-1520-228) -23-1, p 9-34 -23-2, p F-26	-10, pp 2-10, 21 & 24 (IM 55-1520-228) -23-1, pp 8-41/43 -23-2, p F-63		-10, pp 2-10, 22 & 24 (TM 55-1520-228) -23-1, pp 9-67 & 68 -23-2, p F-25		-10, pp 2-10, 20 8 24	-23-2, p F-59
PARAMETER	1.0011110 C								
	CONDITION	>5 amps to brakes from the 28 VDC Essential Bus	>5 amps to solen- oid from the 28 VDC Essential Bus	>1 amp to the sys- tem from the 28 VDC Essential Bus	>5 amps to heater from the 28 VDC Essential Bus	System activated >5 amps to solen- by Switch oid from the 28 Crct Brkr VDC Essential Bus	>5 amps to blow- ers from the 28 VDC Non Essential Bus	>5 amps to DISENG light & electro- mechanical control disconnects from the 28 VDC Essen- tial Bus	>5 amps to control relay & possible JAM light & time delay relay, from same source as
OPERATING	برالس		All			System activated by Switch Crct Brkr		Pri Dir Contr sw at DISENG	Pri Dir Contr sw at ENGAGE
	1 10N1TS				Amps				
3 6	MARYINGS	S		1			u	n	
INDICATOR	PANGE								
	TYPE		Tripped Crct Brkr			Sw Crct Brkr Tripped to OFF		Tripped	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
PARAMETER NAME.	INDICATOR LABEL	Force Trim Magnetic Brake(s) Pur Overdraw -	Hydraulic Bypass Solenoid Pur Overdram - HYD BOOST SOL	Xmsn Oil Pressure Indicating Sys Pur Overdraw - XMSN OIL PRESS	Pitot Tube Heater Pur Overdraw - PITOT HTR	Heater Solenoid (L2) Pur Overdraw -	Defog Blower Motors Pur Overdraw - DEFOG & VENT	Primary Direction Anti-coque Sys	PRI DIR CONTR

Sheet No.: 5

Table: C5 (Electrical - Cont'd)

NOTE # (SH 7) 9 -10, pp 2-10, 17, 24 & 28 (7M 55-1520-228) -23-1, p 8-10 -23-2, pp F-27 & 65 PEFERENCES (TM 55-1520-235) CONDITION TYPE - DURATION PARAMETER 515 amps to lights from the 28 VDC Essential Bus >3 amps to PSI & 2 only from the 28 VDC Essential Bus >5 amps to lights from the 28 VDC Essential Bus >20 amps to system from the 28 >5 amps to sys-from the 28 VDC Essential Bus >3 amps to all devices (same power source) CONDITION Power source unknown OPERATING MODE Nvg/Norm Lgt sw at NVG Nvg/Norm Lgt sw at NORM Ē MARKINGS | UNITS Amps Unknown Z, 15 m 20 INDICATOR RANGE Tripped Crct Brkr TYPE Landing Light Relays (K8 & K9) & Lamps Pur Overdraw -Rpm Sensors (518 & 91), Audio Marning Device (PS17), Caution Panel Per Supply Instrument Light
Pwr Supplies
(PS1 & 2), Night
Vision Goggles
Relay (K18) &
Caution Lgt
Relay (K19) Pwr Landing Light Control Sys Pwr Overdraw -Position Lights Pwr Overdraw -Anti-Collision Lights Pwr Overdraw -ANTI COLL LTS PARAMETER NAME-INDICATOR LABEL CAUTION PNL LTS LDG LT CONT & Dimming Control Pwr Overdraw -LDG LT PWR Overdraw -INST LTS POS LTS

C5 (Electrical - Cont'd)

Table: C5 (Electrical - Cont'd)	rical - Cont'	q						Shee	Sheet No.: 6
SABARCTED LANG		INDICAT	470R		CHITTEGRA		PARAMETER		1
INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	MODE	CONDITION	CONDITION TYPE - DURATION	(TM 55-1520-235)	(SH 7)
Night Vision Goggle Voltage Regulator (VR2) Pwr Overdraw -					Nvg/Norm Lgt switch	Nvg/Norm >5 amps to voltage Lgt regulator from the switch 28 VDC Essential			
NVG VR					at NVG	gns			
Console Switches & Equipment Lgts Pwr Overdraw -	Tripped					>5 amps to lights from the 28 VDC		-10, pp_2-10, 24, 25,	
כאר רג	רוכנ פווצו		u	Amps		Essential Bus		(TM 55-1520-228)	
Cockpit Utility Lgt Pwr Overdraw -			n			>5 amps to light from the 28 VDC Non		-23-2, pp 9-55/5/ 4 /8 -23-2, pp F-29, 61 &	
COCKPIT LTS						Essential Bus			
Signal Light Receptacle Pwr Overdraw -			01			>10 amps to voltage regulator from the 28 VDC Essential			7
SIGNAL LT	!					SUS			

NOTES:

- 1. Sensor is the Voltage Regulator VR1 which energizes the Generator Fail Relay (K11). This relay provides a path to ground at connector P64L on the caution panel.
- 2. Sensor is the Inverter Fail Relay (K10) which is held open by power from the AC Bus. When bus power fails, relay contacts provide a path to ground at connector P64K on the caution panel.
- 3. The Operator's Manual specifies three circuit breakers protecting the ammeter. However, the circuit diagram in the last reference shows only two.
- Circuit breakers are not assigned unique designator numbers on the helicopter. Designators which are used (e.g., CB7, CB5, etc.) are applied to more than one breaker (see TM 55-1520-228-23-2, Appendix F for examples). All circuit breakers are on the overhead breaker panel unless otherwise specified.
- 5. The combination switch and circuit breaker is located on the overhead console control panel.
- Since the most recent changes have not been supplied to General Electric for all of the technical manuals on hand, Figure F-37 for TM-1520-228-23-2 is not available, even though it is referenced in TM 55-1520-228-23-1. Thus the current rating and bus connection for the LDG LT CONT circuit breaker is not known. •
- TM 55-1520-235-10 (0M-58C Operator's Manual) p. 2-10 shows this circuit breaker rated at 7.5 amperes, but TM 55-1520-228-10 (0M-58A Operator's Manual) and TM 55-1520-228-23-2, p. F-67 both indicate a 10 ampere rating. It was assumed that the last manual had the most accurate information since it is a maintenance manual, but it is possible that the correct rating is 7.5 amperes. .

SUBSYSTEM PARAMETER DATA LIST

Sheet No.: 1

Tatie. 36

HELICOPTER: 0H-58C

SUBSYSTEM: Miscellaneous

NOTE # 2 -10, pp 2-8/9 & 20 (TM 55-1520-228) -23-2, pp 11-29, 56 & F-59 REFERENCES (TM 55-1520-235) CONDITION TYPE - DURATION Advisory - none specified Advisory - none specified PARAMETER Pedal force on primary control system is 250 lbs. Electromechanical
Control disconControl disconSwitch at activated, disDISENG abing the primary anti-torque
system CONDITION OPERATING MODE Pri Dir Contr Sw in the ENGAGE position RANGE | MARKINGS | UNITS ł ŀ INDICATOR ; Advisory Light TYPE Primary Directional Anti-Torque System Jammed -PARAMETER NAME-INDICATOR LABEL Primary Directional Anti-Torque System Disengaged -DISENG ₹,

Table: C6 (Miscellaneous - Cont'd)

MOTES:

1. Sensors are two electromechanical control disconnects at opposite ends of the anti-torque system. Each has tension and compression switches which supply power to the JAM light through a 1/2 second time delay network.

2. Sensors are the same as those above, except that the path to ground for electrical power which activates the light is provided by a set of relay activated contacts on each disconnect. The relays are activated by placing the Pri Dir Contr switch at DISENG. A control relay (J517) is used to control electrical paths as a function of the switch position.

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SUBSYSTEM PARAMETER DATA LIST FOR THE YAH-64

SUBSYSTEM PARAMETER DATA LIST

Sheet No.: 1

Table: 01

HEL ICOPTER: YAH-64

SUBSYSTEM: Engine

NOTE (SH 5) 1,2,5,6 1,2,5,9 1,4,7 1,10 1,8 1,8 pp 6-52, 7-8, 12, 13, 16-3 & 20 (PS 14-11017C) pp 6, 9 & 15 (PS 14-11021B) pp 10, 12 & 18 (TM 55-1520-238) -10, pp 5-2, 8-27 & 9-4 pp 6-52, 7-8/11, 16-3 & 20 (PS14-11017C) pp 6, 10 & 14 (TM 55-1520-238) -10, pp 5-3 & 9-4 REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE) - DURATION minutes - transient Maximum (for applying rotor brake) - none specified Maximum - 12 seconds Maximum - continuous seconds - continuous - continuous none Cautionary - none specified . 3 CONDITION TYPE - 12 Cautionary specified Cautionary Cautionary Maximum Normal Normal 9 CONDITION 98-100 99-105 <(93 ±5) 67-99 90-90 8 113 105 20 (63 OPERATING MODE Eng 1 (2) Power Lever(s) in FLY position Eng 1 (2)
Power
Lever(s)
in FLY
position Engines Shut-down, Rotor Brake sw to ON = All (See Note) UNITS Segments.. (40)6 (94-98)A (94-98)A (100-104)A (104-120)R Stripes... (20-40)A (60-90)A (100-104)A Segments.. (40)G (0-62)R (62-102)G (102-105)A (105-120)R Stripes... (102-105)A Red dot to indicate selected parameter MARK I NGS Ž Red ŀ ; INDICATOR RANGE 0-120 0-150 0-999 : 1 Tone in ICS (P & CPG) Segmented Vertical Light Bar W/Digital Readout (P) Warming Lgts (2; P & 2; CPG) Warning Lgts (2; P & 2; CPG) Tone in ICS Selectable Digital Display (CPG) Segmented Vertical Light Bar (part of Engine/ Rotor Tachometer P & CPG) TYPE ENG-RTR RPH X Np 1(2) MG RPM \$ 1 (2) NG % RPM/LEFT (RIGHT) ENG 1 (2) OUT PARAMETER NAME-INDICATOR LABEL ş Engine Power Turbine Speed -Engine Gas Producer Speed ENG 1 (2)

30 20

Table: D1 (Engine - Cont'd)

		INDICATOR	70K		_		PARAMETER	OFFEDENCES	
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	(STUDENT MANUAL: EDT-3 TRNG CRSE)	NOTE # (SH 5)
Engine Turbine Gas Temperature -	Segmented Vertical	0001	Segments (<0)G (0-775)G (775-840)A		Starting engine Ng <67%	810	Maximum - transient		
1GT °C × 100 1 (2)	w/Digital Readout (P)		Stripes (775-840)A Red Diamond at 880		Engine shut- down (after	300	Maximum - transient	20 6.34 E2 # 7.14/1E	
				ာ့	start)		:	(PS14-11017C)	1001
TGT "C/LEFT	Selectable	_	Red dot to			0-775	Normal - continuous	(TM 55-1520-238)	
	Display	666-0	selected			775-850	Cautionary - 30 minutes	0-6 5 61-0 °C-0 dd	
	9		parameter		เานกกาล	850	Maximum - transient		
						988	Maximum - 12 seconds		
				:	Engine shut- down (in flight)	540	Maximum - transient		
Engine Torque -	Segmented		Comment		Dual	0-100	Normal - continuous	21 0 31 2 63 9 55	
TORQUE \$ 1 (2)	Light Bar	120	9(0×) 9(0×)	•	רוואווב	100	Maximum - continuous	(PS14-11017C)	
	Readout (P		(100-120)R	•	Single	0-110	Normal - continuous	(TM 55-1520-238)	71464741
			3.			110	Maximum - continuous	-10, p 3-1	

Sheet No.:

(Engine - Cont'd)

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Table:

1,3,14,15 1,2,5,16 NOTE # 1,2,5,13 1,3,17 pp 6-52, 7-22/24, 16-9

16

(PS14-11017C)

pp 6, 7, 9, 14 & 16

(PS14-11021B)

pp 8, 11, 17 & 18

(TM 55-1520-238)

-10, p 5-4 pp 6-52, 7-18, 16-8 & 16 (PS14-11017C) pp 6, 7, 10, 11, 13 & 16 (PS14-11021B)
pp 8 4 11
(TM 55-1520-238)
-10, pp 5-4, 8-2 & 26 REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE) CONDITION TYPE - DURATION Cautionary - unspecified Cautionary - 5 minutes Cautionary - transient Cautionary - transient Minimum - continuous Normal - continuous Maximum (except on start) - continuous Maximum - transient Normal (Ng >85%) continuous Idle (Ng <85%) continuous PARAMETER CONDITION ₹(20-25) 35-135 135-150 45-100 92 25-45 52 ×100 150 <u>≥</u>135 OPERATING MODE Engine start, power lever at Idle Engine running A] 41 UNITS ပူ psi Segments.. (40)G (20-40)A (40-100)G (100-120)A (110-220)R Stripes... (20-40)A (100-120)A Segments.. (<-60)G (-60-30)A (30-135)G (135-150)A (150-160)R Stripes... Red dot to indicate selected parameter Red dot to indicate selected parameter MARK I NGS Amber Amber INDICATOR - 999 -60 - 160 RANGE 0-220 0-999 8 Caution Lgts (2; P) Caution Lgts (2; P) Selectable Digital Display (CPG) Selectable Digital Display (CPG) Segmented Vertical Light Bar (P) Segment Vertical Light Bar (P) Caution Lgts (2; CPG) Caution Lgts (2; CPG) TYPE 01L PRESS ENG 1 (2) ENG 011 °C X 10 1 (2) PARAMETER NAME-INDICATOR LABER ENG 01L PSI) **9** Engine 011 Temperature Engine Oil Pressure -ENG 1 (2) ENG OIL PSIALEFT (RIGHT) ENG 1 (2) 01L HOT | (2) ENG OIL *CALEFT (RIGHT)

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Table: 01 (Engine - Cont'd)

		INCION	34706			~	ALAME FER		
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE DURATION	(STUDENT MANUAL: LDT-3 TPNG CRSE)	NUTE # (SH 5)
Engine Oil Filter Differential Pressure -	Caution Lgts (2; P)				7			٠	
01L FTR BYP ENG 1 (2)			Amber	psid	ILIA	2(60-80)	Cautionary - translent		1,3,18
ENG 1 (2)	Caution Lgts (2; CPG)							pp 7-19/20, 16-8, 9 416 (PS14-11021R)	
Engine Powertrain Integrity - CHIPS ENG 1 (2)	Caution Lgts (2; P)		Amber	1	A11	Sensor contacts grounded by metal	Cautionary - transient	pp 8, 11, 17 & 18	1,3,19
ENG 1 (2)	Caution Lgts (2; CPG)	į				engine			
Engine Anti-Ice Bleed Air (GE) Valve Position - ENG I (2)	Advisory Lgts (2) on Pilot's Amti-Ice Control Panel		:	1	All	No power to valve	Advisory – none specified	pp 6-44/45 & 15-2/5	1.20
Engine Nose Gearbox/Cross Shaft Fairing Anti-Ice Heating Blanket Temp ANTI-ICE HOT	Caution Lgts (1; P & 1; CPG)		Amber	٩.	All	(\$∓ 0\$1)₹	Cautionary - none specified	pp 15-6/8, 16-12 8 17 (PSI4-11021B) pp 8, 9, 11, 17 8 18	1,3,21
Engine No. 1 Inlet Ice Formation -	Caution Lgt (P)		Amber	1	All	Ice formed on detector probe	Cautionary - none specified	p 16-8 (PS14-11021B) pp 8, 12 & 17	1,20,22
Engine Chop Collar Position - ENGINE CHOP	Warning Lgts (1; P å 1; CPG)		Red	1	A11	Engines chopped to idle by	Advisory – none specified	pp 7-6, 7 & 16-3/4	1,3,7
	Tone in ICS CP & CPG		;			Crew member		pt 10, 11 & 10	

NOTES:

- 1. The terms "P" & CPG" refer to the Pilot's and Copilot/Gunner's crew stations, respectively. In the case of indicator lights, the number of lights at the particular crew station preceeds the crew station designation along with a semicolon.
- TM 55-1520-238-10 is a preliminary Operator's Manual, dated 31 May 1979, Much of the data which describes specific parameter conditions in conjunction with operating modes is yet to be supplied following flight testing. PS14-11017C is a Hughes Helicopter performance specification for engine, rotor and fuel quantity instruments, dated 10 Nov. 1977.
- 3. Sensor is a mechanical switch which has a closed (fault condition) resistance of 10 ohms maximum and an open resistance of 2 megohms minimum. The maximum voltage and current with the switch closed are 0.1 VDC and 5-7 milliamperes respectively, while the switch open values are +5 to 30 VDC (posimum voltage and current with the switch closed are 0.1 VDC and 5-7 milliamperes respectively, while the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values with the switch open values are +5 to 30 VDC (posimum voltage and current with the switch open values with the switch open voltage and the switch open values with the switch open values with the switch open value with the switch open value with the switch open value with the switch open values with the switch open value with the switch open va tive) and 25 microamperes respectively.
- and 25 Sensor is a solid state switch which, when closed (turned on - fault condition), allows the light circuitry to see a maximum of +0.5 VBC 5-10 milliamperes (max). When the switch is open, the voltage at the light circuit is 5-30 VBC (positive) with a maximum current flow of microamperes.
- The indicator light segments are colored red (R), amber (A) or green (G). As the parameter value passes from one color range to the next, the preceeding range disappaars as the first segment in the new color range lights up. Since the only indication of impending operation in a red or amber zone is by remembering where these zones begin and/or the green zones end, the manufacturer has also placed stripes alongside of the light bars, to indicate amber segment ranges plus possible transfent operating zones which are shown as red segments on the instrument itself. ŝ
- The indicator accuracy is within 1% full scale. The sensor is a tachometer generator producing a single phase ac square wave with pulse widths of 200 ±50 microseconds and peak to peak voltage of 4.0 ±0.2 volts over a full speed range of 6,000-25,000 rpm. The pulse frequency at 20,952 rpm (100% Np) is 1396.76 Hz with no error. When torque is increased from a zero load condition, every other pulse will experience a shift in phase from its epoch yaive of up to 20%. Total load impedance presented by both indicators to an individual rpm sensor is a minimum of 20% ohms resistance and a maximum of 0.004 microfarads capacitance.
- 7. The warning lights flash at a 2 ±1 Hertz rate until the master caution light is pressed, at which point the lights are steadily illuminated, for that particular crew station.

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- The aural tone is a 700-1700 Hz sweep tone which can be reset from either crew station by pressing the corresponding warning light.
- 9. Indicator inaccuracy is ±1% of full scale. Sensor is a tachometer generator producing a single phase, 2½p-p signal at 2235 rpm increasing to 75 Vp-p at 44,700 rpm. Signal frequency is 2135.7 Hz at 44,700 rpm (100%). Minimum resistive load presented to sensor by both indicators is 10% ohms, and maximum capacitive impedance load presented to the sensor is 0.01 microfarad.
- 10. Warning lights are the same as those described for the power turbine speed.
- The starting limit Ng condition is a best guess, since the Operator's Manual specifies "idle speed" but does not say what that is. The pilot's indicator has that accuracy over the 501°C to 1000°C range, and it is accurate to ±10°C from 0°C to 500°C. Sensors consist of seven alumel-chromel thermocouples in each engine. Signal levels are in accordance with NBS-CIRC-561 Table 6, March 1974, Thermocouple Reference Table. The thermocouple network maximum resistive impedance is 690 ohms. The minimum indicator load impedance is
- The indicator accuracy is ±1% over the full range. Torque signal scale factor is 1.0 VDC/100 ft-lbs of torque, with a 0.25V_{D-D} maximum ripple at a frequency of 333 Hz for an Np speed of 10,000 rpm. If the Np speed is doubled, the maximum ripple decreases to 0.1V_{D-D} at 660 Hz. For single engine operation, the normalized 100% torque equates to 391 foot-pounds of actual power turbine shaft torque. The normalized 100% value for dual engine operation equates to 709 foot-pounds engine power. (This may in fact be total power from both engines, but this is not so stated in the procurement specification.) Total indicator load resistance is at least 100% obms. 12.

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MOTES (Cont'd):

- Manual is 0-120 psi and the markings are more in line with operating limits (for the same engine) which are detailed for the Uil-604. Since the procurement specification was obtained directly from Hughes Helicopters it is presumed that that document contains the most current information on the actual indicator. The sensor is a pressure transducer producing a dc voltage which varies linearly from 0 to 5 (\pm 0.025) volts for a pressure range of to 220 psig. The maximum signal ripple is 20 millivolts peak-to-peak. The transducer requires an excitation signal of 28 \pm 4 VDC, 50 milliamperes maximum. The output impedance of the transducer is less than 1 ohm. The 0-220 psig range corresponds to 2.5 to 97.5% (\pm 2.5%) of the full scale range of the first of the detailed references. 13. The indicator markings used are based on those in the student manual and procurement specifications. The indicator range shown in the Operator's
- The increasing pressure (switch open) threshold given in the first reference is 23-28 psi. However, the Operator's Manual indicates this threshold is 35-40 psi (p 8-21). The 23-28 psi threshold is more likely, since it is consistent with the turn on threshold. The turn on threshold is itself consistent with the minimum continuous analog signal condition (25 psig). ¥:
- dated 25 Oct 1977, 15. PSI4-11021B is a Hughes Helicopter procurement specification for the caution and warning displays,
- Sensor is part of a combined switch and analog transmitter unit, where the switch operates the 01L HOT caution lights. The analog transmitter is MS28034-3 resistance bulb. The indicator accuracy is $\pm 3^{\circ}$ C. 16.
- The turn-off (decreasing temperature) switch threshold is 118°C.
- The turn-on, turn-off thresholds are both within the 60-80 psid range. Light indicates filter bypass is pending. 18.
- Exact chip detector sensor operating mechanism is not described but suspect a magnetic plug to attract and hold ferrous metal particles close to the switch contacts, thereby creating a path to ground. 19.
- Sensor type and operating mode information is not contained in the available literature. 20.
- 21. The decreasing temperature (light turn-off) threshold is 140° ±5°F.
- Light is activated by a 28 VDC signal from the sensing device to the caution/advisory panel. In the high stage, the fault signal source output voltage is 16-30 VDC with load currents of 5 milliamperes to 10 milliamperes respective. The rise time is from 1 to 20 microseconds. In the no fault case (low state) the output voltage is 0-0.5 VDC. 25.

HELICOPTER: YAH-64

SUBSYSTEM: Fuel

Sheet No.: 1

Table: D2

NOTE # (SH 3) 1,3,4, 6,7 1,3,5,8 1,4,5 2,9 pp 4-6, 8, 12, 14, 16-10 & 17 (PS14-11017C) pp 6/8, 10, 11 & 16 (PS14-11021B) pp 8, 9, 11, 17 & 18 pp 7-26/27, 16-9 & 16 (PS14-11021B) pp 8, 9, 11, 17 & 18 88 pp 4-2, 3 & 14 (TM 55-1520-238) -10, Fig I-1, View BE REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE) Cautionary - none - specified. (However this gives about a 30 minute reserve at cruise power) CONDITION TYPE - DURATION Advisory - unspecified Cautionary - none-specified (see note above) Normal - continuous Cautionary - none specified Engine fuel line pressurized 0-(210 ±10) Fwd 0-(245 ±10) Aft <(210 ±10) Fwd <(245 ±10) Aft CONDITION (210 ±10) 981.5 Fwd (245 ±10) 1417 Aft 27.5 OPERATING MODE Boost
pump ON
(Boost
Pump sw
or Eng.
Start sw
ON) A] A] ٤ UNITS psid <u> 1</u> 1bs : Fwd Segments.. (0-10)R (10-20)A (20-100)G Aft Segments.. Segments.. (0-10)R (10-20)A (20-140)G Red dot to indicate selected parameter MARK I NGS Amber Green Green INDICATOR RANGE 6-1400 0-1400 0-999 1 1 Caution Lgts (2; P) Selectable Digital Display (CPG) Caution Lgts (2; P & 2; CPG) Segmented Vertical Light Bar W/Digital Readout of Total Fuel Discrete Light on Pilot's Fuel Control Panel Caution Lgts (2; CPG) TYPE FUEL QTY LBS X 10/FMD (AFT) Fuel Qty, Fwd & Aft Tanks -PARAMETER NAME-INDICATOR LABEL FUEL LB X 10 FND (AFT) FUEL LOW FIND (AFT) FUEL FTR BYP ENG 1 (2) Engine Fuel Filter Differential Pressure -Boost Pump Pressure -ENG 1 (2) **E**

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Table:

		INDICAT	1TOR		_		DADAMETER	_	
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	HINTIG	OPERATING	ACT TT GWOO	במינים בביים ביים ביים ביים ביים ביים ביים	◆ REFERENCES (STUDENT MANUAL:	NOTE #
				,	ואמר		CONDITION LIPE - DURALION	EUT-3 TRNG CRSE)	(SH 3)
Transfer Refueling Valve Caution Lgt Position - (P)	Caution Lgt (P)		Amber	:	A11	Valve is open (commanded by switch on	Advisory - none	pp 4-7, 13 & 19	1,4,5,
REFUEL VALVE						refueling panel)		pp 8, 11 & 17	3
Fuel Qty. External Tanks - Caution Lgt	Caution Lgt							. 16-11	
EMPTY EXT TANKS	 E		Amber	न्	A11	Tanks empty	Cautionary - none specified	(PS14-11021B) pp 8, 11 & 17	1,4,5
Engine Fuel Pump Pressure -	Caution				1	Low output pres-		(PC14_11021R)	3 7 1
FUEL PRESS ENG 1 (2)	Lgts (2; P)		Red	psi	H .	sure on engine driven fuel pump	Warning - none specified	pp 8, 11 & 18	11,13,

Table: D2 (Fuel - Cont'd)

MOTES:

- 1. The terms "P" & "CPG" refer to the Pilot's and Copilot/Gunner's crew stations, respectively. In the case of indicator lights, the number of lights at the particular crew station preceeds the crew station designation along with a semicolon.
- 2. TN 55-1520-238-10 is a preliminary Operator's Manual, dated 31 May 1979. Much of the data which describes specific parameter conditions in conjunction with operating modes is yet to be supplied following flight testing.
- 3. PSI4-11017C is a Hughes Helicopter performance specification for engine, rotor and fuel quantity instruments, dated 10 Nov. 1977.
- 4. PS14-110218 is a Mughes Helicopter procurement specification for the caution and warning displays, dated 25 Oct 1977.
- Sensor is a machanical switch which has a closed (fault condition) resistance of 10 ohms maximum and an open resistance of 2 megohms minimum. The maximum voltage and current with the switch closed are 0.1 VDC and 5-7 milliamperes respectively, while the switch open values are 5 to 30 VDC (positive) and 25 microamperes respectively. ŝ
- The indicator light segments are colored red (R), amber (A) or green (G). As the parameter value passes from one color range to the next, the praceeding range disappears as the first segment in the new color range lights up. •
- Imaicator accuracy depends on flight attitude. For all indicators the accuracy is 2% of indicated value plus 1% of full scale value, for sustained flight attitudes. For normal flight attitudes, accuracy is 1% of full scale. Sensors are capacitance type probes, two in the forward cell and one in the aft call. The signal parameters are not specified in the available references, but may be shown on Hughes Helicopters drawings 7-211642077 and 7-211642076. These drawings were not available to GE. .
- The actual low level detection is accomplished with thermistor bead type sensors on a fuel quantity probe in each tank. The signal from the beads activates a mechanical switch. The switch presumably would have the resistance characteristics specified in note 5 above, yet PSI4-11017C indicates an open switch resistance of 500-650 ohms. Cl rification would be required prior to designing an interface to that circuit. æ
- Sensor type and signal path not specified in available literature. Altitude limit for "boost pump out" operation is not above 10,000' pressure altitude. ď,
- 10. Valve provides a shunt path around the transfer pump.
- No other references mention monitoring this parameter, yet all the pictures of the pilot's caution panel show these segments. If the engine fuel pressure is lost, the engine will flame out. However, no reference indicates at what fuel pump pressure an actual flame out occurs, or at what prespressure is lost, the engine w sure the lights are activated. :

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SUBSYSTEM PARAMETER DATA LIST

Table: 03 Sheet No.: 1

HELICOPTER: YAN-64

SUBSYSTEM: Powertrain

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	NOTE #			6,9			1,5,7	1,5,8	1,5,7	1,5,8			1,3,4,		
	REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE)					pp 9-14, 16-3, 5 & 20 (PS14-11017C)	pp b, 8, 10 & 15 (PS14-110218) pp 10, 12, & 18 (TM 55-1520-238)	-10, p 5-2					pp 9-14, 18, 24, 25, 16-10 & 17 (PS14-11021B)	pp 8, 9, 11, 17 & 18	•
PARAMETER	CONDITION TYPE - DURATION	Minimum - continuous	Normal - continuous	Maximum - continuous	Normal - continuous	Maximum - 10 seconds	Warning - none specified		Warning - none specified				Cautionary - none speci- fied (but see note 10)		
	CONDITION	3 5	94-104	104	94-104	115	<90.3		>104				(24 82)∑		
	OPERATING MODE		Powered	5	Autoro-	100			<u> </u>				Al		
	UNITS					•	4						psi		
5 5	MARKINGS		Segments.	3 (S (S (S (S (S (S (S (S (S ((104-120)R		Red		Red				Amber		
INDICATOR	RANGE			0-120								•			
	TYPE	Segmented	Light Bar	Engine/	Tachometer		Warning Lgts (1; P & 1; CPG)	Tone in ICS (P & CPG)	Warning Lgts (1; P & 1; CPG)	Tone in ICS (P & CPG)	Caution Lgts (2; P)		Caution Lgts (2; CPG)	Caution Lgt (P)	
	PARAMETER NAME- INDICATOR LABEL	Main Rotor	A MOG ALE SHE	4			LOW RPM ROTOR		HIGH RPM ROTOR		Main Transmission Oil Pressure (Galleries 1 & 2) -	OIL PRES IN XMNS 1 (2)	MAIN XMSN 1 (2)	Main Transmis- sion Accessory Gearbox Oil Pressure -	OIL PRES ACC PMP

Sheet No.: 2

Table: D3 (Powertrain - Cont'd)

		INDICATOR	8		_	_	PARAMETER		
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE)	NOTE #
Hein Transmis- sion Oil Temp. (Galleries I & 2).	Caution Lgts (2; P)								
01L TEMP MM XMSN 1 (2)			Auber	<u></u>	A11	<u>></u> (284 ±10)	Cautionary - none specified		1,3,4,
MAIN XIGN 1 (2)	Caution Lgts (2; CPG)							pp 9-14, 18, 24, 25,	
Main Transmis- sion Oil Qty (Galleries I & 2) -	Caution					Oil quantity in		(PS14-110218) pp 8, 9, 11, 17 & 18	
01L LOW MN XMSN 1 (2)	Lgcs (2; P)		Amber	!	LIA	affected gallery sufficiently low so as to cause	Cautionary - none specified (but see		1,3,4,
MAIN XMSN 1 (2)	Caution Lgts (2; CPG)		,			diverter valve to close	note 12)		
Nose Gearbox Oil Pressure -									
OIL PRES NS GRBX 1 (2)	Caution Lgts (2; P)		Amber	ps₁	A11	((28 ±2)	Cautionary - none		1,3,4,
ENG 1 (2)	Caution Lgts (2; CPG)						Specified (but see note)	pp 9-6/9, 16-9 & 16	01
Nose Gearbox Oil Temp -								(PS14-110218) pp 8, 9, 11, 17 & 18	
01L HOT NOSE GRBX 1 (2)	Caution Lgts (2; P)		Amber	<u>.</u>	Ę.	∑(284 ±10)	Cautionary - none		1,3,4,
ENG 1 (2)	Caution Lgts (2; CPG)						Speci 7 1ed		=

Sheet No.: 3

Table: D3 (Powertrain - Cont'd)

		INDICATOR	æ				PARAMETER	REFERENCES	
TYPE RANGE	RANGE		MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	(STUDENT MANUAL: EDT-3 TRNG CRSE)	NOTE # (SH 4)
Caution Lgt (P)					•				
Caution Lgt (CPG)	·····		Amber	۳	All	(285 ±28)	/ - none	pp 9-36/39 & 16-10 (PS14-11021B)	1,3,4,
Caution Lgt (P)							Specified	pp 6, 12 & 1/	2
Caution Lgt (CPG)				* ** *	•				
Caution Lgts (1; P & 1; CPG)						Sensor contacts grounded by metal particles from main transmission			
Caution Lgts (2; P)			Amber	1	E W	Sensor contacts grounded by metal	Cautionary - none specified	pp 9-6/9, 14, 18, 24, 25, 36/39 & 16-9/17 (PS14-11021B)	1,3,4
Caution Lgts (2; CPG)						engine noise gearbox		71 8 1/	
Caution Lgt (P)			Amber	:	Engines OFF, NR <50%	Rotor brake sw	Advisory - none Specified	pp 9-28/29 & 16-19 (PS14-11021B)	
					All other modes	LOCK position	Cautionary - none specified	(TM 55-1520-238) -10, pp 8-19/21	15,3,

[able: D3 (Powertrain - Cont'd)

MOTES:

- 1. The terms "P" & "CPG" refer to the Pilot's and Copilot/Gunner's crew stations, respectively. In the case of indicator lights, the number of lights the particular crew station preceeds the crew station designation along with a semicolon.
- TN 55-1520-238-10 is a preliminary Operator's Manual, dated 31 May 1979. Much of the data which describes specific parameter conditions in conjunction with operating modes is yet to be supplied following flight testing. PS14-11017C is a Hughes Helicopter performance specification for engine, rotor and fuel quantity instruments, dated 10 Nov. 1977.
 - PSI4-110218 is a Mughes Helicopter procurement specification for the caution and warning displays, dated 25 Oct 1977.
- Sensor is a mechanical switch which has a closed (fault condition) resistance of 10 ohms maximum and an open resistance of 2 megohms minimum. The maximum voltage and current with the switch closed are 0.1 VDC and 5-7 milliamperes respectively, while the switch open values are 5 to 30 VDC (positive) and 25 microamperes respectively.
- can sink å Sensor is a solid state switch which, when closed (turned on - fault condition), allows the light circuitry to see a maximum of +0.5 VDC 5-10 milliamperes (max). When the switch is open, the voltage at the light circuit is 5-30 VDC (positive) with a maximum current flow of
- The indicator light segments are colored red (R), amber (A) or green (G). As the parameter value passes from one color range to the next, the preceeding range disappears as the first segment in the new color range lights up. Since the only indication of impending operation in a red or amber 20ne is by remembering where these zones begin and/or the green zones end, the manufacturer has also placed stripes alongside of the light bars, to indicate amber segment ranges plus possible transient operating zones which are shown as red segments on the instrument itself. ė
- The warning lights flash at a 2 ±1 Hertz rate until the master caution light is pressed, at which point the lights are steadily illuminated, for that particular crew station.
- The aural tone is a 700-1700 Hz sweep tone which can be reset from either crew station by pressing the corresponding warning light.
- Indicator has a full scale accuracy of 1%. The sensor consists of a magnetic pickup mounted adjacent to the rotor brake. The signal to the indicator is a single phase ac signal with no separation between the positive and negative components in each period. At 100% Mg, the signal frequency is 1348 Hz (376 microsecond pulse width) with an amplitude of 3V_{D-P}. At 120% Mg, the frequency is 1618 Hz (209 microsecond pulse width) with an amplitude of 3.5V_{P-P}. The total indicator impedance (both instruments) presented to the sensor is a minimum of 20% ohms resistive.
 - The light turn-off (increasing pressure) threshold is 45 psi. The actual analog pressure is possibly available on the multiplex bus. (Reference PSI4-11021B, p 9-24.) Due to incorporation of wicking, the transmission can run at reduced power for 1/2 hour after loss of oil pressure. <u>.</u>
- ll. Same as above except the light turn-off threshold is 254° ±10°F.
- 12. Available references do not specify what volume of remaining oil causes the diverter valve to close. Same time limit applies as in note 10 above.
- 13. The light turns off when the temperature goes below the maximum limit (but the number is not specified). The Fault Detection/Location Subsystem also monitors vibration (acceleration) levels in the gearbox. The CPG caution light illuminates for an overtemperature in either gearbox.
 - to the Exact chip detector sensor operating mechanism is not described but suspect a magnetic plug to attract and hold ferrous metal particles close switch contacts, thereby creating a path to ground. ₹
- 15. Light is activated by a 28 VDC signal from the sensing device to the caution/advisory panel. In the high state, the fault signal source output voltage is 16-30 VDC with load currents of 5 milliamperes to 10 milliamperes respective. The rise time is from 1 to 20 microseconds. In the no fault case (low state) the output voltage is 0-0.5 VDC.

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Table: 04

HELICOPTER: YAH-64

SUBSYSTEM: Hydraulic

pp 11-4, 8, 16-11 & 15 1,3,4,7 (PS14-110218)
pp 8, 9, 11, 17 & 18 (TM 55-1520-238)
-10, p 5-4 1,2,3,6 1,3,4,8 1,3,4,7 Sheet No.: 1 1,3,4,9 1,3,6 pp 11-16/18, 16-11 & 15 REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE) (PSi4-11021B) pp 8, 9, 11, 17 & 18 pp 11-6 & 16-11 (PS14-11021B) pp 8, 11 & 17 CONDITION TYPE - DURATION Maximum - continuous Maximum - continuous Normal - continuous Normal - continuous Cautionary - none specified Cautionary - none specified - none Cautionary - none specified Cautionary specified PARAMETER Oil down to low level mark in reservoir ₹ (60-80) CONDITION 3000-3250 3000-3250 <1250 3250 3250 **C1250** OPERATING MODE 0AT > (100° ±15°F) Al F A ... UNITS psi 1 psi (Unavail-able) (Unavail-able MARK I NGS Amber Amber Amber Amber INDICATOR RANGE 0-6000 0-6000 Caution Lgt (CPG) Caution Lgt (P) Caution Lgt (P) Caution Lgt (P) Caution Lgt (CPG) Caution Lgt (P) Semicircu-lar Gauge (shared w/Utility System) Semicircu-lar Gauge (shared w/Primary System) TYPE Primary Hydraulic Manifold Reservoir Fluid Qty -Primary Hydraulic Manifold Filter Differential Pressure -OIL PRESS PRI HYD Primary Mydraulic Pump Pressure -Utility Hydraulic Pump Pressure -PARAMETER NAME-INDICATOR LABEL OIL PRES UTL HYD OIL FTR BYP PRI HYD OIL LOW PRI **E E E** PRI HYD HYD UTIL שא בוט

Sheet No.: 2

Table: D4 (Hydraulic - Cont'd)

1,3,4,9 NOTE # (SH 3) 1,3,4,8 1,2,10 REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE) pp 11-20 & 21 (TM 55-1520-238) -10, pp I-3 CONDITION TYPE - DURATION Maximum - continuous Normal - continuous Cautionary - none specified Cautionary - none specified PARAMETER Oil down to low level mark in reservoir 3000-3250 **√(60-80)** CONDITION 3250 OPERATING MODE 0AT >(100° ±15°F) F MARKINGS | UNITS psi ; psi (Unavail-able Amber Amber INDICATOR RANGE 0-4000 Caution Lgt (P) Caution Lgt (P) Circular Gauge TYPE Utility Hydraulic Manifold Reservoir Fluid Qty -Utility Nydraulic Manifold Filter Differential Pressure -Utility Hydraulic Fluid Accumulator Pressure -PARAMETER INVE-INDICATOR LABEL OIL FIR BYP JTU 101 J10 UTIL ACC

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Table: D4 (Hydraulic - Cont'd)

MOTES:

- 1. The terms "P" & "CPG" refer to the Pilot's and Copilot/Gunner's crew stations, respectively. In the case of indicator lights, the number of lights at the particular crew station preceeds the crew station designation along with a semicolon.
- 2. TM 55-1520-238-10 is a preliminary Operator's Manual, dated 31 May 1979. Much of the data which describes specific parameter conditions in conjunction with operating modes is yet to be supplied following flight testing.
- PS14-11021B is a Mughes Helicopter procurement specification for the caution and warning displays, dated 25 Oct 1977.
- Sensor is a mechanical switch which has a closed (fault condition) resistance of 10 ohms maximum and an open resistance of 2 megohms minimum. The maximum wolkage and current with the switch closed are 0.1 VDC and 5-7 milliamperes respectively, while the switch open values are 5 to 30 VDC (positive) and 25 microamperes respectively.
- can sink Sensor is a solid state switch which, when closed (turned on - fault condition), allows the light circuitry to see a maximum of +0.5 VDC and 5-10 milliamperes (max). When the switch is open, the voltage at the light circuit is 5-30 VDC (positive) with a maximum current flow of 25
- Sensor and signal information is not contained in available references. Normal pump pressure is regulated to 3000 psi. Over pressure protection is provided by a high pressure relief valve in the manifold that cracks at 3500 psi and closes at 3300 psi.
- 7. The light turn-off (increasing pressure) threshold is 2050 psi.
- The light will not turn off until the filter has been removed, cleaned and restored.
- 9. Exact quantity remaining in reservoir for light activation not specified.
- 10. The parameter conditions/types are best estimates, based on those of the utility hydraulic system (see note 6 above.)

Sheet No.: 1

Table: 05

HELICOPTER: YAH-64

SUBSYSTEM: Electrical

1,3,5, NOTE # (SH 3) 1,3,5, 6 1,3,4 pp 8-10/17, 16-13 & 15 (PS14-110218) pp 8, 9, 11, 17 & 18 (Hughes Drawing) #7-211821004C pp 8-5, 8, 9, 18/21 & 16-13 (PSI4-110218) pp 8, 11 & 17 (Hughes Drawing) #7-211B21004C REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE) - DURATION Cautionary - none specified Cautionary - none specified CONDITION TYPE Not specified Not specified PARAMETER 1. Volts out >125
VAC, each phase
to ground, or
2. Volts out <90
VAC for more
than 15 seconds, or
3. Feeder current
>25 amps on
any phase Conditions 1 or 3 above or freq. out <380 Hz for more than 2 ±1 seconds CONDITION Not specified Not specified Door is open OPERATING MODE No weight on wheels Weight on wheels Ę A1 A] UNITS Amps Amps ; ŧ MARKI NGS Amber Amber None None INDICATOR RANGE 0-500 0-25 Caution Lgt (P) Caution Lgts (2; P) Circular Dial (P) Circular Dial (P) TYPE Transformer/ Rectifier Output Current -Generator Output Suitability -AC External Pwr Receptacle Door -DC AMP SYS 1 (2) PARAMETER NAME-INDICATOR LABEL KWA SYS 1 (2) Generator A Phase Feeder Current -GEN 1 (2) EXT PAR

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Sheet No.: 2

Table: D5 (Electrical - Cont'd)

NOTE # 1,3,4, 1,2,10 1,3,4, 1,3,4 1,3,4 pp 8-10/17, 16-13 & 15 (PS14-110218) pp 8, 9, 11, 17 & 18 (Hughes Drawing) #7-211821004C REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE) pp 8-14/i7 & 16-14 (PS14-11021B)
- pp 8, 11 & 17 (Hughes Drawing)
#7-211B21004C (Hughes Drawings) #7-211821004 #7-211811096 (TM 55-1520-238) -10, I-4 - DURATION Cautionary - none specified Cautionary - none specified Cautionary - none specified Cautionary - none specified CONDITION TYPE Low voltage on the respective AC bus or low volt-age on the respec-tive transformer/ rectifier output >20 amps to the charger from the #1 OC Essential Bus Low voltage on both AC busses or both transformer/ rectifiers spective trans-former/rectifier, from the respec-tive AC Essential >5 amps to the #1 & #2 contactors from the #2 & #1 OC Essential Bus-Battery not being charged ses, respectively >35 amps to the CONDITION (57 ±3) <u>≥</u>190 Bus OPERATING MODE Ξ A 3.3 F A] Ę UNITS Volts Amps ပူ ပူ ł MARK I NGS Amber Amber Amber Amber 33 ŝ 2 INDICATOR RANGE 1 ; ; Caution Lgts (2; P) Caution Lgt (CPG) Caution Lgts (2; P) Caution Lgt (P) Caution Lgt (P) Tripped Crct Brkrs (CBI & CB4; P) Tripped Crct Brkrs (CB2 & CB3; P) Tripped Crct Brkr (CB5; P) TYPE AC Essential Bus
B Phase or
Transformer/
Rectifier
Voltage
Suftability -Transformer/ Rectifier AC Pur Overdraw -Generator 1 (2) Contactor AC Bus Cross Tie Relay Pur Overdraw -HOT RECT 1 (2) PARAMETER NAME-INDICATOR LABEL FAIL ELEC SYS Battery Charger Status -Battery Charger Pwr Overdraw -XFNR RECT 1 (2) emperature -Transformer/ Rectifier Operating Battery Temperature -RECT 1 (2) GEN 1 (2) BATT CHGR HOT BAT CHARGER

Table: D5 (Electrical - Cont'd)

NOTES:

- 1. The terms "P" & "CPG" refer to the Pilot's and Copilot/Gunner's crew stations, respectively. In the case of indicator lights, the number of lights at the particular crew station preceeds the crew station designation along with a semicolon.
- TM 55-1520-238-10 is a preliminary Operator's Manual, dated 31 May 1979. Much of the data which describes specific parameter conditions in conjunction with operating modes is yet to be supplied following flight testing.
- 3. PSI4-11021 is a Hughes Helicopter procurement specification for the caution and warning displays, dated 25 Oct 1977.
- Sensor is a mechanical switch which has a closed (fault condition) resistance of 10 ohms maximum and an open resistance of 2 megohms minimum. The maximum voltage and current with the switch closed are 0.1 VDC and 5-7 milliamperes respectively, while the switch open values are 5 to 30 VDC (positive) and 25 microamperes respectively.
- Although this instrument is discussed by the first and third cited references, it is not mentioned or illustrated in the cockpit instrumentation diagrams available in the Operator's Manual. The minimum, maximum and/or normal operating ranges are not mentioned in the available references. 'n
- Sensing is accomplished using a transformer type coupling.
- 7. Sensing is accomplished using a resistive shunt.
- No light out (decreasing temperature) threshold is given. A hot condition is generally indicative of a transformer/rectifier cooling fan failure.
- The light turn off (decreasing temperature) threshold is 49° ±3°C. The light on condition also indicates that the battery charger is cut off (at 50° ±3°C battery temperature).

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10. System verification documentation is available only for those circuit breakers listed.

SUBSYSTEM PARAMETER DATA LIST

Table: 06

HELICOPTER: YAH-64

SUBSYSTEM: Miscel	Miscellaneous							She	Sheet No.: 1
		INDICAT	VTOR				PARAMETER		
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	(STUDENT MANUAL: EDT-3 TRNG CRSE)	NOTE #
Shaft Driven Compressor Discharge Pressure -	Caution Lgt (P)		Amber	psi	All	(17 7)>	Cautionary - none specified	pp 14-4, 5 & 16-2 (PS14-11021B)	1,3,6
SHAFT DRIVEN COMP								pp 8, 11 & 17	
Environmental Control Unit Output Air Temp	Caution Lgt (P)		Amber	.پر	All	(250 ∓50)₹	Cautionary - none specified	pp 15-32/33 & 16-2 (PS14-11021B) pp 8, 12 & 17	1,3,7,8
22									
Canopy Temp. and/or Canopy Anti-Ice Heating Element, Sensor & Controller Condition -	Caution Lgt (P)		Amber	1	Canopy Anti-Ice sw ON	1. Canopy temp. > 98° ±3°F, or 2. Sensor or heating element open or shorted, or	Cautionary - none specified	pp 15-10/12 & 16-12 (PS14-11021B) pp 8, 12 & 1/	1,3,5,9
ANTI-ICE HOT CANOPY									
Blade De-Ice Heater Time Schedule, Control Unit Temp., Ground Current Leakage and/or Heater Current -	Caution Lgt (P)		Amber	;	Blade De-Ice sw ON	1. Heater on/off ± 5% out of schedule, or 2. Control unit temp. >55°C, or 3. Ground current >1.5 amps, or 4. Heater current	Cautionary - none specified	p 16-13 (PS14-11021B) pp 8, 12 & 17	1,3,5,10
FAIL BLADE DE-ICE						+24% of nom- inal value			

Table: D6 (Miscellaneous - Cont'd)

	-	INDICATOR	.		_	••	PARAMETER		-
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE)	NOTE # (SH 4)
Canopy Door Condition - CANOPY	Caution Lgt (P)		Amber	:	A11	Either canopy door not closed	Cautionary - none specified	p 16-11 (PS14-11021B) pp 8, 11 & 17	1,3,4
Pitch, Roll & Yaw Stability Command Augmentation System (SCAS) Channels Operating Status - SAS	Caution Lgts (1; P & 1; CPG)		Amber	ŀ	All (ex- cept YAW channel disen- disen- gaged on ground by squat switch)	Channel(s) dis- engaged	Cautionary - none specified	pp 13-10/15 & 16-8 (PS14-110218) pp 8, 9, 12, 17 & 18	1,3,5,
Force Feel Sys Status - F FEEL	Caution Lgt (P)		Amber		Force Feel Sw ON	System inoperative	Cautionary - none specified		
Back Up Control Sys Status - BUC ON	Advisory Lgt (P)		Green	,	Not specified	System operative	Advisory - none specified	pp 11-12 & 16-8 (PS14-11021B) pp 8, 9, 12, 17 & 18	1,3,5,
BUC FAIL	Caution Lgt (P)		Red			System inoperative	Cautionary - none specified		
Tail Wheel Lock Condition - TAIL WHEEL	Discrete Light on Pilot's Inst. Pnl.		Green	•	LIA	Tail wheel unlocked	Advisory - unspecified	рр 3-8, 9 (ТМ 55-1520-238) -10, Fig. I-1	2,13
Stabilator Sys Status - STAB FAIL	Caution Lgts (1; P & 1; CPG)	,	Amber	1	Not specified	Not specified Not specified	Not specified	pp 16-8 & 15 (PS14-110218)	1,3,5,
Infrared Jam Status - IR JAM	Caution Lgt (P)		Amber					pp 8, 9, 11, 17 & 18	13

Sheet No.: 3

(Miscellaneous - Cont'd)

Table: D6

NOTE # 1,3,7, 13 1,3,6, 1,3,7, 1,3,7 pp 16-8 & 15 (PS14-11021B) pp 8, 9, 11, 17 & 18 pp 16-14, 17 & 18 (PS14-11021B) pp 8, 9, 12, 17 & 18 pp 16-8, 18 & 34 (PS14-110218) pp 8, 9, 12, 17 & 18 REFERENCES (STUDENT MANUAL: EDT-3 TRNG CRSE) CONDITION TYPE - DURATION Cautionary - none specified Cautionary - none specified Not specified PARAMETER FCC Primary MUX failed & Backup Bus controller (BBC)/Backup MUX operating CONDITION Not specified No reply Not Specified OPERATING MODE Trans-ponder Mode 4 selected ON MUX Control Sw at PRI UNITS ; ; ł MARKINGS Amber Amber Red INDICATOR RANGE Caution Lgt (CPG) Caution Lgt (P) Voice Security Caution Lgts (1; P & 1; CPG) Caution Lgts (1; P & 1; CPG) Caution Lgts (1; P & 1; CPG) TYPE Transponder Mode 4 Integration Reply Status -Armaments, Fire Control & Sys Status -PARAMETER NAME-INDICATOR LABEL Flight Control Computer Status -VOICE CIPHER PRI MUX ROCKET MISSLE TADS PNVS 3 11

MOTES:

- 1. The terms "p" & "CpG" refer to the Pilot's and Copilot/Gunner's crew stations, respectively. In the case of indicator lights, the number of lights at the particular crew station preceeds the crew station designation along with a semicolon.
- TM 55-1520-238-10 is a preliminary Operator's Manual, dated 31 May 1979. Much of the data which describes specific parameter conditions in conjunction with operating modes is yet to be supplied following flight testing.
 - 3. PS14-11021B is a Hughes Helicopter procurement specification for the caution and warning displays, dated 25 Oct 1977.
- Sensor is a mechanical switch which has a closed (fault condition) resistance of 10 ohms maximum and an open resistance of 2 megohms minimum. The maximum voltage and current with the switch closed are 0.1 VDC and 5-7 milliamperes respectively, while the switch open values are 5 to 30 VDC (positive) and 25 microamperes respectively.
 - can sink Sensor is a solid state switch which, when closed (turned on - fault condition), allows the light circuitry to see a maximum of +0.5 VDC and 5-10 milliamperes (max). When the switch is open, the voltage at the light circuit is 5-30 VDC (positive) with a maximum current flow of 25 ċ
- . Turn off (increasing pressure) threshold is 8 psi.
- 7. Light is activated by a 28 VDC signal from the sensing device to the caution/advisory panel. In the high state, the fault signal source output voltage is 16-30 VDC with load currents of 5 milliamperes to 10 milliamperes respective. The rise time is from 1 to 20 microseconds. In the no fault case (low state) the output voltage is 0-0.5 VDC.
- 8. Turn off (decreasing temperature) threshold is 180°F.
- 9. No turn off threshold is given. Also the listed operating mode is implied by the system description but not specifically stated.
- 10. The system operation is not described in the available references.
- 11. The Built-In-Test equipment for the Automatic Stabilization Equipment (ASE) also can cause a SCAS channel disconnect through detection of a servo mistrack (continuous performance monitoring) or incorrect response to a preprogrammed input set (self test pilot selected).
 - These signals are not currently in use, according to the first listed reference. No information on their operation is available.
- 13. No information available on these systems beyond what is listed.
- 14. Further information is available in the applicable weapons system student manuals which are unavailable to

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SUBSYSTEM PARAMETER DATA LIST

Table: D7 Sheet No.: 1

HELTCOPTER: YAH-64

SUBSYSTEM: Auxiliary Power Unit

		INDICAT	T0R				PARAMETER	REFERENCES	
PARAMETER NAME- INDICATOR LABEL	TYPE	RANGE	MARKINGS	UNITS	OPERATING MODE	CONDITION	CONDITION TYPE - DURATION	(STUDENT MANUAL: EDT-3 TRNG CRSE)	NOTE # (SH 2)
						0-(100.5 ±5)	Normal - continuous		
Speed -	Circular Dial (P)	0-120	(106-120)R	34	A11	(100.5 + 0.5 -	Cautionary - transient	pp 5-7 & 16	1,5
9 0						110%	Maximum - none specified		
FAIL APU	Caution Lgt (P)	1	Amber		3 . •	1. <60% rpm @ 20 seconds, or 2. >107 ±1% rpm, or 3. <90% rpm (see note), or	Cautionary - none	pp 5-4, 16, 17 & 16-12 1,2,3, (PS14-11021B) 6 pp 8, 11, 12 & 17	1,2,3,
APU ON	Advisory Lgt (P)	ŀ	Green	<u> </u>	RUN	4, 21324, ±237 EGT, or 5, <31 psi oil pressure for over 10 secs	specified	-10, pp 8-12 & 13	1,2,4,

NOTES:

1. The terms "P" & "CPG" refer to the Pilot's and Copilot/Gunner's crew stations, respectively. In the case of indicator lights, the number of lights at the particular crew station preceeds the crew station designation along with a semicolon.

2. TM 55-1520-238-10 is a preliminary Operator's Manual, dated 31 May 1979. Much of the data which describes specific parameter conditions in conjunction with operating modes is yet to be supplied following flight testing.

Sensor is a mechanical switch which has a closed (fault condition) resistance of 10 ohms maximum and an open resistance of 2 megohms minimum. The maximum voltage and current with the switch closed are 0.1 VDC and 5-7 milliamperes respectively, while the switch open values are 5 to 30 VDC (positive) and 25 microamperes respectively. ٠÷

Light is activated by a 28 VDC signal from the sensing device to the caution/advisory panel. In the high state, the fault signal source output voltage is 16-30 VDC with load currents of 5 milliamperes to 10 milliamperes respective. The rise time is from 1 to 20 microseconds. In the no fault case (low state) the output voltage is 0-0.5 VDC.

Sensor is most likely a tachometer generator. The (106-120)% range of Ng speeds is presumed marked red, since only black and white copies of the manual are available. 'n

Note that the Operator's Manual, p 8-12, says APU shutdown is initiated for Ng overspeed of 110% yet the Student Manual says this occurs at 107 ±1%. The last figure was selected as the most probable threshold. Note that there is a discrepancy between the turn on thresholds shown in the first reference (pp 5-16 & 17 versus p 16-12). The last listed page indicates that light operation is linked only to oil pressure. That page also indicates a light turn off threshold of 40 psi increasing oil pressure and more than 95% rpm for over 10 seconds. è

7. The light turn off threshold is $107\pm1\%$ rpm or switch turnoff.

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APPENDIX 2

FAULT/PARAMETER MA RIX

																					
	No. 1 & 2 FLT Control																				
	gue S Lael Flow High								××	×											
	Eug 1 Fuel Plow High						×	××	H												
	Right, Main Fuel Cell Overpressure								××	×											
	Left, Main Puel Cell Overpressure						×	××													
Faults	Eng 2 Beep Trim Low Side Fail	×××					×							×							
ı	Eng 1 Beep Trim Low Side Fail	x				×								×	-						
Parameter	Eng 2 N ₂ Sensing Fail	× × ×	 !				×							×				_			
1	Eng 1 N ₂ Sensing Fail	* * ×				×								×							
Multiple	Eng 2 Beep Trim High Side Pail	×××					×							×							
>	Eng 1 Beep Trim High Side Fail	x x x				×							-	×							
	fag 1 & 2 Flameout																	_			
	Eng 2 Flameout	* * *	×				×								×						
	Eng l Flameout	× × ×	×			×				,					×						
	Single Parameter Faults Requiring Inputs as Indicated (See Appendix 2)	01 to 4 to 60	~ ∞ c	10 11	12	1. T. C.	16 17	18 19	20	22	24	56 26	27	5,6,29	3.30	32	33	35	36	388.	40
	Sensor/Signal Availability (A-Analog, D-Discrete)	44444	44	4 Q	001	00	QΨ	A/D A	A/D	. ◀ €	00	Ω	۵ ۵	- ·	∢ <	⋖	< 4	< ≪	≪ <	< «	Ω
	Subsystem Parameter Data List Reference (* Sheet *)	A A 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,											A2,1	A3,1	A3,1	A3,1	A3,1	A3.2	A3,2	A33.2	A3,2
		Gas Producer (N1) Gas Producer (N2) PTIT PTIT Torque	011 Pressure 011 Pressure 011 Temperature		Oil Level Chip		ק י	1 1	1 1	12	Fuel		Press - Rt, Fwd		1 Xmsn Oil Press 2 Xmsn Oil Press	Combining Xmsn 011 Press	FWd Xmsn Oil Press	1 Xmsn Oil Temp	Eng 2 Xmsn Oil Temp	Xmsn Oil Temp	×
	ters	- 0 - 0 - 0		M	0 H	7 6	ູ້	Puel Qty Fuel Qty	Puel Qty Puel Qty	Fuel Qty		Fuel Pr	Fuel Pr		Eng 1 X Eng 2 X	Mebini 1	FWG XMB		Eng 2 X	Fwd Xms Aft Xms	Combining
	Parameters		S S S S S S S S S S S S S S S S S S S							22 22 23 23 24					30 31 En					38 Pr	_
Щ									.4 14	C4 C/				. ~	~ (7)		~ C	, m		<u> </u>	4

					_	_					_					_	-
	No. 1 & 2 PLT Control Hyd Fail			×	×												
	Eug 2 Fuel Flow High																
	guế j hoệi Ljom Hiếh																
	Right, Main Puel Cell Overpressure																
į	Left, Main Fuel Cell Overpressure																
aults	Eng 2 Beep Trim Low Side Fail																
ter F	Eng 1 Beep Trim																
Multiple Parameter Faults	Eng 2 N ₂ Sensing Fail																
ple P	Eng 1 N2 Sensing Fail																
Multi	Eng 2 Beep Trim High Side Fail																
	Eng 1 Beep Trim High Side Fail	_															
	Eng 1 & 2 Flameout				-												
	Eng 2 Flameout																
	Eng l Flameout																
	Single Parameter Faults Requiring Inputs as Indicated (See Appendix 2)	41	43	44	45	46	49	51	52	49-52	53.3	54	55	56	57	28	83
	Sensor/Signal Availability (A-Analog, D-Discrete)	Q	۵۵	A/D	Q/¥	V	A/0	A/D	A/D	ם נ) «	₹	۵	۵	Ω	۵	¥
	(Table #, Sheet #)	A3,2		-	-	-	-		•	υ, L	•		٠.		•	•	7,1
_	Subsystem Parameter Data List Reference	~ <	. ≪	<u> </u>	⋖	_	_	· •			_	•	_	_	⋖	_	⋖
		Chip	Thrust Brng Chip		rl Hyd Press	Utility Hyd Press		ier Load	ter Load	Ext Power Status	Cvelle Trim Actuator Pos		Status	Status	Heater Output Temp	Rt Aft Lndg Gear Phase	Turbine Speed
	Parameters	Pwd Xmsn Chip	Aft Vert Thrust	n Fit Ct	2 Flt Ctrl	tility B	71 Genera	1 Rectifier	2 Rectifier	AC Ext Power	· _	ft Cycli	11 SAS St	#2 SAS St	eater Ou	t Aft Ln	APU Turbi
	i Ference	41 P		_	_	_	* :	•	_	101 101			-	_	_		29 Y
1	Δ.	4.4	4,	4	4.	4.	4	. 4	47	., 4	- 47		43	#J	u)	43	43

	No. 1 & 2 FLT Control Hyd Fail	
	Eug 2 Fuel Flow High	×
	Eug i Fuel Flow High	×
	Right, Main Fuel Cell Overpressure	
	Left, Main Fuel Cell Overpressure	
Faults	Eng 2 Beep Trim Low Side Fail	× × × ××
	Eng 1 Beep Trim Low Side Fail	× ××× × ×
Parameter	Eng 2 N2 Sensing Fail	×
	Eng 1 N2 Sensing Fail	×
Multiple	Eng 2 Beep Trim High Side Fail	× × × ××
W	Eng 1 Beep Trim High Side Fail	× ××× × × ×
	Eng 1 & 2 Flameout	××
	Eng 2 Flameout	× ×
	Eng 1 Flameout	× ×
	Single Parameter Faults Requiring Inputs as Indicated (See Appendix 2)	1,29(3) 2,29(3) 3,4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4
	Signal/Sensor Type (A-Analog, D-Discrete)	00000000000 < <<<<
	New Sensor Required	я кк ки
	Additional Required Inputs	1 Eng 1 Cond-Lever Pos(1) 2 Eng 2 Cond-Lever Pos(1) 3 Eng 1 ignition Sw State 4 Eng 2 ignition Sw State 5 Eng 1 Start Button State 6 Eng 2 Start Button State 7 Eng 1 Beep Trim Sw State 8 Eng 1 & 2 Beep Trim Sw State 9 Eng 1 & 2 Beep Trim Sw State 9 Eng 1 & 2 Beep Trim Sw State 10 Fuel System E-Feed Valve Pos 11 Fuel System E-Feed Valve Pos 11 Utility Hud Temperature 13 Eng 1 N2 Control Actuator 14 Eng 2 N2 Control Actuator 15 Eng 1 Beep Trim Ref Signal 16 Eng 2 Beep Trim Ref Signal 17 Thrust Control Rod Pos 18 APU Accumulator Press 19 Outside Air Temp 20 Fressure Altitude 21 Indicated Airspeed 22 Gross Weight(2) 23 System Status 15 Eng 2 Flamed Out 2 Eng 2 Flamed Out 3 Eng 2 Flamed Out
į	V	100 00 00 00 00 00 00 00 00 00 00 00 00

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CONTRACTOR OF A SECTION OF PERSONS ASSESSED.

			Mul	Multiple	Parameter	eter	Faults	ts
Parareters	Subeystem Parameter Data List Reference (Table #, Sheet #)	Sensor/Signal Availability (A-Analog, D-Discrete)	No. 1 & 2 SAS Fail	No 1 & 2 Generators	No 1 & 2 Rectifiers	AC Bus X-Tie Fail	DC Bus X-Tie Fail	AGB Quill Shaft Fail
Eng 1 Gas Producer (N1) Eng 1 PTIT Eng 1 PTIT Eng 2 PTIT Eng 2 PTIT Eng 2 Oil Pressure Eng 1 Oil Pressure Eng 1 Oil Pressure Eng 1 Oil Temperature Eng 1 Oil Level Eng 2 Oil Level Eng 1 Chip Eng 2 Cond-Lever Position Eng 2 Cond-Lever Position Fuel Qty - Left, Main Fuel Qty - Rt, Main Fuel Press Left, Fwd Fuel Press Left, Fwd Fuel Press Left, Fwd Fuel Press Left, Aft	44444444444444444444444444444444444444	44444444 0000004444 ⁴ 400000004						
Eng 1 Kmsn 011 Press Eng 2 Kmsn 011 Press Combining Kmsn 011 Press Fwd Kmsn 011 Press Aft Kmsn 011 Press Eng 1 Kmsn 011 Temp Eng 2 Kmsn 011 Temp Combining Kmsn 011 Temp Fwd Kmsn 011 Temp Aft Kmsn 011 Temp Aft Kmsn 011 Temp	888 888 8888 8888 8888 8888 8888 8888 8888							×

Parameters 41 Pwd Xman Chip 42 Aff Xman Chip 43 Aff Xman Chip 44 Aff Xman Chip 45 Aff Xman Chip 46 Aff Xman Chip 47 Aff Xman Chip 48 Aff Xman Chip 48 Aff Xman Chip 49 Aff Xman Chip 40 Aff Xman Chip 40 Aff Xman Chip 41 Aff Xman Chip 42 Aff Xman Chip 43 Aff Yman Chip 44 Aff Xman Chip 45 Aff Xman Chip 46 Aff Xman Chip 47 Aff Xman Chip 48 Aff Xman Chip 48 Aff Xman Chip 49 Aff Xman Chip 40 Aff Xman Chip 40 Aff Xman Chip 41 Aff Xman Chip 42 Aff Xman Chip 43 Aff Xman Chip 44 Aff Xman Chip 45 Aff Xman Chip 46 Aff Xman Chip 47 Aff Xman Chip 48 Aff Xman Chip 48 Aff Xman Chip 48 Aff Xman Chip 48 Aff Xman Chip 49 Aff Xman Chip 40 Aff Xman Chip 40 Aff Xman Chip 41 Aff Xman Chip 42 Aff Xman Chip 43 Aff Xman Chip 44 Aff Xman Chip 45 Aff Xman Chip 46 Aff Xman Chip 47 Aff Xman Chip 48 Aff Xman Chip 48 Aff Xman Chip 48 Aff Xman Chip 49 Aff Xman Chip 40 Aff Xman Chip 40 Aff Xman Chip 40 Aff Xman Chip 41 Aff Xman Chip 42 Aff Xman Chip 43 Aff Xman Chip 44 Aff Xman Chip 45 Aff Xman Chip 46 Aff Xman Chip 46 Aff Xman Chip 46 Aff Xman Chip 46 Aff Xman Chip 47 Aff Xman Chip 48 Aff Xman 48 Aff Xman Chip 48 Aff Xman Chip 48 Aff Xman 48 Aff Xman Chip 48 Aff Xman 4				Mu.	Multiple		Parameter	Faults	ts
### Answer Chip	Parameters	Data List Reference	Availabili ty	No. 1 & 2 SAS Fail			AC Bus X-Tie Fail	DC Bus X-Tie Pail	AGB Quill Shaft Fail
### Twen Chip	Pvd Xasn	١.	۵						
### Vert Thrust Brng Chip ## A3,2	Aft Xmsn	A3,2	۵						
#1 Fit Ctrl Hyd Press	Aft Vert Thrust	A3,2	Ω					•	
#2 Fit Ctrl Hyd Press	#1 Flt Ctrl Hyd	A4,1	A/D						×
### A #### A ### A #### A ##### A ##### A ##### A ######	#2 Flt Ctrl Hyd	A4.1	A/D						×
### Generator Load ### Generator Load ### Rectifier	Utility Hyd	A4 .1	۷ ٔ		1				×
#2 Generator Load #2 Generator Load #2 Bectifier Load #5,1 A/D X X X #2 Bectifier Load #5,1 A/D X X X #2 Bectifier Load #5,1 A/D X X X #2 Ext Power Status #5,2 D A5,1 D A A #5,2 D A5,1 A A #6,1 A A A A A A A A A A A A A A A A A A A	#1 Generator	A5,1	0/v		×		×:		×;
#2 Rectilier Load #2 Rectilier Load #3 A5,1 A/D X X AC Ext Power Status DC Ext Power Status A5,2 D A1 Cyclic Trim Actuator Pos A6,1 A A1 Cyclic Trim Actuator Pos A6,1 A A1 SAS Status #2 SAS Status A6,1 D X Heater Output Temp A6,1 D R Aft Lindg Gear Phase	#2 Generator	A5,1	A/U		*	>	< >	>	4
AC Ext Power Status DC Ext Power Status By Cyclic Trim Actuator Pos A6,1 A Aft Cyclic Trim Actuator Pos A6,1 A Aft Cyclic Trim Actuator Pos A6,1 A Aft SAS Status Heater Output Temp A6,1 D Rt Aft Lindg Gear Phase A6,1 D	#2 Rectifier	A5.1	4 /2			< ×	< ×	< ×	
DC Ext Power Status Fwd Cyclic Trim Actuator Pos A6,1 A Aft Cyclic Trim Actuator Pos A6,1 A #1 SAS Status #2 SAS Status #2 SAS Status #2 A6,1 D R4 Aft Lndg Gear Phase A6,1 D	AC Ext Power	A5,1	<u>-</u>			!	:	}	
Fwd Cyclic Trim Actuator Pos A6,1 A Aft Cyclic Trim Actuator Pos A6,1 A #1 SAS Status #2 SAS Status #2 SAS Status #2 A6,1 D R4 Aft Lndg Gar Phase A6,1 D	DC Ext Power	A5,2	۵						
Aft Cyclic Trim Actuator Pos A6,1 A #1 SAS Status A6,1 D #2 SAS Status A6,1 D Heater Output Temp A6,1 D Rt Aft Lindg Gar Phase A6,1 D	Fwd Cyclic Trim Actuator	A6,1	*						
#1 SAS Status #2 SAS Status #2 SAS Status A6,1 D Rt Aft Lindg Gear Phase A6,1 D	Aft Cyclic Trim Actuator	A6,1	V (-					
Reater Output Temp A6.1 D	NAS CA	A6,1	ء د	< >					
Rt Aft Lndg Gear Phase A6,1	Hottor	1.64		•					
	Rt Aft	A6.1	a 0						
APU Turbine Speed	APU Tur	A7.1	¥						

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ıts	AGB Quill Shaft Fail	
r Faults	DC Bus X-Tie Fail	
Parameter	A Since Fail	
	No. 1 & 2 Rectifiers	
Multiple	stoiatened S & I .oM	
n M	No. 1 & 2 SAS Fail	
	Signal/Sensor Type (A-Analog, D-Discrete)	DDDDDDDA A AAAAAA DD
	New Sensor Required	х кккк
	Additional Required Inputs	Eng 1 Cond-Lever Pos(1) Eng 2 Cond-Lever Pos(1) Eng 1 Ignition Sw State Eng 2 Ignition Sw State Eng 2 Start Button State Eng 3 Start Button State Eng 3 Start Button State Eng 1 Beep Trim Sw State Eng 1 Norm Trim Selector Sw Eng 2 Norm Trim Ref Signal Eng 2 No Control Actuator Signal Eng 2 Beep Trim Ref Signal Eng 3 Beep Trim Ref Signal Eng 2 Hamed Out Eng 3 Flamed Out Eng 2 Flamed Out Eng 2 Flamed Out

NOTES

- Engine Condition Lever positions would be a three state discrete STOP, GROUND and FLY.
- 2. Gross Weight could also be entered manually via key pad.
- Note that fault 29, Rotor RPM Limit/Rate, has operating modes which depend not only on Engine Condition Lever positions, but also on the phase of flight. Thus, when the aircraft is on the ground, minimum continuous rpm is 214. If in flight and either both engines are flamed out or both condition levers are at GROUND or STOP the autorotation limits apply. 3

N Limit	45	#2 Flight Control Hydraulic Press Limit/Rate
N ₁ Limit	46	Utility Hydraulic Press Limit/Rate
Pri Limit/Rate	47	Utility Hydraulic Temp Limit
Prir Limit/Rate	48	APU Accumulator Press Limit/Rate
Torque Limit	49	#1 Generator Load Limit
Torque Limit	20	#2 Generator Load Limit
Oil Press Limit/Rate	51	#1 Rectifier Load Limit
Oil Press Limit/Rate	25	#2 Rectifier Lond Limit
Oil Temp Limit/Rate	53	Fwd Cyclic Trim Actuator Position Limit
	54	Aft Cyclic Trim Actuator Position Limit
	55	#1 SAS OFF
Oil Level Limit	26	#2 SAS OFF
Chip Detected	57	Heater Output Temp Limit
Chip Detected	28	Rt. Aft Landing Gear Phase Limit
Condition Lever Out of Detent		
2 Condition Lever Out of Detent		Multiple Parameter Faults
٠.		•
Qty - Left, Main Limit/Rate	29	Eng 1 Flameout
1	90	
1	61	1 & 2 Flameout
1	62	1 Beep Trim High Side
ı	63	N
	64	_
Eng 2 Fuel Pressure Limit	65	N
	99	-
	29	Eng 2 Beep Trim Low Side Pail
Puel Press - Right, Fwd Limit	89	=
Fuel Press - Right, Aft Limit	69	t, Main Fuel Cell
Rotor RPM Limit	20	No. 1 & 2 Flt Control Hyd Fail
Eng 1 Xmsn Oil Press Limit/Rate	71	No. 1 & 2 Generators Fail
Eng 2 Mmsn Oil Press Limit/Rate	72	No. 1 & 2 Rectifiers Fail
Combining Xmsn Oil Press Limit/Rate	73	_
	74	-
Aft Emsn Oil Press Limit/Rate	75	Eng 2 Fuel Flow High
Eng 1 Xmsn Oil Temp Limit/Rate	92	AC Bus X-Tie Fail
Xmsn Oil Temp Limit/Rate	7.2	DC Bus X-Tie Fail
Combining Xmsn Oil Temp Limit/Rate	78	AGB Quill Shaft Fail
Fwd Xmsn Oil Temp Limit/Rate		
Aft Xmsn Oil Temp Limit/Rate		Advisory List
Combining Xmsn Chip Detection		
Fwd Xmsn Chip Detected	79	AC External Power
Aft Xmsn Chip Detected	80	DC External Power
Aft Vertical Thrust Bearing Chip Detected	81	Parking Brake Status
#1 Flight Control Hydraulic Press Limit/Rate	82	Cargo Hook Status
	8	ADII Status

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APPENDIX 4

ROUTINE CHECKLISTS

ROUTINE CHECKLISTS (Sheet 1 of 12)

STARTING ENGINES

se EMMADS Actions	Initialize by relegendable switch. Place a box around item 1.	ige Detect acknowledge, change response to a "√", move box next item.	ige Same as above.	ge Same as above.	ige Same as above.	ge Same as above.	ige Same as above.	h Sense APU ON condition (APU speed is 98-106%) and place that message in Response column. Begin a 30 second countdown for hydraulic pressures. When fault condition 45 is sensed as cleared, indicate item 8 is ready to be accomplished by boxing both the procedure description and response. Also enable faults 34 and 39 when values reach lower normal limits.	Sense switch position if possible and remove box around response. Do not move box to next item until 30 second countdown is halted. The countdown should halt when faults 44-46 and 69 are all cleared. At this point these faults should be enabled. If the countdown is completed, all these faults should be enabled. Mhen the faults are cleared box around item 9, including the response.	Sense the switch position and enable fault 49. If no DC Ext. Power is connected (sense advisory condition) enable fault 51. If no faults detected, move box to item 10.	Same as above, but substitute faults 50 and 52 for 49 and 51. If no DC Ext. Power is connected, also enable faults 76 and 77.	ige If only AC Ext. Power was on aircraft, sense the acknowledge and move box to next item. If DC Ext Power was also sensed on, wait until that advisory is cleared, enable faults 76 and 77, sense acknowledge and move box to next step.	ge Same as for item 1.	ge Same as for item 1.
Pilot Response		Acknowledge	Acknowledge	Acknowledge	Acknowledge	Acknowledge	Acknowledge	Accomplish	RELEASE	NO	NO	Acknowledge	Acknowledge	Acknowledge
Procedure Description		*CHECK INTERPHONE	*CHECK MAIN FUEL & X-FEED VALVE LIGHTS (FLT BNG)	*POST FIRE GUARD	*CHECK APU LIGHTS (PRESS)	*APU SWITCH TO APU, CHECK LOW OIL PRESS LIGHT OUT, HIGH EXH TEMP AND OVSP LIGHTS ON	*GND-APU-AGB TO START (HOLD)	*APU SWITCH TO START (RELEASE AT 90%)	*GND-APU-AGB SWITCH TO	GENERATOR #1 CONTROL SWITCH TO	GENERATOR #2 CONTROL SWITCH TO	DISCONNECT EXTERNAL POWER	POSITION FLIGHT CONTROLS	AVIONICS ON AS REQUIRED
Item			01	ო	4	'n	ဖ	٠	œ .	os.	10	11	12	13

^{*} EMMADS can only display these items if AC external power is supplied, unless the APU is started first. If when EMMADS powers up it detects the APU operating, selection of this checklist causes a jump to item 9, enabling faults 34, 39, 44-46 & 69)

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ROUTINE CHECKLISTS (Sheet 2 of 12) (Continued)

STARTING ENGINES

EMMADS Actions	Same as item 10.	as above.	as above.	If fault (advisory) 81 changes state ending with an active condition, place an "ON" in the Response section. Move box to next item.	Same as item 13.	as above.	Same as above.	as in item 1.	Same as above, plus begin a 2 minute countdown. If item 28 is completed before the end of this countdown, blank the checklist and display the remaining time plus the message "HEATER PURGING - PLEASE STANDBY". Return to checklist at completion of countdown and move box to next item.	Same as item 18.	Same as above.	Since fault 44 is enabled, the checklist will be cleared and the hydraulic subsystem will be displayed with an appropriate message. When the fault clears, place a "/" in the Response column. Move box to next item.	Similar to item above.	as item 1.	Begin 8 second countdown when switch position is sensed. If the beep reference signal slopes are not zero when countdown is complete, blank screen and display "ENG 1(2) BEEP STILL DECREASING AFTER 8 SECONDS" with the proper engine number selected. If slopes at zero before countdown is complete, stop countdown, change response to "RELEASE". When switch is released, move box to next item.	Same as item 1.
Pilot Response	Acknowledge San	Acknowledge Same	Acknowledge Same	Accomplish If	Acknowledge Sar	Acknowledge Same	Acknowledge Sau	Acknowledge Same	Acknowledge Sam be: re	Acknowledge Sau	Acknowledge Sa	Accomplish Since hydra the 1	Accomplish Si	Acknowledge Same	DECREASE Be re sc th	Acknowledge Sa
Procedure Description	SET POSITION LIGHTS AS REQUIRED (ON-DAY; OPP-NIGHT)	TURN ON ANTI-COLL LIS SWITCH AND CHECK	CHECK SEARCH LIGHT FOR PROPER OPERATION	RESET PARKING BRAKE	CHECK CRUISE GUIDE INDICATOR	SET ALTIMETER TO FIELD ELEVA- TION	TEST FIRE DETECTOR	CHECK AND SET STICK POSITIONER	TURN OFF HEATER	CHECK ROTOR BLADE POSITION	CHECK PLIGHT CONTROLS WITH HYD BST SWITCH AT BOTH	CHECK FLIGHT CONTROLS WITH HYD BST SWITCH AT NO. 1 ON.	CHECK FLIGHT CONTROLS WITH HYD BST SWITCH AT NO. 2 ON.	CHECK AVIONICS	NO 1 & 2 ENG BEEP TRIM SWITCH	CLEAR ENG 1 FOR START
I te	5 1	15	16	11	18	19	50	21	22	23	24	25	56	27	88	59

ROUTINE CHECKLISTS (Sheet 3 of 12) (Continued)

STARTING ENGINES

Procedure Description	Pilot Response	EMMADS Actions
LEPT MAIN FUEL PUMP SWITCHES TO	NO	Monitor fault 23. When the fault is de-activated (main fuel pressure is up) move box to next item.
CHOSS PEED FUEL VALVE SWITCH TO	OPEN	Monitor fault 24. When the fault is de-activated, move box to next item.
ENG 1 CONDITION LEVER TO	STOP	Sense lever position, move box to next item.
ENG 1 START FUEL SWITCH TO	OPEN	Sense switch position, move box to next item.
ENG 1 IGNITION SWITCH TO	NO	Same as above.
ENG 1 START BUTTON	PRESS & HOLD	during both engine starts. This would come up when the START button is pressed and last until "ENG 12 RUNNING" is displayed.) Sense switch position and disable faults 50, 52, 76 and 77 unless APU is not running. Display "LOAD FAULT" and electrical subsystem if any of the disabled series and display "RELEASE START BUTTON - CHECKLIST ITEMS MISSED". When button is released, return to checklist display boating first incompleted item. Allow all items remaining to be completed in sequence. Begin a 45 second countdown for engine acceleration, and monitor NI. When NI = 10%, change response of item 32 from "STOP" to "GROUND and remove item 32 change response of item 32 from "STOP" to "GROUND and remove item 32 box. Also monitor PIT, TORGUE, Oil Press. and Temp. for Eng 1 plus all Xmsn Oil Pressures and temperatures. As each parameter reaches the lower end of its normal limit, enable the corresponding faults (1, 3, 5, 7, 9), change the response of item 33 from "OPEN" to "CLOSE" and flash a box around the response of item 33 from "OPEN" to "CLOSE" and flash a box around the response of item 33 from "OPEN" to "CLOSE" and flash a box around the response of item 33 from "OPEN" to "CLOSE" and flash a box around the response from "PRESS & HOLD" to "RELEASE". Remove flashing boxes from these items when the desired switch position(s) are attained. If Ni, PTIT and engine oil press, and temp. faults are all enabled before countdown, and display as required. When the response of item 35 is complete, disconfinue countdown and remove flashing changed to "RELEASE", begin a 3 minute countdown for starting Eng 2 START button is not pressed after 2 minutes, blank screen and display "2 MINUTES SINCE ENGINE START - PLEASE ACKNOWLEDGE AND START after item 35 was is removed enable fault 59 and display to the checklist.
CLEAR ENG 2 FOR START	Acknowledge	Sense the acknowledge and proceed as in item 1.

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GENERAL ELECTRIC CO SINSHAMTON N Y AIRCRAFT EQUIPMENT DIV F/8 1/3 .

ELECTRONIC MASTER MONITOR AND ADVISORY DISPLAY SYSTEM. OPERATIO—ETC(U)

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Sec. | END | END

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ROUTINE CHECKLISTS (Sheet 4 of 12) (Continued)

STARTING ENGINES

EMMADS Actions	Same as item 32, going to item 38 instead of 33.	Same as item 33, going to item 39 instead of 34.	Same as item 34, going to item 40 instead of item 35.	Same as for item 35. If items 38-39 have not been accomplished, follow the guidelines given for item 35. If no items are missed, again follow procedures similar to those in item 35. For fault enabling, disregard the Kmsn ofl Press. and Temp, faults since these are already enabled during the previous engine start. Substitute faults 2, 4, 6, 8, 10, 31 and 36 for faults 1, 3, 5, 7, 9, 30 and 35 in item 35. When normal limits are reached, enable faults 60 and 61 at the points corresponding to enabling fault 59 in item 35. Display "ENG 2 RUNNING" after item 40 when box moved to item 41. Also re-enable faults 50, 52, 76 and 77 if applicable.	Sense lever positions at "FLIGHT", move box to next item and enable fault 29 plus any of faults 30-33 and 35-38 not already enabled.	Monitor rotor rpm and Eng 1 and 2 torque (whenever engine torques are matched, symbology on torque indicator should be modified in same way to indicate this match or "lock"). When both conditions are met handle response symbol and flash next item. Enable faults 62-67. Move box to next item.	Sense switch position and remove box. Wait for acknowledge and clear display. Enable all faults that were supposed to be enabled in this checklist, as previously described.
Pilot Response	STOP	OPEN	NO	Press & Hold	FLIGHT		STOP
Procedure Description	ENG 2 CONDITION LEVER TO	ENG 2 START FUEL SWITCH TO	ENG 2 IGNITION SWITCH TO	ENG 2 START BUTTON	EMG CONDITION LEVERS TO	ADJUST ENG BREP TO 245 ROTOR RPM AND MATCHED TORQUE	APU SWITCH TO
Ite	37	38	39	9	7	₽ 3 2	#

ROUTINE CHECKLISTS (Sheet 5 of 12) (Continued)

ENGINE GROUND OPERATION

 *	Procedure Description	Pilot Response	EMMADS Actions
			Initialize checklist with acknowledge switch. Draw a box around item 1.
-	SET VGI SWITCHES AS REQUIRED	Acknowledge	Same as item 1 of preceding checklist.
a	GEN 1 SWITCH TO	OPF	Since faults 49, 51, 76 and 77 are enabled, the response is automatic. When the fault(s) clear, return to the checklist. Change "OFF" to "ON", and move box to next item.
n	GEN 2 SWITCH TO	0 PF	Same as above (faults 50, 52 vs faults 49 and 51). When fault(s) cleared, maintain display and place item 4 in the position where the message capsule normally is, with a box around it. Enable faults 71 and 72.
•	CHECK PITOT HEAT	Acknowledge	When the acknowledge is sensed, clear the electrical subsystem display and replace it with that of the engine subsystem. Display item 5 with a box around it where the message capsule normally appears.
ın	CHECK ANTI-ICING	Acknowledge	Sense the acknowledge and return to the checklist display. Items 4 and 5 should have a "/" after them in the Response column.
ъ 183	CLOSE FUEL X~FRED VALVE	Acknowledge	Sense fault 24 active, move box to next item and display a "/" in the Response column.
	ALL FUEL BOOST PUMP SWITCHES TO	OFF	Sense faults 23-28 active and move box to next item.
c	LEFT AFT AUX FUEL PUMP SWITCH TO	NO	Sense faults 23 and 26 not active, change response to "OFF". Sense faults 23 and 26 active. Move box to next item.
o	LEFT MAIN FUEL PUMP SWITCHES TO	NO	Same as above but sense only fault 23.
10	LEFT PWD AUX PUEL PUMP SWITCH TO	NO	Sense faults 23 and 25 not active, handle as in item 8 above.
11	RIGHT PWD AUX PUEL PUMP SWITCH TO	NO	Same as item 8 but use faults 24 and 27 respectively.
12	RIGHT MAIN PLEL PUMP SWITCHES TO	NO	Same as item 9 using fault 24.
13	RIGHT AFT AUX PUEL PUMP SWITCH TO	NO	Same as item 10 using faults 24 and 28 respectively.
14	TURN ON ALL BOOST PUMPS	Acknowledge	Sense acknowledge and enable faults 23-28, 68 and 69.
15	CHECK PLIGHT INSTRUMENTS	Acknowledge	Same as in item 1.

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ROUTINE CHECKLISTS (Sheet 6 of 12) (Continued)

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ENGINE GROUND OPERATION

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EMMADS Actions	As the check is currently accomplished, simply sense acknowledge change "1" to "2" in Procedure Description, sense acknowledge a second time and go to next item. However, must leave open the possibility for testing the Emergency Beep Trim Display mode as well (partial display using Ni and PTIT).	Sense acknowledge, remove box and place a "/" in response column. Enable all faults listed in past two checklists if not already enabled. Sense second acknowledge and blank display.
Pilot Response	Acknowledge	Acknowledge
Procedure Description	CHECK ENG 1 EMERGENCY TRIM	PERPORME HIT CHECK

ROUTINE CHECKLISTS (Sheet 7 of 12) (Continued)

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BEPORE TAKEOPF/LANDING

EMMADS Actions	Initialize by sensing acknowledge or relegendable switch. Enable fault 78 unless this check preceeded by the HOVER CHECK. Put box around item 1.	Sense acknowledge and move box to next item. Place a " $'$ " in response column.	Same as above.	When fault 73 sensed as active, enable faults 55, 56 and 73 unless already enabled. Move box to item 4. Enable faults 53 and 54.	Same as item 1.	Same as item 1.	Same as item 1.	Same as item 1.	Same as item 1. If this check preceded by HOVER CHECK or ENGINE GROUND OPERATION CHECK wait for CRUISE CHECK or HOVER CHECK respectively. If preceded by CRUISE CHECK, disable faults 74 and 75 and wait for HOVER CHECK. Sense second acknowledge and blank screen.
Pilot Response		Acknowledge	Acknowledge	ENGAGE	Acknowledge	Acknowledge	Acknowledge	Acknowledge	Acknowledge
Procedure Description		SET PARKING BRAKE AS REQUIRED	LOCK AFT WHEEL	EMER SAS RELEASE SWITCH TO	SET PSAS AS REQUIRED	SET CYCLIC TRIM	SET TRANSPONDER AS REQUIRED	CHECK CREW, PAX AND EQUIPMENT	SET SEARCH LIGHTS AND/OR LANDING LIGHTS AS REQUIRED
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ROUTINE CHECKLISTS (Sheet 8 of 12) (Continued)

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HOVER CHECK

Pilot Response

Procedure Description

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EMMADS Actions

		Initialize by sensing acknowledge or relegendable switch and place box around item 1. (Reaffirm faults from previous checklists all enabled.)
CHECK PLIGHT CONTROLS	Acknowledge	Sense acknowledge, move box to next item and place a "/" in response column.
CHECK PLIGHT INSTRUMENTS	Acknowledge	Same as above.
CHECK POWER MARGIN	Acknowledge	Same as above.
SAS CHRCKED?	Acknowldge	If acknowledge sensed before 15 second countdown completed, remove box, blank remainder or checklist and place a "/" in response column. Sense second acknowledge and blank display. If countdown completed before acknowledge sensed, move box to item 5.
TURN OFF PITCH STAB AUG SWITCH	Acknowledge	Same as item 1.
CRECK SAS WITH SWITCH AT	NO.1 ON	Since fault 56 is enabled, fault will be displayed in normal manner. If acknowledge sensed, clear display back to checklist and change "1" to "2" in response. When switch position is changed, fault 55 will be detected. Follow same procedure. When both faults are cleared remove box and place a "/" in the response column. Sense second acknowledge and blank display.

ROUTINE CHECKLISTS (Sheet 9 of 12) (Continued)

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CRUISE CHECK

EMMADS Actions	Initialize by sensing acknowledge or relegendable switch. Place a box around item 1.	Sense acknowledge, move box to next item.	Begin 30 minute countdown when acknowledge sensed. At end of countdown, reinitalize this checkout, unless a BEPORE LANDING CHECK occurs first, which stops the countdown. Move box to next item. Start 10 second countdown.	If acknowledge is sensed before end of 10 second countdown, sense average fuel consumption over next 15 minutes and use as a baseline for faults 74 and 75. Then enable these faults, unless already enabled and remove box from item. Place a "\" in the response column. Action is the same if no acknowledge sensed before countdown ends, except no baseline is set. Sense second acknowledge and blank screen.
Pilot Response		Acknowledge	Acknowledge	Acknowledge (YES)
Procedure Description	•	SUT PITCH STAB ADG SWITCH AS REQUIRED	CHECK RAMP AREA	SET FUEL FLOW BASELINE (provisional checklist item)
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ROUTINE CHECKLISTS (Sheet 10 of 12) (Continued)

APTER LANDING

Pilot Response

Procedure Description

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EMMADS Actions

		Initialized by a relegendable switch. Place box around item 1.
SET EMERG SAS REL SWITCH TO DESIRED POSITION	Acknowledge	Since SAS faults are enabled, if EMERG SAS REL switch activated, display faults normally. When acknowledge sensed, clear back to checklist, display a "\" in Response column, move box to item 2.
SET AFT WEEELS SWIVEL SWITCH AS DESIRED	Acknowledge	Sense acknowledge, move box to next item, place a "/" in response column.
SET SEARCH LIGHTS AS DESIRED	Acknowledge	Same as above.
SET TRANSPONDER AS REQUIRED	Acknowledge	Sense acknowledge, remove box, place a "'" in response column. Sense second acknowledge and clear display.

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ROUTINE CHECKLISTS (Sheet 11 of 12) (Continued)

ENGINE SHUTDOWN

			ENGINE SHOLDOWN
=======================================	Procedure Description	Pilot Response	EMMADS Actions
			Initialize by sensing relegendable switch or acknowledge. Disable fault. (Advisory) 83. Draw box around item 1.
-	LOCK APT WHEELS SWIVEL	Acknowledge	Sense acknowledge, move box to next item, place a "," in response column.
n	SET PARKING BRAKE AS REQUIRED	Acknowledge	Same as above.
ო	TURN OFF HEATING SWITCHES	Acknowledge	Same as above.
•	TURN OFF ANTI-ICE SWITCHES	Acknowledge	Same as above.
10	DISARM EMERG EXIT LIGHTS	Acknowledge	Same as above.
•	SET FLIGHT CONTROLS	Acknowledge	Same as above.
~	EMERIC SAS RELEASE SWITCH TO	RELEASE	Since fault 73 is enabled, the acknowledge for the fault is sensed before display will return to the checklist. Disable faults 55, 56 and 73. Move box to next item.
•	SET RAMP AS REQUIRED	Acknowledge	Same as item 1.
00	CHOCK WHRELS	Acknowledge	Same as above.
10	PTIT (TGT) RATE IS BEING CHECKED	WAIT	Monitor this parameter on both engines. When time rate of change is neither positive nor greater than 10°C/minute (based on current instrument resolution and experience) display "STABLE" instead of "BEING CHECKED" and "Acknowledge" instead of "WAIT". Proceed as in item 1.
11	POST FIREGUARD	Acknowledge	Same as item 1.
2	ENG 2 CONDITION LEVER TO	GROUND	Sense engine condition lever position. Monitor PTIT on engine #2 for negative slope. When slope goes to zero and/or begins to go positive, change response to "STOP". Sense lever position and move box to next item. (Continue to monitor for fault 4 until power down. All related Eng. faults, 1.e., 2, 4, 6, 8, 10 and 31 should be detected when Eng. stopped - acknowledge brings back checklist. Eng. flameout will not be detected.)
13	ENG 2 FUEL PUMP SWITCHES TO	OPF	Faults 24, 27 and 28 should be detected. When acknowledged, return to checklist. Move box to next item.
14	BEEP (1 & 2) TO	235	When rotor rpm stable at 235 for 5 seconds, move box to next item.
15	CHECK APU LIGHTS (APU)	Acknowledge	Same as item 1.

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ENGINE SHUTDOWN

Procedure Description	Pilot Response	EMMADS Actions
APU SWITCH TO APU, CHECK LOW OIL PRESS LIGHT OUT, HIGH EXH TEMP AND OVSP LIGHTS ON	Acknowledge	Same as item 1.
APU SWITCH TO START (RELEASE AT 90%)	Accomplish	Sense APU ON (fault/advisory 83) and place that message in Response column. Move box to next item.
BEEP (1 & 2) SWITCH TO	DECREASE	Same as item 28 in STARTING ENGINES CHECKLIST. Move box to next item.
ENG 1 CONDITION LEVER TO	GROUND	Same as item 12 (substitute faults 1, 3, 5, 7, 9 and 30 for 2, 4, 6, 8, 10 and 31). Also may detect faults 24 and 32-34 rotors wind down. Move box to next item.
ENG 1 FUEL PUMP SWITCHES TO	OFF	Same as item 13, substitute faults 23, 25 and 26 for 24, 27 and 28 respectively. Move box to next item.
TURN OFF AVIONICS	Acknowledge	Same as item 1.
GENERATOR CONTROL SWITCHES TO	4 d0	Faults 49-52 and 71 and 72 should be detected and displayed. Faults 73 or 76 should not appear. When faults are cleared go to next item if PTIT stability conditions in items 12 and 19 are met. Otherwise display engine parameters. (If faults 3 or 4 are tripped due to rising PTIT, engine parameters will come up on display.) Move box to next item.
TURN OFF LIGHT SWITCHES	Acknowledge	Sense acknowledge and Rotor rpm at zero, then proceed as in item 1.
APU SWITCH TO	STOP	EMMADS will power down. (Also expect faults 34, 44-46, 70 and 78.)*

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If fault 78 triggers an automatic APU start, must disable fault 78 before item 24 is accomplished and verify it is disabled.

*Note:

